

**STATUS OF THE SPACE-BASED COMPONENT
OF THE GLOBAL OBSERVING SYSTEM (GOS)
as of September 2006**

(Submitted by WMO)

This document contains essential information on satellites and instruments that form the space-based component of the GOS at the nominal date of September 2006. It is updated and extended from the first issue, CGMS XXXII WMO WP-26 and the second one, CGMS XXXIII WMO WP-23. It is compiled on the basis of:

- information provided by satellite operators members of CGMS at their annual meetings;
- extensive search on the Web for missing information, details and latest updates;
- books and personal notes, especially for the historical elements;
- updates from satellite operators following specific requests.

The structure of the document is such that it provides, on an annual basis, a short historical background on the various programmes, a slowly-evolving framework on current and developing systems/instruments, and a more evolutionary framework for input of the latest information on systems/instruments that are in their definition phase.

An effort has been made to provide template-like information in order to ensure compliance with homogeneity and completeness, and facilitate comparisons of programmatic elements and performances. The purpose is to provide an available and simple tool to check to which extent Earth Observation satellites fulfil WMO requirements in terms of both coverage and quality.

The following systems have been considered:

- the constellation of operational meteorological geostationary satellites;
- the constellation of operational meteorological sunsynchronous satellites;
- a selection of R&D programmes conducted by space agencies associated to CGMS.

It is regretted that a number of gaps of information or doubtful information still exist, both in the chapters dealing with operational meteorological satellites and, more, in the R&D chapter. Gaps are highlighted in **yellow colour**, and are progressively reducing from issue to issue.

The report has been prepared by Dr. Bizzarro Bizzarri as WMO consultant.

ACTIONS PROPOSED

1. CGMS to note the status of current and planned satellites of GOS at the nominal date of Sept. 2006, i.e. close to CGMS XXXIV. Special attention is called on the sections reporting the analysis of compliance of GOS with WMO requirements in terms of observation coverage (Sections 2.9 and 3.8) and instruments performance (Sections 2.10 and 3.9).
2. CGMS Members to carefully check the information reported and contribute to resolving doubtful areas and complete missing areas (**highlighted in yellow**), soon after CGMS-XXXIV and in preparation of the next issue for CGMS-XXXV. To this purpose, CGMS Members are recommended to designate a contact point to interact with Dr. Bizzarri at bibizzar@tin.it.

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1. THE SPACE-BASED COMPONENT OF THE GLOBAL OBSERVING SYSTEM

The **Global Observing System (GOS)** is coordinated by WMO in support of all its programmes:

- WWW (World Weather Watch)
- WCP (World Climate Programme), including:
 - World Climate Data and Monitoring Programme
 - World Climate Applications and Services Programme
 - World Climate Impact Assessment and Response Strategies Programme
 - World Climate Research Programme
 - Global Climate Observing System
- AREP (Atmospheric Research and Environment Programme), including:
 - Global Atmosphere Watch
 - World Weather Research Programme
 - Tropical Meteorology Research Programme
 - Physics and Chemistry of Clouds and Weather Modification Research Programme
- AMP (Applications of Meteorology Programme), including:
 - Agricultural Meteorology Programme
 - Aeronautical Meteorology Programme
 - Marine Meteorology and Associated Oceanographic Activities Programme
 - Public Weather Services Programme
- HWRP (Hydrology and Water Resources Programme), including:
 - Operational Hydrology Programme - Basic Systems
 - Operational Hydrology Programme - Applications and Environment
 - Programme on Water-related Issues
- Education and Training Programme
- Technical Cooperation Programme
- Regional Programme
- WSP (WMO Space Programme)
- WDPMP (Natural Disaster Prevention and Mitigation Programme).

The GOS is composed of surface-based systems and space-based systems. The space-based component of the GOS is implemented and managed by agencies linked to national meteorological services as well as two intergovernmental organizations, EUMETSAT and ESA. The **Coordination Group for Meteorological Satellites (CGMS)** is a forum for coordination of the space-based systems. CGMS Members or Observers whose primary focus is operational meteorological satellite systems are:

- CMA (China Meteorological Department)
- EUMETSAT, on behalf of 18 European Member States and 11 Cooperating States
- IMD (India Meteorological Department)
- IOC (Intergovernmental Oceanographic Commission) of UNESCO
- JMA (Japan Meteorological Agency)
- KMA (Korea Meteorological Administration)
- NOAA (National Oceanic and Atmospheric Administration)
- RosHydroMet (Hydro-Meteorological Service of the Russian Federation)
- WMO (World Meteorological Organization).

CGMS now includes several R&D space agencies, either as supportive to their corresponding operationally-oriented agency or as a full CGMS member. They are:

- CNES (Centre National d'Etudes Spatiales).
- CNSA (China National Space Agency)
- ESA (European Space Agency) on behalf of 17 European Member States and 3 Cooperating States
- ISRO (India Space Research Organisation)

- JAXA (Japan Aerospace Exploration Agency), formerly NASDA
- KARI (Korea Aerospace Research Institute)
- NASA (National Aeronautics and Space Administration)
- RosKosmos (Russian Space Agency)

The space-based component of the GOS includes:

- operational meteorological satellites in geostationary orbit
- operational meteorological satellites in sunsynchronous orbit
- a number of R&D satellites, or instruments carried by R&D satellites or R&D instruments carried on an operational satellite, that comply with certain basic WMO criteria such as:
 - relevance to WMO programmes
 - some sort of service continuity, though, in some cases, within an evolutionary system/instrument environment
 - data access on a non-discriminatory basis as defined by the R&D agency and according to modes standardised to the maximum extent possible
 - a formal statement made to WMO describing the commitment.

The **WMO Space Programme** agreed upon by the Fourteenth World Meteorological Congress in May 2003 and entered into force on 1 January 2004, provides monitoring of the space-based component of the GOS and, specifically, of the progressive extension from the traditional operational “core” to a wider system inclusive of contributions from R&D satellites as well as the transition of appropriate R&D missions and instruments into operational services.

The **operational meteorological geostationary satellite system** includes the following series:

- the European Meteosat
- the United States of America’s GOES
- the Japanese now replaced by MTSAT
- the Russian GOMS-Elektro
- the Chinese FY-2 to be replaced by FY-4
- the Indian INSAT and Kalpana (formerly MetSat)
- the Korean COMS currently being developed.

The **operational meteorological sunsynchronous satellite system** includes the following series:

- the United States of America’s POES, supported by DMSP, to converge into NPOESS
- the European MetOp
- the Russian Meteor
- the Chinese FY-1 to be replaced by FY-3.

The system of operational meteorological satellites in geostationary and sunsynchronous orbits is intended to fulfil the WMO requirement for:

- six satellites regularly spaced in the geostationary orbit
- four satellites optimally spaced in sunsynchronous orbits
- comparable quality across systems.

Fig. 1.1 and **Fig. 1.2** show the coverage that would be provided by the space-based component of the GOS if implemented by (Fig. 1.1) six geostationary satellites 60-degrees spaced, at any time, and (Fig. 1.2) four sunsynchronous satellites at equally-spaced Local Solar Time (LST), in three hours. The figures refer to instruments with day-and-night capability (i.e. operating in IR or MW), useful field of view of 60° geocentric angle from GEO, and various swaths from LEO: typical of VIS/IR imagers (2900 km), of sounders (2200 km) and of conical scanning microwave radiometers (1400 km).

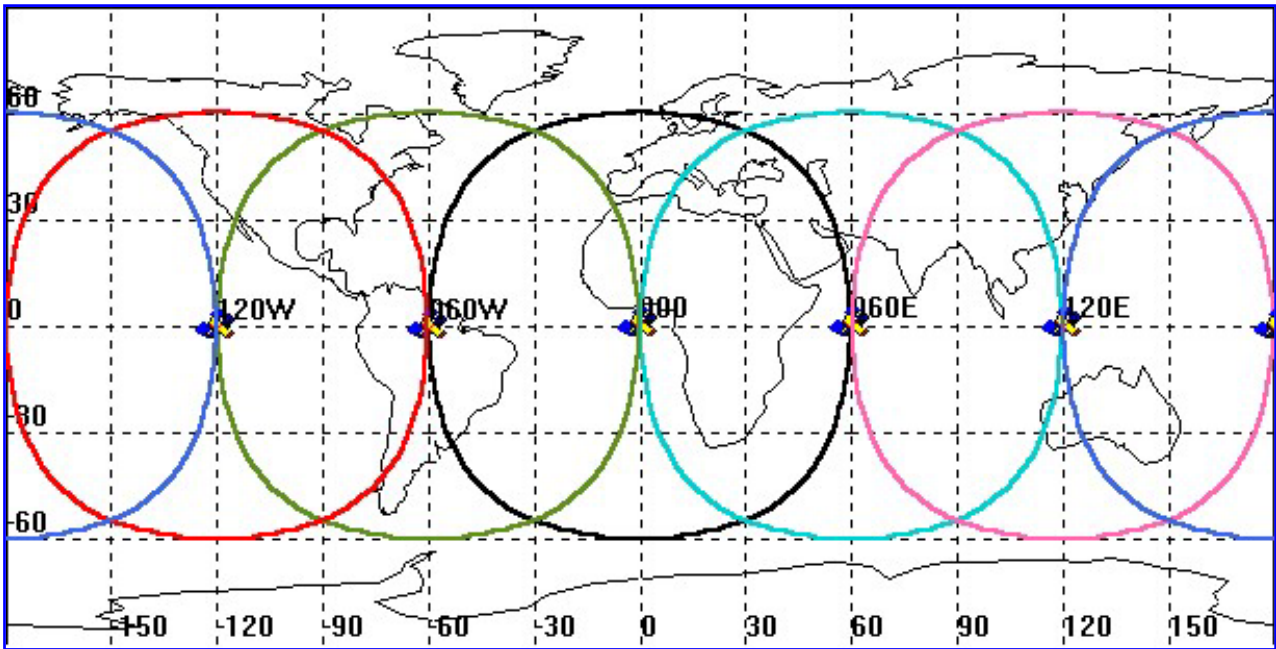


Fig. 1.1 - Coverage from six regularly-space geostationary satellites. The circles subtend a geocentric angle of 60°, considered the practical limit for quantitative observations (images extend beyond). All latitudes between 55°S and 55°N are covered.

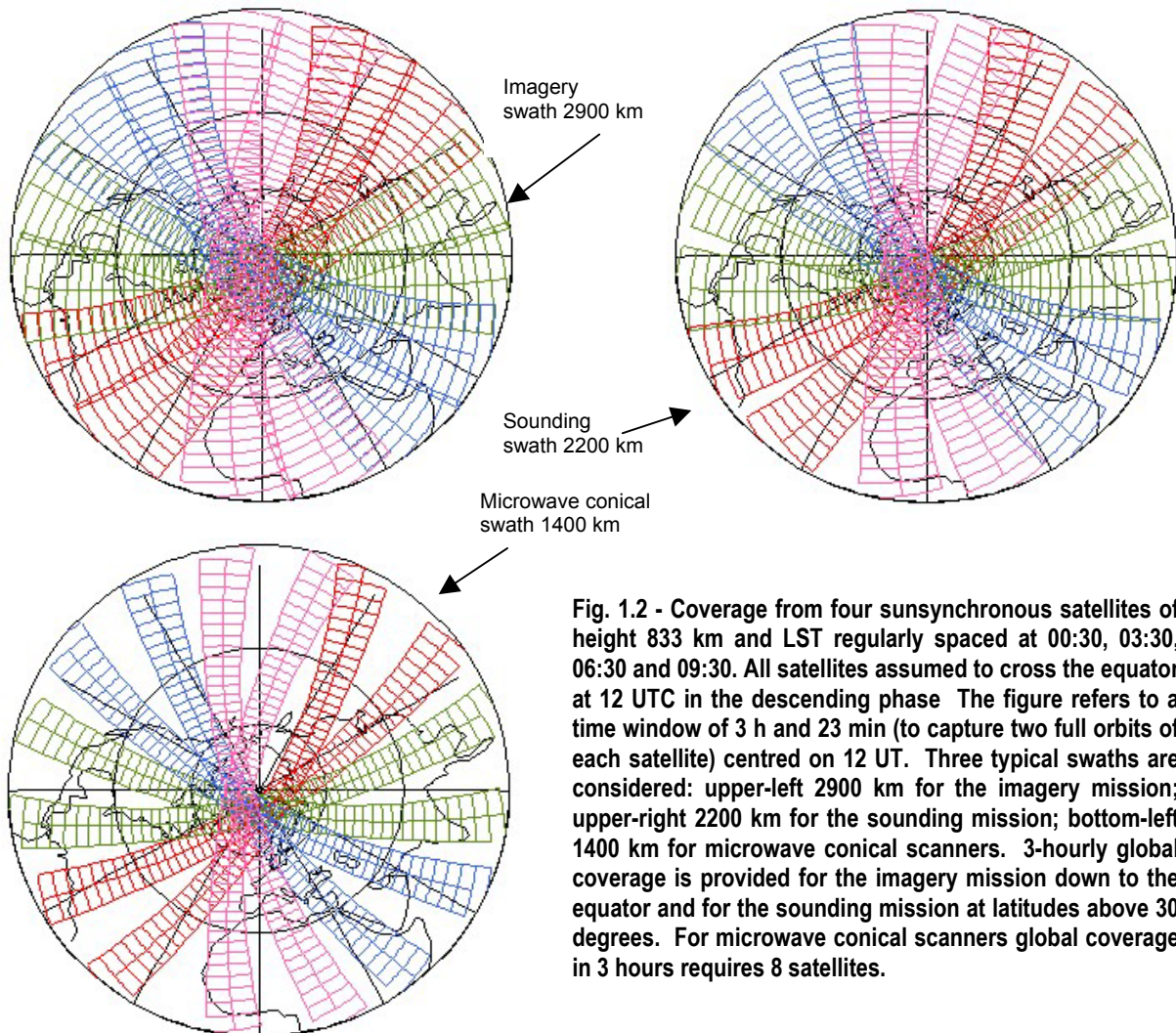


Fig. 1.2 - Coverage from four sunsynchronous satellites of height 833 km and LST regularly spaced at 00:30, 03:30, 06:30 and 09:30. All satellites assumed to cross the equator at 12 UTC in the descending phase. The figure refers to a time window of 3 h and 23 min (to capture two full orbits of each satellite) centred on 12 UT. Three typical swaths are considered: upper-left 2900 km for the imagery mission; upper-right 2200 km for the sounding mission; bottom-left 1400 km for microwave conical scanners. 3-hourly global coverage is provided for the imagery mission down to the equator and for the sounding mission at latitudes above 30 degrees. For microwave conical scanners global coverage in 3 hours requires 8 satellites.

The integration of **R&D satellites** into the GOS was formally established by the WMO Congress in 2003, and coordinated under the Commission for Basic Systems (CBS) with guidance for the WMO Space Programme by the “WMO Consultative Meetings on High Level Policy on Satellite Matters” (CM) and with CBS having lead technical commission responsibility for the Space Programme.

The variety of R&D programmes is extreme, both because of the high number of national space agencies in the world, and the number of programmes within a space agency. In this Report we only include consideration of a selection of the most significant programmes for the purpose of the GOS, run by space agencies connected with CGMS. Reporting includes:

- for ESA: the ERS-1/ERS-2/Envisat satellites; the Earth Watch and Earth Explorer programmes;
- for NASA: the Nimbus, Landsat, EOS, ESSP programmes; the SeaSat/ERBS/UARS satellites; and a selection of other missions relevant for GOS;
- for JAXA: the MOS-1, MOS-1B, JERS, ADEOS-1, ADEOS-2, ALOS and GOSAT satellites;
- for CNES: the SPOT and Plèiades programmes, and atmospheric and oceanic missions;
- for ISRO: the IRS programme;
- for RosKosmos: the Resurs and Okean programmes, the Monitor-E satellite.

In this Report, the following information is provided, for each satellite programme:

- a short description of the programme, inclusive of some historical background
- the status of the currently operational satellites
- a description of the next satellites in the series
- the radio frequency plans for data transmission to the ground (limited to meteorological satellites) (in **Annex 1**)
- tables containing instrument information for currently operational and consolidated planned payloads (in **Annex 3**).

The level of detail of instrument description is uneven: the basic imagery and sounding missions are described to some extent, whereas other missions are mentioned to a lower extent.

The Report attempts to assess the degree of compliance of the operational meteorological satellite constellation with WMO requirements in respect of the following features:

- coverage from the geostationary orbit (requirement: global in the latitude belt $\pm 55^\circ$)
- coverage from the sunsynchronous orbits (requirement: global each three hours)
- suitability of the instrumentation to provide information of comparable quality across systems.

It is recognised that the parts of the Report dealing with operational meteorology and R&D programmes do not have the same level of accuracy. The reason is that, for operational meteorology, this document is already at its third iteration (CGMS XXXII, XXXIII and XXXIV), and benefited of intensive interaction with most agencies responsible of meteorological satellite. For the R&D part this is the second issue (CGMS XXXIII and XXXIV), and the interaction with R&D space agencies has been less intensive.

When compiling this Report, extensive use has been made of information available from the Web. On this subject, it is regretted that the trend in web architecture is in the direction of more and more spectacle, sometime at level of advertisement, and less technical information.

It would have been useful to assimilate in this Report the last-minute information provided by CGMS members at the CGMS Session. Unfortunately, though the issue of this Report has been differed as much as practicable, up to 12 days prior to CGMS XXXIV only very few Members had loaded their reports on the status of current and planned satellites.

2. GEOSTATIONARY METEOROLOGICAL SATELLITES

2.1 Generalities

At the time of the First GARP Global Experiment (FGGE, 1979-80) the WMO requirement for geostationary satellites was four satellites, regularly spaced by about 90° around the equator. The coverage was varying from a maximum of over 60° latitude at the longitude of stationarity to a minimum of 45° latitude in between the stationarity points of two satellites. In the early 90's the

requirement was increased to five satellites spaced 72° to rise the minimum coverage to about 52° latitude. In 2002 the requirement has been increased to six satellites optimally spaced, that extends global coverage to a minimum of 55° latitude. That also ensures that sufficient contingency margins exist in case one of the satellites is defective, waiting for the replacement.

The mission of geostationary satellites is, as a core:

- to provide cloud imagery at 30 min intervals for the purpose of nowcasting
- to derive wind vectors by tracking cloud or water vapour features, for the purpose of NWP.

Several satellites provide more than this. Some provide more frequent images, some temperature and humidity profiles by IR radiometry, some Earth radiation budget observation. In addition, several products are derived by image processing, specifically surface parameters and precipitation estimates. It is reminded that the “*Implementation Plan for Evolution of Space and Surface-based Sub-systems of the GOS*” developed by the CBS Open Programme Area Group on the Integrated Observing Systems (OPAG-IOS) (WMO/TD No. 1267 dated April 2005), recommended that, as concerns future geostationary satellites:

- *GEO Imagers - Imagers of future geostationary satellites should have improved spatial and temporal resolution (appropriate to the phenomena being observed), in particular for those spectral bands relevant for depiction of rapidly developing small-scale events and retrieval of wind information.*
- *GEO Sounders - All meteorological geostationary satellites should be equipped with hyper-spectral infrared sensors for frequent temperature/humidity sounding as well as tracer wind profiling with adequately high resolution (horizontal, vertical and time).*
- *GEO Sub-mm - An early demonstration mission on the applicability of sub-mm radiometry for precipitation estimation and cloud property definition from geostationary orbit should be provided, with a view to possible operational follow-on.*

The first two recommendations are consistent with CGMS Action 31.36, the third one with the CGMS initiative (Action 32.19) for an International Geostationary Laboratory (IGeoLab) as a mechanism to implement demonstration mission of potential operational interest through international cooperation.

2.2 The Meteosat programme

The Meteosat programme is designed to be fully redundant, with the nominal operational satellite stationary over 0°. The programme evolved through three phases:

- **Meteosat Pre-operational Programme** (Meteosat-1/2/3)
- **Meteosat Operational Programme (MOP)** (Meteosat-4/5/6/7, the last also known as **Meteosat Transition Programme** or **MTP**)
- **Meteosat Second Generation (MSG)** (Meteosat-8 and then 9/10/11).

All Meteosat satellites, both of the first series (**Fig. 2.2.1**) and MSG (**Fig. 2.2.2**), are spin-stabilised. **Table 2.2.1** summarises the chronology of the Meteosat programme.

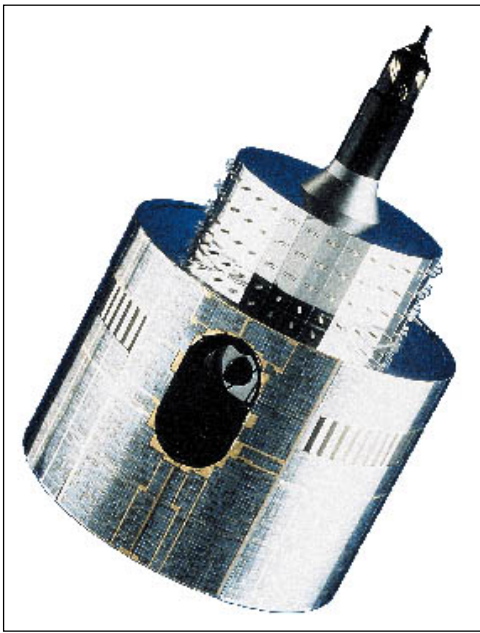


Fig. 2.2.1 - View of Meteorolite/MOP.



Fig. 2.2.1 – View of Meteorolite/MSG.

Table 2.2.1 - Chronology of the Meteorolite programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Position | Status (Sept 2006) | Instruments |
|------------------------------|--------------------|------------------------|-----------------|---------------------------------|----------------------------------|
| Meteorolite-1 | 23 Nov 1977 | 24 Nov 1979 | | Inactive | MVIRI, DCS |
| Meteorolite-2 | 19 Jun 1981 | 2 Dec 1991 | | Inactive | MVIRI, DCS |
| Meteorolite-3 | 15 Jun 1988 | 22 Nov 1995 | | Inactive | MVIRI, DCS |
| Meteorolite-4 | 6 Mar 1989 | 8 Nov 1995 | | Inactive | MVIRI, DCS |
| Meteorolite-5 | 2 Mar 1991 | expected ≥ 2007 | 63°E | Operational | MVIRI, DCS |
| Meteorolite-6 | 20 Nov 1993 | expected ≥ 2007 | 10°E | Backup (+ rapid scan) | MVIRI, DCS |
| Meteorolite-7 | 3 Sep 1997 | expected ≥ 2008 | → 57.5°E | To replace Meteorolite-5 | MVIRI, DCS |
| Meteorolite-8 (MSG-1) | 28 Aug 2002 | expected ≥ 2009 | 3.4°W | Operational | SEVIRI, GERB, DCS, GEOSAR |
| Meteorolite-9 (MSG-2) | 22 Dec 2005 | expected ≥ 2013 | → 0° | Hot standby | SEVIRI, GERB, DCS, GEOSAR |
| Meteorolite-10 | 2011 | expected ≥ 2018 | | In storage | SEVIRI, GERB, DCS, GEOSAR |
| Meteorolite-11 | 2013 | expected ≥ 2019 | | Being built | SEVIRI, GERB, DCS, GEOSAR |
| MTG | 2015 | expected ≥ 2020 | | Being defined | Being defined (FCI, IRS, LI) |

At mid-2006, three satellites of the MOP series are still active (Meteorolite 5, 6 and 7); the commissioning of the prototype of the MSG series (MSG-1 = Meteorolite-8) has been completed and the satellite is operational; MSG-2 (Meteorolite-9) has been successfully launched in December 2005 and its commissioning has recently been completed.

Meteorolite-5

Launched in March 1991, Meteorolite-5 was moved in July 1998 over the longitude of 63°E to support INDOEX (Indian Ocean Experiment). Since then it still continues to provide an operational service. It will be operated through 2006.

Meteorolite-6

Launched in November 1993, Meteorolite-6 was moved in August 2000 over the longitude of 9°W to support MAP (Mesoscale Alpine Programme) by providing frequent imagery (at 10 min intervals) over a limited area. Since then, the rapid scan service is being continued. It also constitutes the backup of Meteorolite-7, the nominal operational satellite of the MOP series. After the launch of MSG-1, in October 2002 it has been moved over 10°E. It could in principle be operated through 2008 and beyond.

Meteosat-7

Previously known as MTP (Meteosat Transition Programme), Meteosat-7, launched in September 1997, is the nominal MOP operational satellite over the 0° longitude. It has been operated till mid 2006 in parallel with MSG-1 to ensure a smooth transition between the two satellite generations. It is now being shifted to 57.5°E to replace Meteosat-5 for covering the Indian Ocean.

Payload of Meteosat 1 to 7

All Meteosat satellites till Meteosat-7 are equipped with a single sensor:

- **MVIRI (Meteosat Visible and Infra Red Imager)**, a 3-channel VIS/IR radiometer with 5 km resolution in two IR channels and 2.5 km in VIS; image cycle 30 min (or less, over a progressively limited area, as with Meteosat-6). See instrument sheet in Annex A3.1.
- **Data Collection Service (DCS)** to relay *in situ* observations from Data Collection Platforms (DCP) - Main features:
 - uplink: frequencies 402.0-402.1 MHz for 33 international channels, 402.1-402.2 MHz for 33 regional channels; bandwidth 3.0 kHz each, data rate 100 bps, polarisation right-hand circular.

Data transmission from Meteosat 1 to 7

Image data are transmitted in real time to the:

- **Primary Ground Station (PGS)**. Main transmission characteristics:
 - frequency 1686.833 MHz, bandwidth 1.3332 MHz, linear polarisation, data rate 333 kbps (nominal mode) and 5.4 MHz at data rate of 2.66 Mbps (burst mode).

After pre-processing, data are re-transmitted to user stations in S-band. There are two services:

- **HRIDS, High Resolution Image Dissemination Service**, for digital images
- **WEFAX Dissemination Service**, for analogue images.

Correspondingly, there are two types of user stations:

- **PDUS (Primary Data User Station)** - Main features:
 - frequency: 1694.5 MHz; bandwidth: 1.5 MHz; polarisation: linear
 - antenna diameter ~ 3 m, G/T ~ 10.5 dB/K, data rate 166 kbps.
- **SDUS (Secondary Data User Station)** - Main features:
 - frequency: 1691 (dedicated) and 1694.5 MHz (shared); bandwidth: 1.5 MHz; polarisation: linear
 - antenna diameter ~ 1.5 m, G/T ~ 2.5 dB/K, base band 1.6 kHz (analogue).

The satellites of the operational series (Meteosat 4 to 7) also provide:

- **Meteorological Data Distribution (MDD) Service** to relay meteorological maps (gridded or fac-simile) and other data from national meteorological centres to remote user terminals - Main features:
 - uplink: from up to four centres (currently from three: Rome, Bracknell and Toulouse);
 - user terminals: frequency 1695.68-1695.80 MHz (four 20-kHz-width channels spaced 31.2 kHz), antenna diameter ~ 2.4 m, G/T ~ 6.0 dB/K, data rate 2.4 kbps, linear polarisation.

Meteosat-8

Launched in August 2002, Meteosat-8, previously known as MSG-1, i.e., first flight model of the **Meteosat Second Generation** has completed its commissioning phase in December 2003 at the 10.5°W position. The satellite has been moved during January 2004 to a 3.4°W position to become operational in parallel with Meteosat-7.

Meteosat-9

Launched in December 2005, Meteosat-9, previously known as MSG-2, has completed its commissioning phase in June 2006 at the 6.4°W position. The satellite has been moved during July 2006 to the 0° position, to establish with Meteosat-8 the twin satellite configuration at

0 degrees. In parallel, Meteosat 7 has started the relocation to East, to continue the mission above the Indian Ocean after the end of life of Meteosat-5, at least until 2008.

Payload of Meteosat Second Generation

- **SEVIRI (Spinning Enhanced VIS and IR Imager)**, a 12-channel VIS/IR radiometer with 3 km resolution in 11 VIS/IR narrow-bandwidth channels and 1 km in one broad-bandwidth VIS channel, 15 min image cycle. See instrument sheet in Annex A3.1.
- **GERB (Geostationary Earth Radiation Budget experiment)**, 2-channel broad-band radiometer for Earth Radiation Budget, 42 km resolution, image cycle 5 min (or 15 min after integration to meet SNR requirements). See instrument sheet in Annex A3.1.
- **Data Collection Service (DCS)** to relay *in situ* observations from Data Collection Platforms (DCP) - Main features:
 - uplink: frequency 402.0-402.1 MHz for 33 international channels with 3 kHz bandwidth, 402.10-402.44 for 223 regional channels with 1.5 kHz bandwidth, 401.7-402.0 for 200 channels with 1.5 kHz bandwidth as contingency; data rate 100 bps, polarisation right-hand circular.
- **GEOSAR (Geostationary Search And Rescue)**, to relay distress signals from beacons at 406 MHz to a central European station of the international Search & Rescue system.

Data transmission from Meteosat Second Generation

Image data are transmitted in real time to the:

- **Primary Ground Station (PGS)**. Main transmission characteristics:
 - frequency 1686.833 MHz, bandwidth 5.4 MHz linear polarisation, data rate 3.2 Mbps.

After pre-processing, data are re-transmitted to user stations in S-band. There are two transmission services, both digital:

- **HRIT, High Rate Information Transmission**
- **LRIT, Low Rate Information Transmission**

Correspondingly, there are two types of user stations:

- **HRUS (High Rate User Station)** - Main features:
 - frequency: 1695.15 MHz; bandwidth: 2.0 MHz; polarisation: linear
 - antenna diameter ~ 3 m, G/T ~ 14 dB/K, data rate 1.0 Mbps;
- **LRUS (Low Rate User Station)** - Main features:
 - frequency: 1691.0 MHz; bandwidth: 0.66 MHz; polarisation: linear
 - antenna diameter ~ 2 m, G/T ~ 6 dB/K, data rate 128 kbps.

In addition, continuation is provided to:

- **Meteorological Data Distribution (MDD) Service** to relay meteorological maps and other data from national meteorological centres to remote user terminals - Main features:
 - uplink: from up to four centres (currently from three: Rome, Bracknell and Toulouse);
 - user terminals: not required in so far as the data are made available to HRUS and LRUS.

The EUMETCast service

As a matter of fact, one Meteosat-8 Solid State Power Amplifier basic for the HRIT and LRIT services failed in orbit. After that failure, the data to be disseminated (both images and DCP/MDD data) are been transmitted by means of commercial satellites using the Digital Video Broadcast (DVB) system. This is called **EUMETCast service**. This service has been baselined for the full duration of the MSG mission, in parallel the Power Amplifiers have been modified on MSG-2/3/4, ensuring the capability of the direct dissemination on board. The LRIT dissemination will be activated starting from Meteosat-9, although EUMETCast will remain the primary dissemination mean. There are two types of user terminals:

- Ku-band terminals (10853.44 MHz) served by HotBird-6 managed by EUTELSAT, optimally covering Europe; antenna diameter 85-180 cm; polarisation linear;

- C-band terminals served by Atlantic Bird-3 at 3731.757 MHz managed by EUTELSAT and NSS-806 at 3803 MHz managed by New Skies Satellites, together covering also Africa, Eastern North/Central America and Western Asia; antenna diameter 2.4-3.7 m; polarisation left-hand circular.

Plans for Meteosat Third Generation

Planning for MTG (Meteosat Third Generation) has started in early 2001 and, in mid-2003, initial requirements were agreed. After preliminary industrial studies and several iterations with the requirements, the Phase-A industrial study will start end-2006. The prototype MTG should be ready for launch in 2015. The following missions/instruments are being defined.

- **Flexible Combined imager (FCI)** - A 16-channel VIS/IR radiometer combining different resolutions and two operation modes, to meet regional nowcasting and global requirements:
 - 0.5 km resolution at 0.645 and 2.26 μm ; 1.0 km at 3.8 and 10.5 μm and in further 6 short-wave channels; 2.0 km in further 6 IR channels;
 - fast scanning (at 2.5 min intervals) over the northern quarter of the disk, full disk scanning at 10 min intervals; alternating scanning scenarios possible.
- **Infra-Red Sounder (IRS)** - An IR interferometer is foreseen, to provide high vertical resolution profile of temperature and humidity and derive wind profiles in clear air by tracking water vapour features in humidity profiles. Main features:
 - two spectral ranges: 4.6-6.25 μm and 8.26-14.3, spectral resolution 0.625 cm^{-1} ;
 - geometric resolution 4 km, full disk scanning in 30 min (or limited scanning at corresponding shorter intervals).
- **Lightning Imager (LI)** - CCD camera operating at 777.4 nm (O_2), full disk continuous coverage, resolution 10 km, time resolution ~ 1 ms, probability of lightning detection $> 90\%$, probability of false detection $< 1 \text{ s}^{-1}$.
- **Follow-on of GERB** - Not in the baseline, could be considered at a later stage.
- **Chemistry mission by UV/VIS spectroscopy** - Requirements and instrument definition being developed. It could be considered as a cooperative programme with the European Union and ESA.
- **Precipitation mission by MW/Sub-mm imagery/sounding** - Being considered as a side activity.

Instrument sheets of FCI, IRS and LI, although still in the definition phase, are provided in Annex A3.1.

2.3 The GOES programme

The GOES programme is designed to cover two positions (GOES-W at 135°W, GOES-E at 75°W) by two satellites, with one common backup satellite in intermediate position (105°W) to be moved in replacement of any of the two in case of failure. The programme evolved through the following phases:

- the precursor **ATS (Application Technology Satellite)**, ATS-1 and ATS-3 spin-stabilised, ATS-6 three-axis stabilised;
- the prototype **SMS (Synchronous Meteorological Satellite)** (SMS-1 and SMS-2) and the first three **GOES (Geostationary Operational Environmental Satellite)** (GOES-1/2/3), spin-stabilised, equipped with an imager (VISSR);
- GOES 4 to 7, with VISSR upgraded to VAS to provide either imagery or sounding;
- GOES-8 and follow-on (to continue to GOES-16), three-axis stabilised, equipped with independent IMAGER and SOUNDER.

Table 2.3.1 records the chronology of the GOES programme.

Table 2.3.1 - Chronology of the GOES programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Position | Status (Sept 2006) | Instruments |
|----------------|--------------------|--|--------------------------------------|--------------------|--|
| ATS-1 | 6 Dec 1966 | 1 Dec 1978 | | Inactive | SSCC |
| ATS-3 | 6 Nov 1967 | 1 Dec 1978 | | Inactive | MSSCC |
| ATS-6 | 30 Apr 1974 | 3 Aug 1979 | | Inactive | VHRR |
| SMS-1 | 17 May 1974 | 21 Jan 1981 | | Inactive | VISSR, DCIS, SEM |
| SMS-2 | 6 Feb 1975 | 5 Aug 1982 | | Inactive | VISSR, DCIS, SEM |
| GOES-1 | 16 Oct 1975 | 7 Mar 1985 | | Inactive | VISSR, DCIS, SEM |
| GOES-2 | 16 Jun 1977 | during 1993 | | Inactive | VISSR, DCIS, SEM |
| GOES-3 | 16 Jun 1978 | during 1993 | | Inactive | VISSR, DCIS, SEM |
| GOES-4 | 9 Sep 1980 | 11 Nov 1988 | | Inactive | VAS, DCIS, SEM |
| GOES-5 | 22 May 1981 | 18 Jul 1990 | | Inactive | VAS, DCIS, SEM |
| GOES-6 | 28 Apr 1983 | during 1989 | | Inactive | VAS, DCIS, SEM |
| GOES-7 | 26 Feb 1987 | 11 Jan 1996 | | Inactive | VAS, DCIS, SEM |
| GOES-8 | 13 Apr 1994 | 5 May 2004 | | Inactive | IMAGER, SOUNDER, DCIS, SEM, GEOSAR |
| GOES-9 | 23 May 1995 | expected \geq 2007 | 160°E | Standby | IMAGER, SOUNDER, DCIS, SEM, GEOSAR |
| GOES-10 | 25 Apr 1997 | expected \geq 2009 | \rightarrow 60°W | Operational | IMAGER, SOUNDER, DCIS, SEM, GEOSAR |
| GOES-11 | 3 May 2000 | expected \geq 2009 | 135°W | Operational | IMAGER, SOUNDER, DCIS, SEM, GEOSAR |
| GOES-12 | 23 Jul 2001 | expected \geq 2009 | 75°W | Operational | IMAGER, SOUNDER, DCIS, SEM, SXI, GEOSAR |
| GOES-13 | 24 May 2006 | expected \geq 2011 | \rightarrow 105°W | Post launch test | IMAGER, SOUNDER, DCIS, SEM, SXI, GEOSAR |
| GOES-14 | Feb 2007 | expected \geq 2014 | | Being built | IMAGER, SOUNDER, DCIS, SEM, SXI, GEOSAR |
| GOES-15 | Jan 2008 | expected \geq 2015 | | Planned | IMAGER, SOUNDER, DCIS, SEM, SXI, GEOSAR |
| GOES-R | 2014 | expected \geq 2021 | | Being defined | ABI, HES (to be confirmed), GML |

Short information on past series

ATS-1 and ATS-2 were equipped, respectively, with SSCC (Spin Scan Cloud Camera) e MSSCC (Multi-colour SSCC). ATS-6 was equipped with VHRR (Very High Resolution Radiometer) that, afterwards, became operational on the INSAT satellites.

The SMS-1, SMS-2 and GOES 1 to 3 were equipped with:

- **VISSR (Visible and Infrared Spin Scan Radiometer)**, a 2-channel VIS/IR radiometer with resolution 0.9 km in VIS (0.55-0.75 μ m) and 7 km in IR (10.5-12.6 μ m); cycle 30 min.

On GOES 4 to 7 VISSR was upgraded to enable temperature/humidity sounding, alternate with images:

- **VAS (VISSR Atmospheric Sounder)**, adding to the two VISSR channels further 12 narrow-bandwidth channels centred at 3.94, 4.44, 4.51, 6.7, 7.2, 11.2, 12.7, 13.3, 14.0, 14.2, 14.5 and 14.7 μ m; resolution 7 or 14 km depending on the channel, cycle lasting as necessary to collect enough energy as required for profile retrieval; generally used for limited area scanning.

Fig. 2.3.1 and **Fig. 2.3.2** show the change of structure from the GOES 4/5/6/7 spacecrafts to the current series (GOES-8 and follow-on).



Fig. 2.3.1 - View of GOES-4/5/6/7.

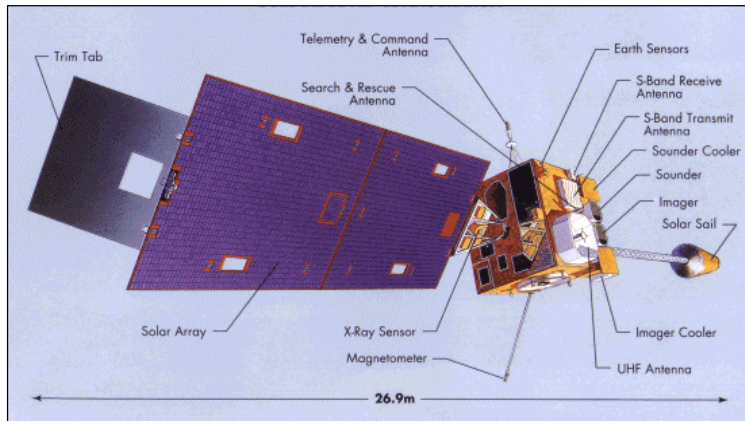


Fig. 2.3.2 – Sketch view of GOES-8 and follow-on.

GOES-9

Launched in May 1995, GOES-9 has served as GOES-W at 135°W until 1999, when GOES-10 took over. In early 2003 was moved to 155°E to partially fill the gap between the end-of-life of GMS-5 and the launch of MTSAT-1R in 2005. Currently the spacecraft is at 200°W in standby mode.

GOES-10

Launched in April 1997, GOES-10 was originally placed in the standby position at 105°W. From 1999 to June 2006 it served as the GOES West operational satellite at 135°W. Currently, the spacecraft is moving towards 60°W to provide better coverage of South America.

GOES-11 (current GOES-W)

Launched in May 2000, GOES-11 is the GOES West operational spacecraft at 135°W. It replaced GOES-10 as the GOES West spacecraft in June 2006.

GOES-12 (current GOES-E)

Launched in July 2001, GOES-12 was originally placed in the standby position at 105°W. Thereafter, spring 2003, it has replaced GOES-8 as the operational satellite at 75°W.

GOES-13 (post launch testing)

Launched in May 2006, GOES-13 is in the middle of Post Launch Testing. In December 2006, the spacecraft will be placed into storage at 105°W and will be available to replace either GOES-11 or GOES-12 if needed.

Payload of GOES 8 to 15

- **IMAGER**, a 5-channel VIS/IR radiometer with 4.0 km resolution in four IR channels and 1.0 km in the VIS channel, 30 min image cycle (less for limited areas). See instrument sheet in Annex A3.1.
- **SOUNDER**, a 19-channel IR sounding radiometer (including one in VIS) with 8.0 km resolution, generally used for limited areas (e.g., 1000 x 1000 km² in 5 min, 3000 x 3000 km² in 42 min: it would be 8 h for full disk). See instrument sheet in Annex A3.1.
- **Data Collection and Interrogation Service (DCIS)** to relay *in situ* observations from Data Collection Platforms (DCP) either transmitting at fixed times or after interrogation. This mission is in use, with progressive updating, since SMS-1. Main features:
 - uplink: two bands, frequencies 401.900 MHz and 402.200 MHz, bandwidth 350 kHz each for a total of 223 channels of bandwidth 3 kHz; data rate 100 bps, polarisation right-hand circular;
 - downlink for interrogation: two frequencies, 468.8250 MHz and 468.8375 MHz, bandwidths 200 kHz each, data rate 100 bps, polarisation right-hand circular.

- **Space Environment Monitoring (SEM)**, in use, with progressive updating, since SMS-1. A set of instruments for *in situ* measurement, at the platform's altitude, of:
 - EPS (Energetic Particles Sensor) for low-energy electron, proton and alpha particles
 - HEPAD (High Energy Proton and Alpha Particles Detector)
 - XRS (X-Ray Sensor)
 - two redundant Magnetometers.
- **Solar X-ray Imager (SXI)**, starting with GOES-12, to image the sun each minute.
- **PDR, Processed Data Relay**, associated to the WEFAX service (in use since SMS-1).
- **GEOSAR (Geostationary Search And Rescue)**, to relay distress signals from beacons at 406 MHz to the American Search & Rescue Coordination Center.

Data transmission from GOES

GOES data are transmitted in real time to the:

- **Command and Data Acquisition station (CDA)**. Main transmission characteristics:
 - frequency 1676.2 MHz, bandwidth 6.0 MHz, linear polarisation, data rate 3.0 Mbps.

Afterwards, data are re-transmitted to several centres in several modes. The ones that concern most users occurs after pre-processing, to two types of S-band stations:

- **GVAR (GOES Variable Data Format)**, for processed image and sounding data - Main features:
 - frequency: 1685.7 MHz; bandwidth: 5.0 MHz; polarisation: linear
 - antenna diameter ~ 3 m, G/T ~ 16 dB/K, data rate 2.1 Mbps;
- **WEFAX**, for selected image frames - Main features:
 - frequency: 1691.0 MHz; bandwidth: 1.0 MHz; polarisation: linear
 - antenna diameter ~ 1.5 m, G/T ~ 2.5 dB/K, base band 1.6 kHz (analogue).

The WEFAX mode is fully consistent with that one of Meteosat 1 to 7. GOES-12 has started to alternate the analogue WEFAX transmission to the digital mode as MSG (LRIT), i.e. for stations:

- **LRUS (Low Rate User Station)** - Main features:
 - frequency: 1691.0 MHz; bandwidth: 0.66 MHz; polarisation: linear
 - antenna diameter ~ 2 m, G/T ~ 6 dB/K, data rate 128 kbps.

It is foreseen that, during 2005, WEFAX will definitively be replaced by LRIT.

Plans for GOES next generation starting with GOES-R (GOES-16)

Planning for GOES-R has started in early 2001 and is making progress under the guidance of the yearly GOES User Conference. The launch should be in 2014. The following instruments are being defined.

- **ABI (Advanced Baseline Imager)**, with about 16 VIS/IR channels, resolution 2 km for 12 channels, 0.5 km for one VIS channel, 1.0 km for other three SW channels, cycle 15 min for full disk, 5 min for 3000 x 5000 km² ("CONUS", Continental United States), 30 s for 1000 x 1000 km²;
- **HES (Hyperspectral Environmental Suite)**, initially defined to address several objectives: full disk sounding, limited-area nowcasting and coastal water observation (ocean colour). Spectral range for sounding from 4.44 μm (option 3.68 μm) to 15.38 μm (with gaps) with resolving power changing with band from 1000 to 3000, plus one VIS channel. For coastal waters about 14 VIS/NIR channels of 20 nm width and possibly 3 SWIR channels of 30 or 50 nm width and the split IR window at 11 and 12 μm. Geometric resolution: 2 to 10 km for sounding (0.5-1.0 km for the VIS channel), 0.15 to 2 km for coastal waters. Cycle: maximum 1 h for full disk, down to minutes depending on operating mode. HES has currently been removed from the GOES-R baseline and its plan is being revisited.
- **GLM (Geostationary Lightning Mapper)**, CCD camera operating at 777.4 nm (O₂), resolution 8 km, time resolution 2 ms, probability of lightning detection > 90 %, probability of false detection < 1 s⁻¹.

- **MW/Sub-mm imaging/sounder for precipitation**, being studied as a side activity.

Instrument sheets of ABI, HES (before revisiting) and GLM are provided in Annex A3.1.

2.4 The GMS and MTSAT programmes

The Japanese **GMS (Geostationary Meteorological Satellite)**¹ was a spin-stabilised satellite (**Fig. 2.4.1**) to cover the position 140°E. Its successor, **MTSAT (Multi-functional Transport Satellite)**, is 3-axis stabilised (**Fig. 2.4.2**), coupling the meteorological mission to an aviation navigation one. **Table 2.4.1** records the chronology of the GMS/MTSAT programme.

Table 2.4.1 - Chronology of the GMS/MTSAT programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Position | Status (mid-2006) | Instruments |
|-----------------|--------------------|------------------------|--------------|--------------------|--------------------|
| GMS-1 | 14 Jul 1977 | 30 Jun 1989 | | Inactive | VISSR, DCS |
| GMS-2 | 11 Aug 1981 | 20 Nov 1987 | | Inactive | VISSR, DCS |
| GMS-3 | 3 Aug 1984 | 22 Jun 1995 | | Inactive | VISSR, DCS |
| GMS-4 | 6 Sep 1989 | 24 Feb 2000 | | Inactive | VISSR, DCS |
| GMS-5 | 18 Mar 1995 | 21 Jul 2005 | | Inactive | VISSR, DCS |
| MTSAT-1R | 26 Feb 2005 | expected ≥ 2015 | 140°E | Operational | JAMI, DCS |
| MTSAT-2 | 18 Feb 2006 | expected ≥ 2016 | 145°E | Standby | IMAGER, DCS |

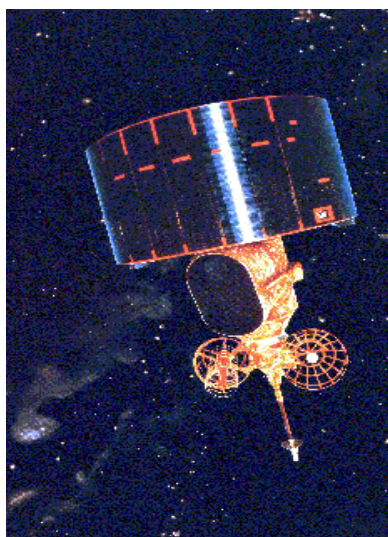


Fig. 2.4.1-View of GMS

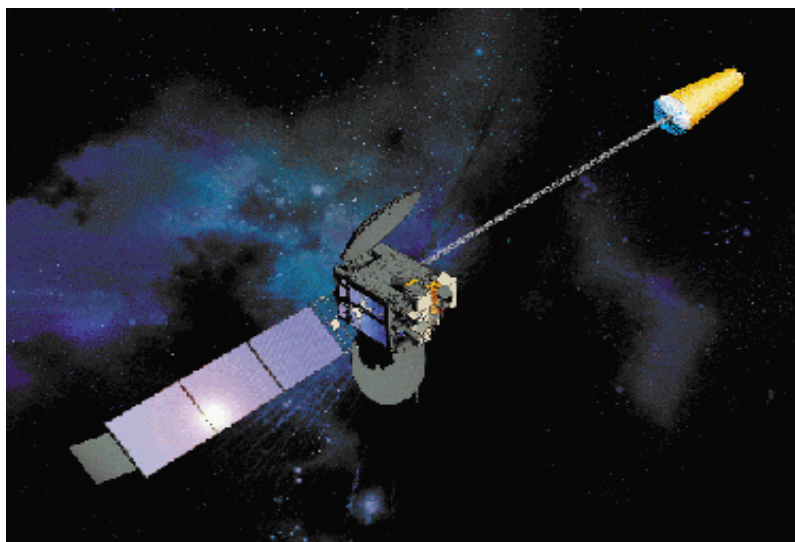


Fig. 2.4.2-View of MTSAT-1R

The last GMS satellite in the series, GMS-5, was equipped with:

- **VISSR (Visible and Infrared Spin-Scan Radiometer)**, a 4-channel VIS/IR radiometer with 5.0 km resolution in three IR channels (6.5-7.0 μm , 10.5-11.5 μm and 11.5-12.5 μm) and 1.25 km in the VIS channel (0.55-0.90 μm), 30 min image cycle (less for limited areas).
- **DCS (Data Collection Service)**, also foreseen on MTSAT (see next).

The first launch of MTSAT failed in 1999. **MTSAT-1R** had been launched on 26 February 2005. **MTSAT-2** has been launched on 18 February 2006, and placed in standby until 2010.

Payload of MTSAT-1R

- **JAMI (Japanese Advanced Meteorological Imager)**: a 5-channel VIS/IR radiometer with 4.0 km resolution in four IR channels and 1.0 km in the VIS channel, 30 min image cycle (half disk in 15 min image cycle). Re-named **IMAGER** on MTSAT-2. See the instrument sheets of JAMI and IMAGER in Annex A3.1.

¹ Original name: *Himawari*, that means “Sun Flower”.

- **Data Collection Service (DCS)** to relay *in situ* observations from Data Collection Platforms (DCP) either transmitting at fixed times or after interrogation - Main features:
 - uplink: two bands, frequencies 402.0-402.1 MHz for international DCP's (33 channels of bandwidth 3 kHz), 402.1-402.4 MHz for regional DCP's (100 channels of bandwidth 3 kHz); data rate 300/100 bps, polarisation right-hand circular;
 - downlink for interrogation: frequency 468.875 MHz for international DCP's, 468.924 MHz for regional DCP's, bandwidth 5.0 kHz each, data rate 300 bps, polarisation right-hand circular.

Data transmission from MTSAT-1R and MTSAT-2

MTSAT-1R data are transmitted in real time to the:

- Command and Data Acquisition Station (CDAS). Main transmission characteristics:
 - frequency 1677.0 MHz, bandwidth 8.2 MHz, linear polarisation, data rate 2.7 Mbps.

Afterwards, data are re-transmitted to user stations. Initially, MTSAT-1R is being providing compatibility with existing receiving stations for GMS; then, compatible HiRID and WEFAX will be ended in 2007.

New format image data has been disseminated since the MTSAT-1R beginning of operation.

- **HiRID (High Resolution Imager Data)** provides service continuity for the Medium-scale Data Utilisation Stations (MDUS) toward the end of 2007. Main features:
 - frequency: 1687.1 MHz; bandwidth: 2.0 MHz; polarisation: linear
 - antenna diameter ~ 4 m, G/T ~ 10.4 dB/K, data rate 660 kbps;
- **HRIT (High Resolution Information Transmission)** was started on 28 June 2005. Main features:
 - frequency: 1687.1 MHz; bandwidth: 5.2 MHz; polarisation: linear
 - antenna diameter ~ 4 m, G/T ~ 10.4 dB/K, data rate 3.5 Mbps;
- **WEFAX (Weather Facsimile)** will be time-shared toward the end of 2007 and then replaced by the **LRIT**, that also similar to MSG and GOES. Main features:
 - frequency: 1691.0 MHz; bandwidth: 250 kHz; polarisation: linear
 - antenna diameter ~ 2.5 m, G/T ~ 3 dB/K, base band 1.6 kHz (analogue).
- **LRIT (Low Rate Information Transmission)** was started on 28 June 2005. Main features:
 - frequency: 1691.0 MHz; bandwidth: 250 kHz; polarisation: linear
 - antenna diameter ~ 2.5 m, G/T ~ 3 dB/K, data rate 75 kbps.



2.5 The GOMS/Elektro programme

The Russian programme **GOMS (Geostationary Operational Meteorological Satellites)**, also called **Elektro**, is based on 3-axis stabilized satellites due to cover the 76°E position. The first spacecraft, named GOMS-N1 (**Fig. 2.5.1**), was launched in 1994, but its functioning experienced several problem till final deactivation in 1998. The next flight unit is now being prepared, as a first satellite of a new series **Elektro-L (Fig. 2.5.2)**. **Table 2.5.1** records the chronology of the GOMS/Elektro programme.

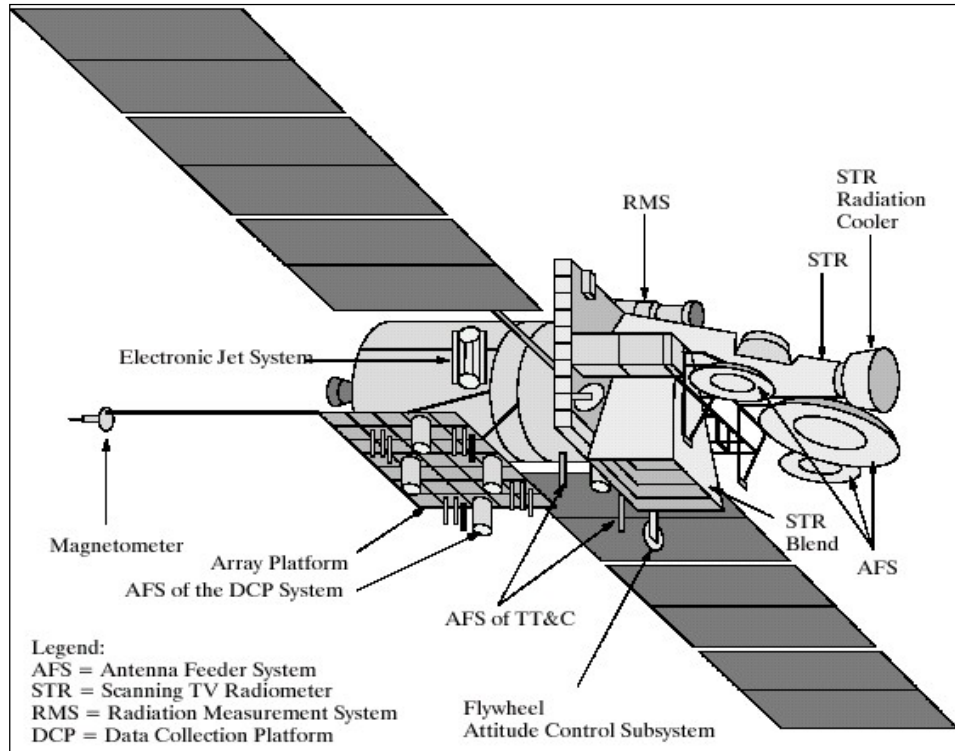


Fig. 2.5.1 – Sketch view of GOMS-N1.

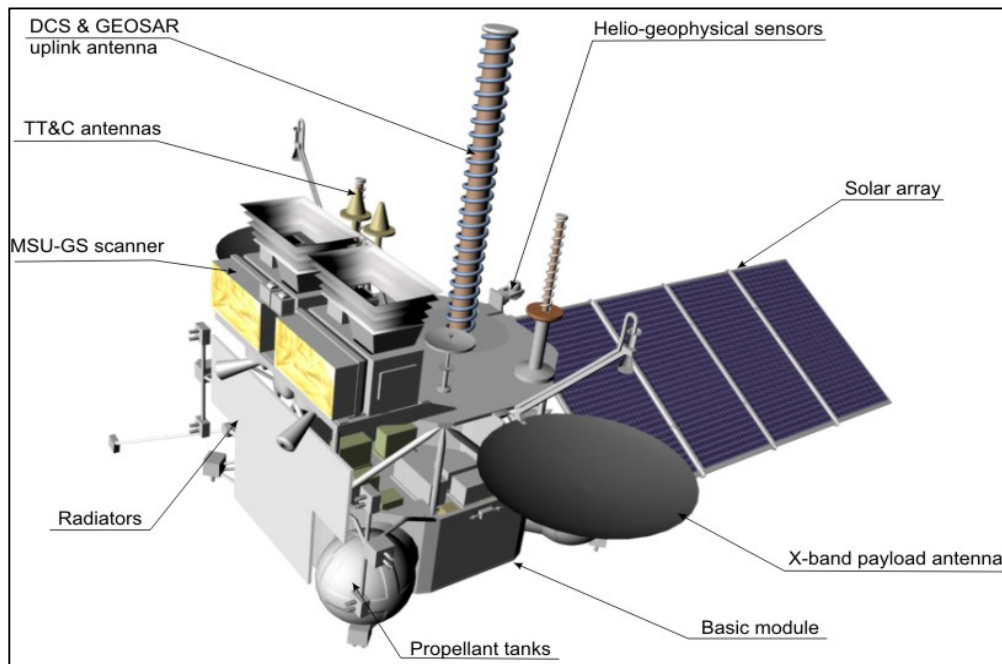


Fig. 2.5.2 – Sketch view of Elektro-L N1.

Table 2.5.1 - Chronology of the GOMS / Elektro programme (no satellite active at September 2005)

| Satellite | Launch | End of service | Position | Status (Sept 2005) | Instruments |
|-------------|-------------|-----------------|----------------|--------------------|--------------------------|
| GOMS-1 | 31 Oct 1994 | during 1998 | 76°E | Inactive | STR, DCS, RMS |
| Elektro-L-1 | 2007 | expected ≥ 2014 | 76°E | Being built | MSU-GS, DCS, HMS, GEOSAR |
| Elektro-L-2 | 2010 | expected ≥ 2017 | 76°E or 14.5°E | Planned | MSU-GS, DCS, HMS, GEOSAR |
| Elektro-L-3 | 2015 | expected ≥ 2022 | 76°E or 14.5°E | Planned | MSU-GS, DCS, HMS, GEOSAR |

GOMS-1 was equipped with the radiometer:

- **STR (Scanning TV Radiometer)**: it was a 3-channels VIS/IR radiometer; 6.5 km resolution in two IR channels (6.0-7.0 μm and 10.5-12.5 μm), 1.25 km in VIS (0.46-0.70 μm), 30 min image cycle.

Elektro-L is being built for a first launch in 2007 and a second one in 2009.

Payload of Elektro-L

- **MSU-GS**, a 10-channel VIS/IR imaging radiometer with 4.0 km resolution in seven IR channels and 1.0 km in three VIS channels, 15-30 min image cycle. See instrument sheet in Annex A3.1.
- **Data Collection Service (DCS)**, to relay *in situ* observations from Data Collection Platforms (DCP) at fixed times - Main features:
 - uplink: three bands, frequencies 402.0-402.1 MHz for international DCP's (33 channels of bandwidth 3 kHz), 401.5-402.0 MHz and 402.1-402.5 MHz for regional DCP's (300 channels of bandwidth 3 kHz); data rate 100 bps, polarisation right-hand circular;
 - downlink for DCS ground acquisition station: 1697 MHz, bandwidths 2 MHz, data rate 100-1200 bps, linear polarisation.
- **Heliogeophysical Measurements System (HMS)**, for *in situ* measurement of charged particles of the solar wind at the platform's altitude.
- **GEOSAR (Geostationary Search And Rescue)**, to relay distress signals from beacons at 406 MHz to stations of the international COSPAS/SARSAT Search & Rescue system.

Data transmission from Elektro-L

Elektro-L data are transmitted in real time to the:

- **Raw Data Acquisition Station (RDAS)** for MSU-GS and HMS. Main features:
 - frequency: 7500 MHz; bandwidth: 60 MHz; polarisation: right-hand circular; data rate 30.72 Mbps.

Afterwards, data are re-transmitted to user stations. The broadcast will comply with the HRIT and LRIT standards:

- **HRIT (High Rate Information Transmission)**. Main features:
 - frequency: 1691.0 MHz; bandwidth: 2 MHz; polarisation: right-hand circular
 - antenna diameter \sim 3.7 m, G/T \sim 12 dB/K, data rate 0.665-1 Mbps;
- **LRIT (Low Rate Information Transmission)**, similar to MSG, GOES and MTSAT. Main features:
 - frequency: 1691.0 MHz; bandwidth: 200 kHz; polarisation: right-hand circular
 - antenna diameter \sim 1.5 m, G/T \sim 4 dB/K, data rate 64-128 kbps.
- **DCS Acquisition station (DCSA)**. Main features:
 - frequency 1697 MHz, bandwidth 2 MHz, linear polarisation, data rate 100-1200 bps.

2.6 The FY-2 and FY-4 programmes

The Chinese series **FY-2 (Feng-Yun-2)**², operational since 1997, due to cover the 105°E position, is spin stabilised (**Fig. 2.6.1**). The next generation, **FY-4** (see **Fig. 2.6.2**), to take service around 2012, will be 3-axis stabilised. **Table 2.6.1** records the chronology of the FY-2/F-4 programme.

² **Feng-Yun** means "Wind and Cloud". The "2" series is geostationary, the "1" and "3" series sunsynchronous.

Table 2.6.1 - Chronology of the FY-2 and FY-4 programmes (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Position | Status (Sept 2006) | Instruments |
|--------------|--------------------|------------------------|-----------------|--------------------|-------------------------------------|
| FY-2A | 10 Jun 1997 | 08 April 1998 | 86.5°E | Inactive | S-VISSR, DCS, SEM |
| FY-2B | 25 Jun 2000 | Sept. 2004 | 123°E | Partial backup | S-VISSR, DCS, SEM |
| FY-2C | 19 Oct 2004 | expected ≥ 2009 | 105°E | Operational | S-VISSR (improved), DCS, SEM |
| FY-2D | 2006 | expected ≥ 2011 | 86.5°E | Ready for launch | S-VISSR (improved), DCS, SEM |
| FY-2E | 2009 | expected ≥ 2014 | 123°E | Planned | S-VISSR (improved), DCS, SEM |
| FY-2F | 2011 | expected ≥ 2016 | 86.5°E | Planned | S-VISSR (improved), DCS, SEM |
| FY-2G | 2013 | expected ≥ 2018 | 123°E | Planned | S-VISSR (improved), DCS, SEM |
| FY-4O/A | 2012 | expected ≥ 2017 | 105°E or 86.5°E | Being defined | Imager, sounder, lightning mapper |
| FY-4M/A | 2015 | expected ≥ 2020 | 123°E | Being defined | MW radiometer |

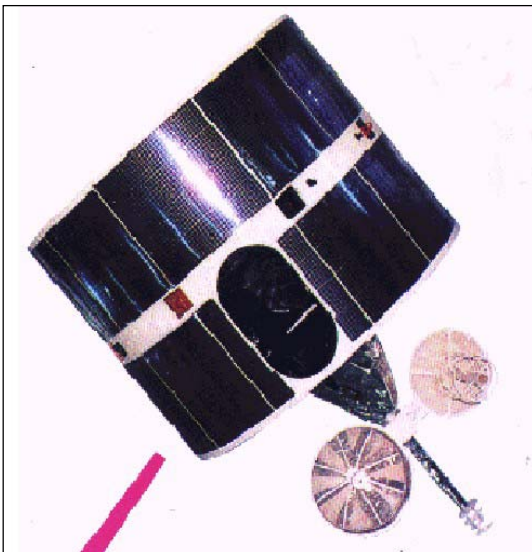


Fig. 2.6.1 – View of FY-2.

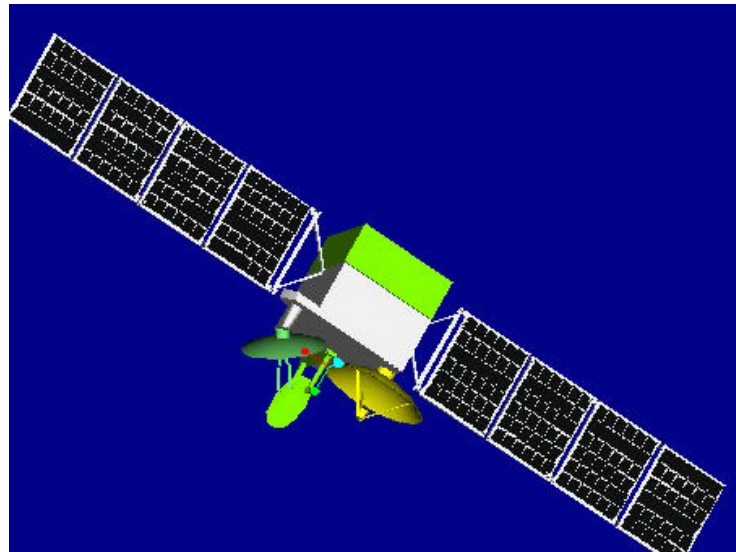


Fig. 2.6.2 – View of FY-4.

FY-2A

Launched in June 1997 on the 105°E position, was moved to 86.5°E in July 2000 to leave the operational service to FY-2B. It still has some capabilities that could be used in emergency.

FY-2B

Launched in June 2000, it exhibits now several operational limitation and serves as backup at 123.5°E.

FY-2C, 2D, 2E, 2F and 2G

FY-2C has been launched on 19 October 2004, and will be followed by FY-2D (2006), FY-2E (2009), FY-2F (2011) and FY-2G (2013). The payload has been improved in respect of that one of FY-2A/B.

Payload of FY-2

- **S-VISSR (Stretched Visible and Infrared Spin Scan Radiometer)** – The version of FY-2A/B had three VIS/IR channels (0.5-1.05 μm , 6.3-7.6 μm and 10.5-12.5 μm) the improved version for FY-2 C/D/E/F splits the IR channel in two and adds a 3.5-4.0 μm channel. The resolution also is slightly improved: from 5.76 km (IR) and 1.44 km (VIS), to 5.0 km (IR) and 1.25 km (VIS). The image cycle is 30 min. See instrument sheet in Annex A3.1.
- **Data Collection Service (DCS)** - Main features:
 - uplink: two bands, frequencies 402.0-402.1 MHz for international DCP's (33 channels of bandwidth 3 kHz), 401.1-401.4 MHz for regional DCP's (100 channels of bandwidth 3 kHz); data rate 100 bps, polarisation right-hand circular.

- **SEM (Space Environment Monitor).**

Data transmission from FY-2

FY-2 data are transmitted in real time to the:

- **Command and Data Acquisition Station (CDAS).** Main transmission characteristics:
 - frequency 1681.6 MHz, bandwidth 14 MHz, linear polarisation, data rate 14 Mbps.

Afterwards, data are re-transmitted to user stations. The broadcast will comply with the HRIT and LRIT standards and initially, with WEFAX for continuity reasons:

- **S-VISSR Data Transmission**, compatible with MDUS acquisition stations. Main features:
 - frequency: 1687.5 MHz; bandwidth: 2.0 MHz; polarisation: linear
 - antenna diameter ~ 3 m, G/T ~ 12 dB/K, data rate 660 kbps.
- **WEFAX** from FY-2 A/B, **LRIT (Low Rate Information Transmission)** from FY-2 C/D/E/F, similar to MSG, GOES, MTSAT and GOMS-Elektro-L. Main features of LRIT:
 - frequency: 1691.0 MHz; bandwidth: 260 kHz; polarisation: linear
 - antenna diameter ~ 1 m, G/T ~ 3 dB/K, data rate 150 kbps.

FY-4

A second generation geostationary series, **FY-4**, in being defined. It will be based on a 3-axis stabilized platform, with much improved payload in respect of FY-2. Currently, it is thought to have two types of missions:

- the series **FY-4O** ('O' stands for 'optical'), prototype to be launched around 2012 currently thought to be equipped by:
 - an advanced VIS/IR imager comparable with those of GOES-R and Meteosat 3rd Generation,
 - an advanced IR sounding spectrometer-interferometer,
 - a lightning mapper,
 - a Solar X-ray Detector and a Space Environment Monitor;
- the series **FY-4M** ('M' stands for 'microwave') prototype to be launched around 2015, currently thought to be equipped by:
 - a millimetre-submillimetre-wave radiometer for nearly-all-weather sounding and precipitation.

2.7 The INSAT and Kalpana programmes

Although not part of the GOS, the **Indian National Satellite programme (INSAT)** supports national requirements and is coordinated within CGMS. It combines the meteorological mission with the function of supporting domestic telecommunications. It is a 3-axis stabilised satellite (**Fig. 2.7.1**), with generally two flight models in orbit, at 74°E and 93.5°E. Not all INSAT flight models carry a meteorological payload. In 2002 a small satellite entirely dedicated to meteorology, originally named **MetSat**, thereafter renamed **Kalpana**³, was launched over 74°E. **Table 2.7.1** records the chronology of the INSAT and Kalpana programmes.

³ Kalpana is the name of the female astronaut of Indian ancestry lost with the accident of the Shuttle "Columbia" in February 2003.

Table 2.7.1 - Chronology of the INSAT and Kalpana programmes (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Position | Status (Sept 2006) | Instruments |
|------------------|--------------------|--|---------------|--------------------|-----------------------|
| INSAT-1A | 10 Apr 1982 | 6 Sep 1982 | | Inactive | VHRR, DCS |
| INSAT-1B | 30 Aug 1983 | Jul 1993 | | Inactive | VHRR, DCS |
| INSAT-1C | 22 Jul 1988 | Nov 1989 | | Inactive | VHRR, DCS |
| INSAT-1D | 12 Jun 1990 | May 2002 | | Inactive | VHRR, DCS |
| INSAT-2A | 10 Jul 1992 | 30 May 2002 | | Inactive | VHRR, DCS |
| INSAT-2B | 23 Jul 1993 | 2004 | | Inactive | VHRR, DCS |
| INSAT-2C | 7 Dec 1995 | April 2002 | | Inactive | No meteo |
| INSAT-2D | 4 Jun 1997 | 4 Oct 1997 | | Inactive | No meteo |
| INSAT-2E | 3 Apr 1999 | expected \geq 2006 | 83°E | Meteo not used | VHRR, CCD |
| INSAT-3A | 10 Apr 2003 | expected \geq 2012 | 93.5°E | Operational | VHRR, CCD, DCS |
| INSAT-3B | 22 Mar 2000 | expected \geq 2008 | | Operational | No meteo |
| INSAT-3C | 24 Jan 2002 | expected \geq 2010 | 74°E | Operational | Meteo telecom only |
| INSAT-3D | 2007 | expected \geq 2014 | 83°E | Being built | IMAGER, SOUNDER, DCS |
| Kalpana-1 | 12 Sep 2002 | expected \geq 2010 | 74°E | Operational | VHRR, DCS |

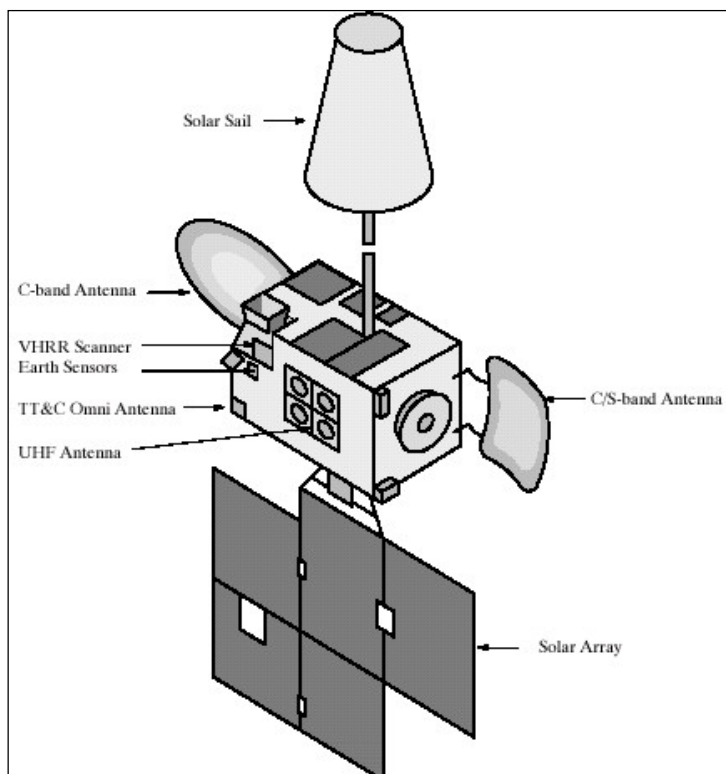


Fig. 2.7.1 – Sketch view of INSAT satellites.



Fig. 2.7.2 – View of Kalpana.

The series **INSAT-1**, used from 1982 to 2002, was carrying an imager, **VHRR**, derived by ATS-6 (see Table 2.3.1). It had only two VIS/IR channels (0.55-0.75 μm and 10.5-12.5 μm); resolution 11 km in IR, 2.75 km in VIS.

INSAT-2E and 3A

INSAT 2E, launched in April 1999, is no longer being used for meteorological services. This satellite is located over 83°E. **INSAT-3A** is the operational satellite, on 93.5°E.

Kalpana-1

The Kalpana-1 satellite was launched in September 2002 as a part of dedicated meteorological mission. It provides the operational service from 74°E.

Payload of INSAT and Kalpana satellites

- **VHRR (Very High Resolution Radiometer)** is a 3-channels VIS/IR/WV radiometer with 8 km resolution in the IR/WV channels and 2 km in the VIS channel (INSAT-1 and INSAT-2 A/B had only two channels). The image cycle is three hours for INSAT 3A and hourly for Kalpana-1, but more frequent images are taken at half an hour intervals to generate cloud motion winds at 00, 06, 12, 18 UTC every day. See instrument sheet in Annex A3.1.
- On INSAT-2E and INSAT-3A: **CCD Camera**, a TV camera with three VIS/NIR/SWIR channels each at 1 km resolution, image cycle 3 hours, more frequent on demand. See instrument sheet in Annex A3.1.
- **Data Collection Service (DCS)** - Main features:
 - uplink: frequencies 402.65-402.85 MHz for international DCP's (8 channels of bandwidth 6 kHz), data rate 4.8 kbps, polarisation right-hand circular.

INSAT-3D

The traditional difficulty with INSAT usage was the need to share satellite resources with the (priority) telecommunication mission. **INSAT-3D**, instead, is being designed to be dedicated to meteorology. It will have imagery and sounding capabilities similar to those of the current GOES series:

- **IMAGER**, a 6-channels VIS/IR radiometer with 4.0 km resolution in 3 IR channels, 1.0 km in the VIS channel, 8 km in the water-vapour channels. Image cycle 30 min. See instrument sheet in Annex A3.1.
- **SOUNDER**, a 19-channel IR radiometer (including a VIS channels), 10 km resolution, Cycle 3 hours for 6000 km x 6000 km viewing area. See instrument sheet in Annex A3.1.

Data transmission from INSAT and Kalpana

INSAT and Kalpana data are first transmitted in real time to:

- **Command and Data Acquisition Station (CDAS)**: main transmission characteristics:
 - VHRR frequency 4503.5 (Kalpana-1), 4501.5 (INSAT-3A) MHz, bandwidth 500 kHz, linear polarisation, data rate 526.5 kbps. CCD frequency 4508.93 (INSAT-3A) MHz, bandwidth 500 kHz, linear polarisation, data rate 1.28875 Mbps.

After ground processing, data are provided to the users by using INSAT-3C. There are two modes:

- **Meteorological Data Dissemination (MDD) Service**. Regular transmissions occur at 3-hour interval. Main features:
 - uplink: from the system central processing facility at 5899.225 MHz;
 - user terminals: frequency 2599.225 MHz, bandwidth 200 kHz, linear polarisation, antenna diameter ~ 3.66 m, G/T ~ 9 dB/K, base band 10 kHz (analogue); in progress to be changed to digital, frequency 2586.000, data rate 64/128 kbps.
- **Cyclone Warning Dissemination System (CWDS)**, activated during the cyclone season. Features:
 - uplink: from the system central processing facility at 5859.225 MHz and 5885.0 MHz;

- user terminals: frequency 2559.225 MHz, bandwidth 200 kHz, linear polarisation, antenna diameter ~ 3.66 m, G/T ~ 9 dB/K, base band 10 kHz (analogue); in progress to be changed to digital, frequency 2585.0 or 2615.0 GHz, data rate 64/128 kbps.

With INSAT-3D, 2007, the system will be brought to compliance with HRIT and LRIT standards.

2.8 The COMS programme

The Korea Aerospace Research Institute (KARI) is developing **COMS (Communication, Oceanography and Meteorology Satellite)** for the Korea Meteorological Administration (KMA). It will be a multi-purpose satellite, 3-axis stabilised. **Table 2.8.1** records the planning details as known so far. **Fig. 2.8.1** provides an idea of the spacecraft structure

Table 2.8.1 - Chronology of the COMS programme

| Satellite | Launch | End of service | Position | Status (Sept 2006) | Instruments |
|-----------|--------|----------------------|----------------------|--------------------|-------------|
| COMS-1 | 2008 | expected \geq 2015 | 128.2°E (or 116.2°E) | Being defined | MI, GOCI |
| COMS-2 | 2014 | expected \geq 2021 | 128.2°E (or 116.2°E) | Being defined | TBD |

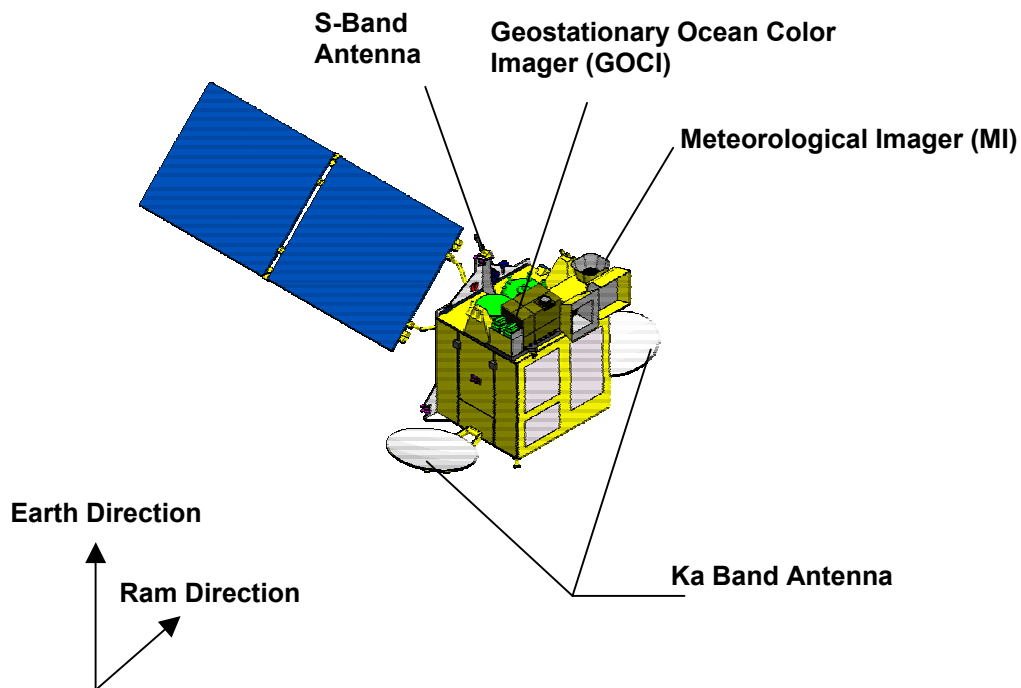


Fig. 2.8.1 - Sketch view of COMS.

The **COMS payload** for Earth Observation includes:

- A **Meteorological Imager (MI)** with 5 channels in the range 0.55-12.5 μm , resolution 1 km in 1 VIS channel, 4 km in 4 IR channels, 27 min for full disk imaging (proportionally less for limited areas). See instrument sheet in Annex A3.1.
- A **Geostationary Ocean Colour Imager (GOCI)** with 8 narrow-band channels in the range 400-865 nm for ocean colour monitoring; resolution 500 m over a limited coverage (2500 km x 2500 km). See instrument sheet in Annex A3.1.

Data transmission from COMS

Raw data are transmitted to:

- the **Meteo/Ocean Data Application Center (MODAC)** and the Satellite Operation Center. MODAC includes the Korea Meteorological Satellite Center (MSC) and the Korea Ocean Satellite Center (KOSC). Main feature:
 - frequency 1687 MHz, bandwidth 6.0 MHz, polarisation RHC or LHC, data rate 6 Mbps.

After ground processing at MODAC, data are re-transmitted to the users by:

- **HRIT (High Rate Information Transmission)**. Main features:
 - uplink: from the system central processing facility at 2040.9 MHz; antenna diameter ~ 13 m;
 - user terminals: frequency 1695.4 MHz; bandwidth: 5.2 MHz; polarisation: RHC or LHC, antenna diameter ~ 3.7 m, G/T ~ dB/K, data rate 3 Mbps;
- **LRIT (Low Rate Information Transmission)**, similar to MSG, GOES and MTSAT. Main features:
 - uplink: from the system central processing facility at 2037.64 MHz; antenna diameter ~ 13 m;
 - user terminals: frequency 1692.14 MHz; bandwidth: 1.0 MHz; polarisation: RHC or LHC, antenna diameter ~ 1.2 m, G/T ~ dB/K, data rate 256 kbps.

2.9 Coverage provided by geostationary satellites in 2006 and 2008

In this Section the compliance of the constellation of geostationary satellites with WMO requirements is evaluated. Since the requirement calls for six satellites equally spaced around the equator, **Table 2.9.1** identifies six sectors each one 60° wide. In addition, since two main satellites, Elektro-L and INSAT-3D, are planned for launch in 2007, and COMS-1 in 2008, the perspective situation in year 2008 is shown in **Table 2.9.2**. For 2008, the assumption has been made that INSAT-3D takes the current position of INSAT-2E (83°E) and GOES-13 replaces GOES-11 at 135°E. It is further assumed that, with the advent of INSAT-3D at 83°E, Kalpana-1 (74°E) and INSAT-3A (93.5°E), that have inferior instruments, are considered backup of INSAT-3D; and that FY-2D (86.5°E) is backup of FY-2C (105°E) (or that they have inverted positions, with 105°E as primary). GOES-11 has not been allocated.

Table 2.9.1 - Coverage from GEO as of September 2006 (CGMS XXXIV)

| Geographic area | Satellite | Position | Status (Sept 2006) | Main instruments |
|---|------------|----------|-----------------------|------------------|
| 30°W - 30°E Europe, Africa, Eastern Atlantic | Meteosat-8 | 3.4°W | Operational | SEVIRI, GERB |
| | Meteosat-9 | 0° | Hot standby | SEVIRI, GERB |
| | Meteosat-6 | 10°E | Backup + Rapid scan | MVIRI |
| 30°E - 90°E Western Asia, Indian Ocean | Meteosat-7 | → 57.5°E | To replace Meteosat-5 | MVIRI |
| | Meteosat-5 | 63°E | Operational | MVIRI |
| | Kalpana-1 | 74°E | Operational | VHRR |
| 90°E - 150°E East-Asia, Australia, West- Pacific | INSAT-3A | 93.5°E | Operational | VHRR, CCD |
| | FY-2C | 105°E | Operational | S-VISSR |
| | FY-2B | 123.5°E | Partial backup | S-VISSR |
| | MTSAT-1R | 140°E | Operational | JAMI |
| | MTSAT-2 | 145°E | Hot standby | IMAGER |
| 150°E - 150°W Oceania, Central Pacific | GOES-9 | 160°E | Standby | IMAGER, SOUNDER |
| 150°W - 90°W East-Pacific, North-West America | GOES-11 | 135°W | Operational | IMAGER, SOUNDER |
| | GOES-13 | → 105°W | Being commissioned | IMAGER, SOUNDER |
| 90°W - 30°W South America, NE America, West Atlantic | GOES-12 | 75°W | Operational | IMAGER, SOUNDER |
| | GOES-10 | → 60°W | Operational | IMAGER, SOUNDER |

Table 2.9.2 - Coverage from GEO as expected for 2008

| Geographic area | Satellite | Position | Expected status in 2007 | Main instruments |
|---|--------------------|----------------|-------------------------|------------------------|
| 30°W - 30°E Europe, Africa, Eastern Atlantic | Meteosat-9 | 0° | Operational | SEVIRI, GERB |
| | Meteosat-8 | 3.4°W | Hot standby | SEVIRI, GERB |
| 30°E - 90°E Western Asia, Indian Ocean | Meteosat-7 | 57.5°E | Operational | MVIRI |
| | Kalpana-1 | 74°E | Backup of INSAT-3D | VHRR |
| | Elektro-L-1 | 76°E | Operational | MSU-GS |
| | INSAT-3D | 83°E | Operational | IMAGER, SOUNDER |
| 90°E - 150°E East-Asia, Australia, West- Pacific | FY-2D | 86.5°E | Backup of FY-2C | S-VISSR |
| | INSAT-3A | 93.5°E | Backup of INSAT-3D | VHRR, CCD |
| | FY-2C | 105°E | Operational | S-VISSR |
| | COMS-1 | 128.2°E | Operational | MI, GOCI |
| | MTSAT-1R | 140°E | Operational | JAMI |
| 150°E - 150°W Oceania, Central Pacific | MTSAT-2 | 145°E | Hot standby | IMAGER |
| | | | | |
| 150°W - 90°W East-Pacific, North-West America | GOES-13 | 135°W | Operational | IMAGER, SOUNDER |
| | GOES-14 | 105°W | Hot standby | IMAGER, SOUNDER |
| 90°W - 30°W South America, NE America, West Atlantic | GOES-12 | 75°W | Operational | IMAGER, SOUNDER |
| | GOES-10 | 60°W | Operational | IMAGER, SOUNDER |

Table 2.9.3 shows the distribution of gaps of coverage in respect of the required $\pm 55^\circ$ latitude. The gaps in respect of the requirement are highlighted in grey

Table 2.9.3 – Latitudinal coverage at Sept 2006 and expected for 2008 (highlighted if < 55°)

| 2006 | GOES-11 | GOES-12 | GOES-10 | Meteosat-8 | Meteosat-5 | Kalpana-1 | INSAT-3A | FY-2C | MTSAT-1R | GOES-11 | |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|---------|
| S.S.P. | 135°W | 75°W | 60°W | 3.4°W | 63°E | 74°E | 93.5°E | 105°E | 140°E | 135°W | |
| Δ SSP | 60° | 15° | 56.6° | 66.4° | 11° | 19.5° | 11.5° | 35° | 85° | | |
| Latitude cover | $\pm 55^\circ$ | $\pm 59^\circ$ | $\pm 56^\circ$ | $\pm 53^\circ$ | $\pm 60^\circ$ | $\pm 59^\circ$ | $\pm 60^\circ$ | $\pm 58^\circ$ | $\pm 47^\circ$ | | |
| 2008 | GOES-13 | GOES-12 | GOES-10 | Meteosat-9 | Meteosat-7 | Elektro-L-1 | INSAT-3D | FY-2C | COMS-1 | MTSAT-1R | GOES-13 |
| S.S.P. | 135°W | 75°W | 60°W | 0° | 57.5°E | 76°E | 83°E | 105°E | 128.2°E | 140°E | 135°W |
| Δ SSP | 60° | 15° | 60° | 57.5° | 18.5° | 7° | 22° | 23.2° | 11.8° | 85° | |
| Latitude cover | $\pm 55^\circ$ | $\pm 59^\circ$ | $\pm 55^\circ$ | $\pm 56^\circ$ | $\pm 59^\circ$ | $\pm 60^\circ$ | $\pm 59^\circ$ | $\pm 59^\circ$ | $\pm 60^\circ$ | $\pm 47^\circ$ | |

It is noted that the major gap is over Oceania and Central Pacific, where at the longitude of about 180° the covered latitude range drops to $\pm 47^\circ$. A minor gap is in the Middle-East until Meteosat-9 takes over the 0° position. It is noted that, in the mid-Atlantic, there is no gap thanks to GOES-10, otherwise there would be a substantial gap around the longitude of about 40° W where the covered latitude range would drop to about $\pm 51^\circ$.

Fig. 2.9.1 and **Fig. 2.9.2** show the composite coverage from the operational satellites in September 2006 and in 2008, respectively (in bold in Tables 2.9.1 and 2.9.2). The figures should be compared with the WMO requirement shown in Fig. 1.1. It can be noted that, from a “mechanical” viewpoint, i.e. independent on data quality (the subject of section 2.10, next), the coverage situation, though not optimal, is and will remain satisfactory. Also, there is enough built-in contingency to keep the system operational under most circumstances.

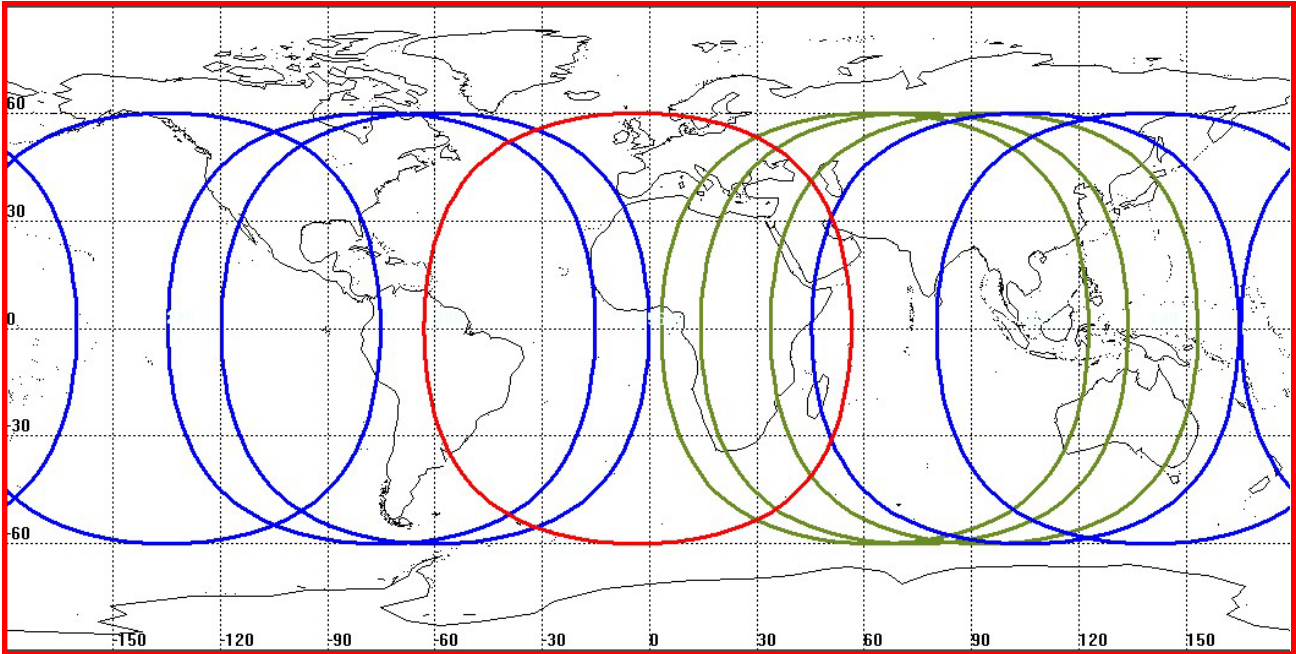


Fig. 2.9.1 – Coverage from operational geostationary satellites as of September 2006. Satellites: GOES-11 (135°W), GOES-12 (75°W), GOES-10 (60°W), Meteosat-8 (3.4°W), Meteosat-5 (63°E), Kalpana-1 (74°E), INSAT-3A (93.5°E), FY-2C (105°E) and MTSAT-1R (140°E). The figure also highlights the quality of the imager. Red: advanced imagers (only Meteosat-8 SEVIRI); blue: 5 channel imagers (GOES-11/12 IMAGER, FY-2C S-VISSR, MTSAT-1R JAMI); green: 3 channel imagers (Meteosat-5 MVIRI, INSAT-3A VHRR and CCD, Kalpana-1 VHRR).

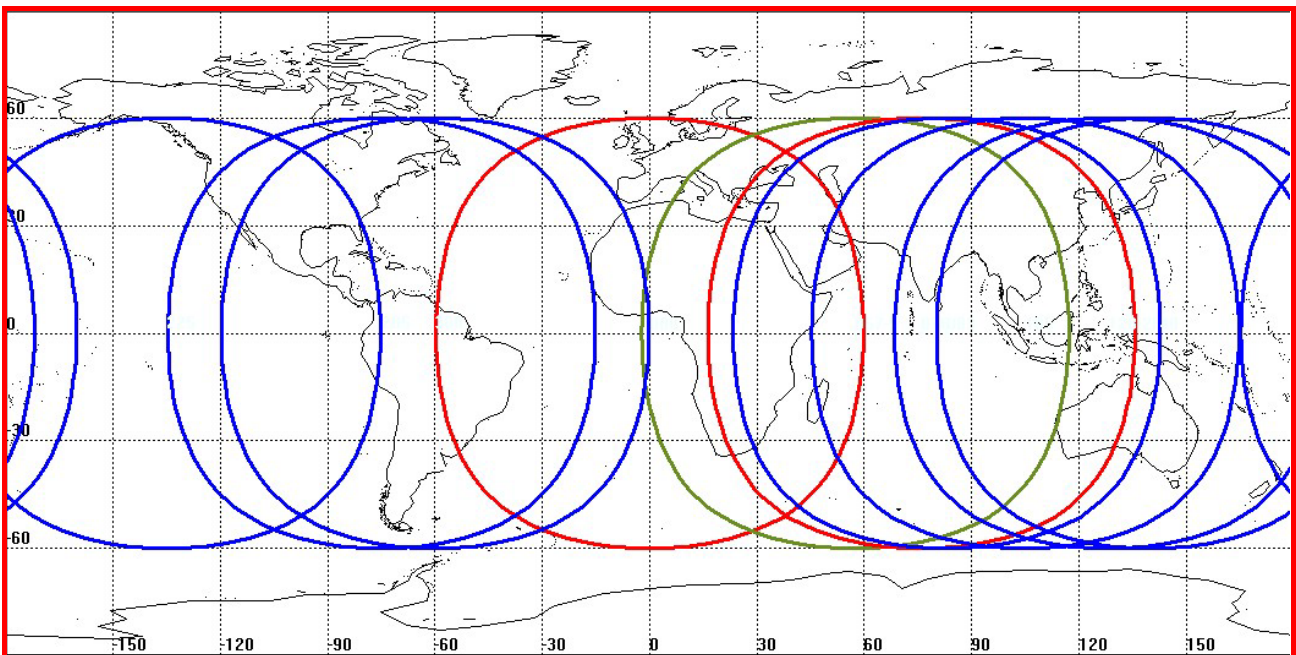


Fig. 2.9.2 – Coverage from operational geostationary satellites as expected in 2008. Satellites: GOES-13 (135°W), GOES-12 (75°W), GOES-10 (60°W), Meteosat-9 (0°), Meteosat-7 (57.5°E), Elektro-L-1 (76°E), INSAT-3D (83°E), FY-2C (105°E), COMS-1 (128.2°E) and MTSAT-1R (140°E). The figure also highlights the quality of the imager. Red: advanced imagers (Meteosat-9 SEVIRI, Elektro-L-1 MSU-GS); blue: 5-6 channel imagers (GOES 12/13 IMAGER, INSAT-3D IMAGER, FY-2C S-VISSR, COMS-1 MI and MTSAT-1 JAMI); green: 3 channel imagers (Meteosat-7 MVIRI).

2.10 Comparative instrument performances

In addition to the coverage, the system also must provide homogeneous performances in terms of data quality, that depends on the instruments. **Table 2.10.1** compares the main features of imagers being operational in September 2006, **Table 2.10.2** refers instead to what is expected in year 2008.

Table 2.10.1 - Main features of imagers on-board GEO satellites in Sept 2006

| Meteosat-8 SEVIRI (*) | Meteosat-5 MVIRI | GOES-10/11 IMAGER | GOES-12 IMAGER | FY-2C S-VISSR | INSAT-3A VHRR + CCD | MTSAT-1R JAMI | Kalpana-1 VHRR |
|-------------------------------|-------------------------------|-------------------------|-------------------------|---------------------------|---------------------------------------|-------------------------|-------------------------|
| 12.4-14.4 μm | | | 13.0-13.7 μm | | | | |
| 11.0-13.0 μm | | 11.5-12.5 μm | | 11.5-12.5 μm | | 11.5-12.5 μm | |
| 9.80-11.8 μm | 10.5-12.5 μm | 10.2-11.2 μm | 10.2-11.2 μm | 10.3-11.3 μm | 10.5-12.5 μm | 10.3-11.3 μm | 10.5-12.5 μm |
| 9.38-9.94 μm | | | | | | | |
| 8.30-9.10 μm | | | | | | | |
| 6.85-7.85 μm | | | | | | | |
| 5.35-7.15 μm | 5.70-7.10 μm | 6.50-7.00 μm | 5.80-7.30 μm | 6.30-7.60 μm | 5.70-7.10 μm | 6.50-7.00 μm | 5.70-7.10 μm |
| 3.40-4.20 μm | | 3.80-4.00 μm | 3.80-4.00 μm | 3.50-4.00 μm | | 3.50-4.00 μm | |
| 1.50-1.78 μm | | | | | 1.55-1.70 μm | | |
| 0.74-0.88 μm | | | | | 0.77-0.86 μm | | |
| 0.56-0.71 μm | 0.50-0.90 μm | 0.55-0.75 μm | 0.55-0.75 μm | 0.55-0.99 μm | 0.55-0.75 μm | 0.55-0.90 μm | 0.55-0.75 μm |
| 0.60-0.90 μm | | | | | 0.63-0.79 μm | | |
| 15 min | 30 min | 30 min | 30 min | 30 min | 180 min | 30 min | 3 hours |
| VIS/IR 3.0 km HRVIS 1.0 km | VIS/IR 5.0 km HRVIS 2.5 km | IR 4.0 km VIS 1.0 km | IR 4.0 km VIS 1.0 km | IR 5.76 km VIS 1.44 km | IR 8.0 km VIS 2.0 km CCD 1.0 km | IR 4.0 km VIS 1.0 km | IR 8.0 km VIS 2.0 km |

(*) SEVIRI channels are defined as 99 % of encircled energy instead of half-power-width.

Table 2.10.2 - Main features of imagers on-board GEO satellites expected for 2008

| Meteosat-9 SEVIRI (*) | Meteosat-7 MVIRI | GOES-10 IMAGER | GOES-12/13 IMAGER | MTSAT-1 JAMI | Elektro-L-1 MSU-GS | FY-2C S-VISSR | INSAT-3D IMAGER | COMS-1 MI |
|-------------------------------|-------------------------------|-------------------------|-------------------------|-------------------------|----------------------------|--------------------------|--------------------------------|-------------------------|
| 12.4-14.4 μm | | | 13.0-13.7 μm | | | | | |
| 11.0-13.0 μm | | 11.5-12.5 μm | | 11.5-12.5 μm | 11.2-12.5 μm | 11.5-12.5 μm | 11.5-12.5 μm | 11.5-12.5 μm |
| 9.80-11.8 μm | 10.5-12.5 μm | 10.2-11.2 μm | 10.2-11.2 μm | 10.3-11.3 μm | 10.2-11.2 μm | 10.3-11.3 μm | 10.2-11.2 μm | 10.3-11.3 μm |
| 9.38-9.94 μm | | | | | 9.20-10.2 μm | | | |
| 8.30-9.10 μm | | | | | 8.20-9.20 μm | | | |
| 6.85-7.85 μm | | | | | 7.50-8.50 μm | | | |
| 5.35-7.15 μm | 5.70-7.10 μm | 6.50-7.00 μm | 5.80-7.30 μm | 6.50-7.00 μm | 5.70-7.00 μm | 6.30-7.60 μm | 6.50-7.00 μm | 6.5-7.0 μm |
| 3.40-4.20 μm | | 3.80-4.00 μm | 3.80-4.00 μm | 3.50-4.00 μm | 3.50-4.00 μm | 3.50-4.00 μm | 3.80-4.00 μm | 3.50-4.0 μm |
| 1.50-1.78 μm | | | | | | | 1.55-1.70 μm | |
| 0.74-0.88 μm | | | | | 0.80-0.90 μm | | | |
| 0.56-0.71 μm | 0.50-0.90 μm | 0.55-0.75 μm | 0.55-0.75 μm | 0.55-0.90 μm | 0.65-0.80 μm | 0.55-0.99 μm | 0.52-0.72 μm | 0.55-0.8 μm |
| 0.60-0.90 μm | | | | | 0.50-0.65 μm | | | |
| 15 min | 30 min | 30 min | 30 min | 30 min | 15 min | 30 min | 30 min | 30 min |
| VIS/IR 3.0 km HRVIS 1.0 km | VIS/IR 5.0 km HRVIS 2.5 km | IR 4.0 km VIS 1.0 km | IR 4.0 km VIS 1.0 km | IR 4.0 km VIS 1.0 km | IR 4.0 km VIS/NIR 1.0km | IR 5.0 km VIS 1.25 km | IR 4km,WV 8km VIS/NIR 1.0km | IR 4.0 km VIS 1.0 km |

(*) SEVIRI channels are defined as 99 % of encircled energy instead of half-power-width.

Three categories of instruments can be identified:

- with 3 channels: Meteosat-5/7 MVIRI, Kalpana-1 VHRR, INSAT-3A VHRR, INSAT-3-A CCD;
- 5-6 channels: GOES-10/11/12/13 IMAGER, MTSAT-1R JAMI, FY-2C S-VISSR, INSAT-3D IMAGER, COMS-1 MI;
- advanced imagers with pseudo-sounding capability: Meteosat-8/9 SEVIRI, Elektro-L-1 MSU-GS.

In Fig. 2.9.1 and Fig. 2.9.2 the coverage from images of different classes is highlighted by different colours. It is noted that in September 2006 there is lack of quality in Central Asia / Indian Ocean, whereas in 2008 this gap will be filled.

3. SUNSYNCHRONOUS METEOROLOGICAL SATELLITES

3.1 Generalities

At the time of the First GARP Global Experiment (FGGE, 1979-80) the WMO requirement for sunsynchronous satellites was two satellites with orthogonal orbital planes. For large-swath instruments with day and night capability this would ensure global coverage at 6-hour intervals. In the 90's, the EUMETSAT and NOAA agreement for a Joint Polar System (JPS) was aiming at three satellites with orbital planes de-phased by 60° so as to achieve global coverage at 4-hour intervals. In 2002 the WMO requirement has been increased to four satellites, two in morning orbits and two in afternoon orbits, so as to provide global coverage at 3-hour intervals in average, and also to ensure that sufficient contingency margins exist in case one of the satellites experiences degraded performance, waiting for the replacement.

The mission of sunsynchronous satellites is, as a minimum:

- to provide temperature and humidity global sounding for the purpose of NWP;
- to provide imagery mission to high latitudes inaccessible to geostationary satellites.

Several satellites provide more than this. Some provide observation of ozone and other trace gases, some exploit microwave radiometry for precipitation observation, some carry active microwave instruments (radar) for, e.g., sea-surface wind observation, etceteras. In addition, several products are derived by image processing, specifically surface parameters. Imaging and sounding instruments are in continuous upgrading process, generally under the aspects of number of channels (imagers) and spectral resolution (sounders). As for further upgrading to be pursued within the operational context, it is reminded that the "*Implementation Plan for Evolution of Space and Surface-based Sub-systems of the GOS*" developed by the CBS Open Programme Area Group on the Integrated Observing Systems (OPAG-IOS) (WMO/TD No. 1267 dated April 2005), as concerns future polar satellites has recommended the following:

- *LEO Sea Surface Wind - Sea-surface wind data from R&D satellites should continue to be made available for operational use; 6-hourly coverage is required. In the NPOESS and Metop era, sea surface wind should be observed in a fully operational framework. Therefore it is urgent to assess whether the multi-polarisation passive MW radiometry is competitive with scatterometry.*
- *LEO Altimeter - Missions for ocean topography should become an integral part of the operational system.*
- *LEO Earth Radiation Budget - Continuity of ERB-type global measurements for climate records requires immediate planning to maintain broad-band radiometers on at least one LEO satellite.*

In addition, OPAG-IOS indicated missions to be prepared by R&D satellites before considering their adoption into an operational framework. These recommendation are recorded in Section 4.1 to follow.

3.2 The NOAA/POES programme

The American **POES (Polar-orbiting Operational Environmental Satellite)**, when considering the precursor series TIROS, ESSA and ITOS, is the most long-standing meteorological satellite programme (first launch: 1° April 1960). It evolved through the following phases.

- 1st generation – Ten satellites **TIROS (Television and Infra-Red Observation Satellite)**, spin-stabilised (**Fig. 3.2.1**), to experience orbits, instruments and communication systems. Instruments:
 - VCS (Vidicon Camera System) with Narrow-Angle (NA) and high resolution (0.25 km), Medium-Angle (MA) and resolution (1.6 km), Wide-Angle (WA) and low resolution (2.4 km);
 - APT (Automatic Picture Transmission), resolution 1.8 km;
 - MRIR (Medium Resolution Infrared Radiometer) and FPR (Flat Plate Radiometer)
- 2nd generation – Nine satellites **ESSA (Environmental Science and Services Administration)**, two in orbit at any time (**TOS, TIROS Operational System**) for image broadcasting either in real time (ESSA-2/4/6/8) or after on-board storage (ESSA-1/3/5/7/9).

They were spin-stabilised in a “cartwheel” mode so as to be able to point the camera towards Earth (**Fig. 3.2.2**). Instruments:

- on ESSA-2/4/6/8: APT (Automatic Picture Transmission), resolution 3.7 km;
 - on ESSA-1/3/5/7/9: AVCS (Advanced Vidicon Camera System), resolution 3.7 km, and FPR.
- 3rd generation – Six satellites **ITOS (Improved TOS)**, the first named TIROS-M or ITOS-1, the other ones **NOAA (National Oceanic and Atmospheric Administration) (Fig. 3.2.3)**. They introduced IR imagery and temperature sounding. 3-axis stabilised. Instruments:
 - SR (Scanning Radiometer): 0.55-0.75 μ m, resolution 3.6 km, and 10.5-12.5 μ m, 7.2 km;
 - VHRR (Very High Resolution Radiometer): same channels as SR but with resolution 0.9 km;
 - VTPR (Vertical Temperature Profile Radiometer): 8 channels, 11 to 20 μ m, resolution 55 km;
 - SPM (Solar Proton Monitor) and FPR;
 - 4th generation – Ten operational satellites, the first named TIROS-N, the following nine **NOAA** from 6 to 14, with an improvement (**ATN, Advanced TIROS-N**) starting from NOAA-8. Two satellites in orbit at any time, with LST (Local Solar Time) at 7.30 and 14.00. 3-axis-stabilised. Instruments:
 - AVHRR (Advanced VHRR): see next
 - HIRS/2 (High-resolution Infra Red Sounder): see next
 - MSU (Microwave Sounding Unit): 4 channels from 50 to 58 GHz, resolution 110 km
 - SSU (Stratospheric Sounding Unit): three channels around 14.95 μ m, resolution 150 km
 - SBUV/2 (Solar Backscatter Ultraviolet): see next
 - ERBE (Earth Radiation Budget Experiment): only on NOAA-9 and NOAA-10
 - SEM (Space Environment Monitor), SARSAT (Search and Rescue Satellite Aided Tracking System), ARGOS/DCS (ARGOS Data Collection System); see next.
 - 5th generation, the current one, now called **POES (Polar-orbiting Operational Environmental Satellite)**, started in 1998 with NOAA-15, to be used until around 2012 by five flight models (NOAA-K/L/M/N/N'). POES satellites (**Fig. 3.2.4**) still use the 3-axis stabilised ATN platform and are in orbit two at any time, at LST 7.30 and 14.00. The difference between the 4th and 5th generations consists of the improvement of the instrumentation for MW atmospheric sounding.

Table 3.2.1 records the chronology of NOAA and precursor satellites. For sunsynchronous satellites (starting with TIROS-9) the LST is provided, for previous the orbital inclination. Morning LST's are defined at the equatorial descending node, afternoon at the ascending node.

As of September 2006, the two nominal operational satellites are NOAA-17 and NOAA-18, with NOAA-15 and NOAA-16 still sufficiently efficient as to act as backup. NOAA-12 and NOAA-14 still have some functionalities (NOAA-12: AVHRR, SEM and Argos; NOAA-14, the last satellite of the 4th generation, still has SSU, Argos and SARSAT operable).

Table 3.2.1 – Chronology of the NOAA/POES programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST or inclin. | Status (Sept 2006) | Instruments |
|-------------------|-------------|-----------------|---------|----------------|--------------------|--|
| TIROS-1 | 1 Apr 1960 | 17 Jun 1960 | 720 km | 48.4° | Inactive | VCS-WA, VCS-NA |
| TIROS-2 | 23 Nov 1960 | 24 Dec 1961 | 670 km | 48.6° | Inactive | VCS-WA, VCS-NA, MRIR, FPR |
| TIROS-3 | 12 Jul 1961 | 27 Feb 1962 | 780 km | 47.9° | Inactive | 2 x VCS-WA, MRIR, FPR |
| TIROS-4 | 8 Feb 1962 | 19 Jul 1962 | 770 km | 48.3° | Inactive | VCS-WA, VCS-MA, MRIR, FPR |
| TIROS-5 | 19 Jun 1962 | 27 Nov 1963 | 750 km | 58.1° | Inactive | VCS-WA, VCS-MA |
| TIROS-6 | 18 Sep 1962 | 12 Oct 1963 | 700 km | 58.3° | Inactive | VCS-WA, VCS-MA |
| TIROS-7 | 19 Jun 1963 | 3 Jun 1968 | 680 km | 58.2° | Inactive | 2 x VCS-WA, MRIR, FPR |
| TIROS-8 | 21 Dec 1963 | 1 Jul 1967 | 730 km | 58.5° | Inactive | APT, VCS-WA |
| TIROS-9 | 22 Jan 1965 | 12 Jun 1968 | 1350 km | 9.30 d | Inactive | 2 x VCS-WA ("cartwheel") |
| TIROS-10 | 2 Jul 1965 | 1 Jul 1967 | 790 km | 9.30 d | Inactive | 2 x VCS-WA |
| ESSA-1 | 3 Feb 1966 | 8 Mar 1967 | 770 km | 9.30 d | Inactive | 2 x VCS-WA, FPR |
| ESSA-2 | 28 Feb 1966 | 16 Oct 1970 | 1390 km | 9.30 d | Inactive | 2 x APT |
| ESSA-3 | 2 Oct 1966 | 2 Dec 1968 | 1440 km | 9.30 d | Inactive | 2 x AVCS, FPR |
| ESSA-4 | 26 Jan 1967 | 5 May 1968 | 1380 km | 9.30 d | Inactive | 2 x APT |
| ESSA-5 | 20 Apr 1967 | 20 Feb 1970 | 1390 km | 9.30 d | Inactive | 2 x AVCS, FPR |
| ESSA-6 | 10 Nov 1967 | 3 Dec 1969 | 1450 km | 9.30 d | Inactive | 2 x APT |
| ESSA-7 | 16 Aug 1968 | 10 Mar 1970 | 1450 km | 9.30 d | Inactive | 2 x AVCS, 2 x FPR |
| ESSA-8 | 15 Dec 1968 | 12 Mar 1976 | 1440 km | 9.30 d | Inactive | 2 x APT |
| ESSA-9 | 26 Feb 1969 | 15 Nov 1972 | 1470 km | 9.30 d | Inactive | 2 x AVCS, 2 x FPR |
| ITOS-1 (TIROS-M) | 23 Jan 1970 | 18 Jun 1971 | 1470 km | 14.30 a | Inactive | 2 x AVCS, 2 x APT, 2 x SR, FPR, SPM |
| NOAA-1 (ITOS-A) | 11 Dec 1970 | 19 Aug 1971 | 1450 km | 13.30 a | Inactive | 2 x AVCS, 2 x APT, 2 x SR, FPR, SPM |
| NOAA-2 (ITOS-D) | 13 Oct 1972 | 30 Jan 1975 | 1450 km | 14.30 a | Inactive | 2 x VHRR, 2 x SR, 2 x VTPR, SPM |
| NOAA-3 (ITOS-F) | 6 Nov 1973 | 31 Aug 1976 | 1500 km | 14.30 a | Inactive | 2 x VHRR, 2 x SR, 2 x VTPR, SPM |
| NOAA-4 (ITOS-G) | 15 Nov 1974 | 18 Nov 1978 | 1450 km | 14.30 a | Inactive | 2 x VHRR, 2 x SR, 2 x VTPR, SPM |
| NOAA-5 (ITOS-H) | 29 Jul 1976 | 16 Jul 1979 | 1510 km | 14.30 a | Inactive | 2 x VHRR, 2 x SR, 2 x VTPR, SPM |
| TIROS-N | 13 Oct 1978 | 27 Feb 1981 | 850 km | 14.30 a | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos |
| NOAA-6 | 27 Jun 1979 | 31 Mar 1987 | 840 km | 07.30 d | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos |
| NOAA-7 | 23 Jun 1981 | 7 Jun 1986 | 860 km | 14.30 a | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos |
| NOAA-8 | 28 Mar 1983 | 29 Dec 1985 | 820 km | 07.30 d | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos, SARSAT |
| NOAA-9 | 12 Dec 1984 | 13 Feb 1998 | 850 km | 14.30 a | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos, SARSAT, ERBE, SBUV/2 |
| NOAA-10 | 17 Sep 1986 | 30 Aug 2001 | 810 km | 07.30 d | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos, SARSAT, ERBE, SBUV/2 |
| NOAA-11 | 24 Sep 1988 | 16 Jun 2004 | 843 km | 14.10 a | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos, SARSAT, SBUV/2 |
| NOAA-12 | 14 May 1991 | expected ≥ 2006 | 804 km | 05.10 d | Limited use | AVHRR, HIRS/2, MSU, SSU, SEM, Argos |
| NOAA-13 | 9 Aug 1993 | 21 Aug 1993 | 820 km | 14.00 a | Inactive | AVHRR, HIRS/2, MSU, SSU, SEM, Argos, SARSAT, SBUV/2 |
| NOAA-14 | 30 Dec 1994 | expected ≥ 2006 | 844 km | 09.30 d | Limited use | AVHRR/2, HIRS/2, MSU, SSU, SEM, Argos, SARSAT, SBUV/2 |
| NOAA-15 | 13 May 1998 | expected ≥ 2006 | 807 km | 05.30 d | Backup | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SEM/2, Argos, SARSAT |
| NOAA-16 | 21 Sep 2000 | expected ≥ 2006 | 849 km | 15.30 a | Backup | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |
| NOAA-17 | 24 Jun 2002 | expected ≥ 2009 | 810 km | 10.20 d | Operational | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |
| NOAA-18 | 20 May 2005 | expected ≥ 2010 | 854 km | 13.40 a | Operational | AVHRR/3, HIRS/3, AMSU-A, MHS, SBUV/2, SEM/2, Argos, SARSAT |
| NOAA-19 (NOAA-N') | 2009 | expected ≥ 2014 | 840 km | 14.00 a | Being built | AVHRR/3, HIRS/3, AMSU-A, MHS, SBUV/2, SEM/2, Argos, SARSAT |

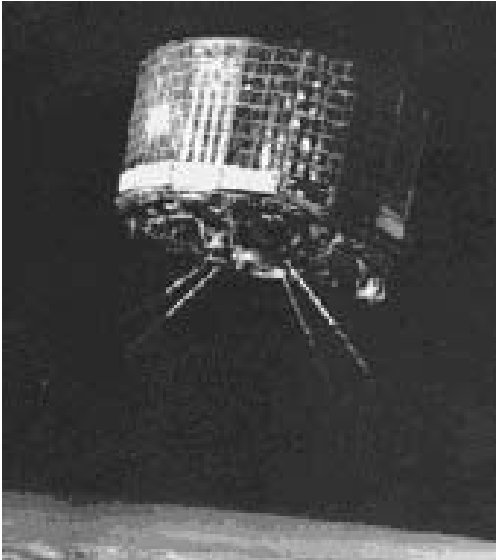


Fig. 3.2.1 – View of TIROS (spin-stabilised).

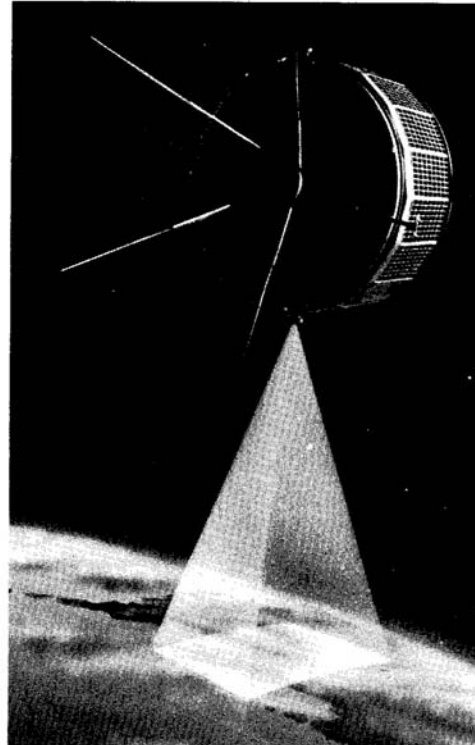


Fig. 3.2.1 – View of ESSA ("cartwheel" spin-stabilised).

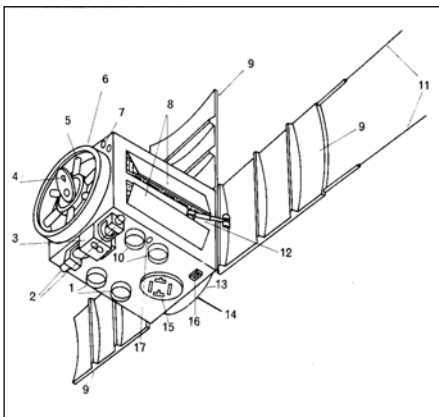


Fig. 3.2.3 – Sketch view of ITOS (first 3-axis stabilised of the POES series).

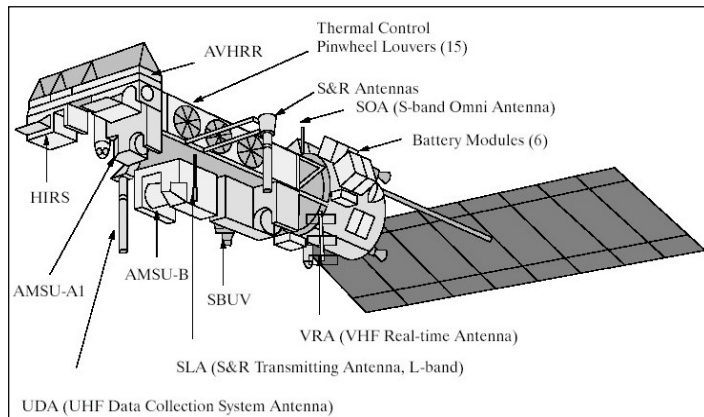


Fig. 3.2.4 – Sketch view of NOAA (K, L, M series).

NOAA-15

Launched in May 1998, it is the first satellite of the 5th generation, that replaces the sounding package TOVS (TIROS Operational Vertical Sounding = HIRS/2 + MSU + SSU), by **ATOVS (Advanced TOVS = HIRS/3 + AMSU-A + AMSU-B)**. Some instruments currently are defective, but still NOAA-15 could backup NOAA-17 in the morning orbit in case of problems.

NOAA-16

Launched in September 2000, it is the backup of NOAA-18 in the afternoon orbit. Several instruments are out of order, and the VHF transmitter for APT has failed.

NOAA-17

Launched in June 2002, it is the last NOAA satellite in the morning orbit.

NOAA-18

Launched in May 2005, it is the first of the two last satellites (NOAA-N and NOAA-N'), on which AMSU-B is replaced by the EUMETSAT-provided MHS.

Payload of the 5th generation NOAA satellites (NOAA-15 onwards)

- **AVHRR/3 (Advanced VHRR):** 6-channel VIS/IR radiometer for multi-purpose imagery with 1.1 km resolution and 2900 km swath. Only 5 channels transmitted (1.6 μm and 3.7 μm are alternative, day and night respectively). See instrument sheet in Annex A3.1.
- **HIRS/3 (High-resolution Infra Red Sounder - 3):** 20-channels IR radiometer (including one VIS) for temperature/humidity sounding, resolution 18 km and swath 2250 km. See instrument sheet in Annex A3.1.
- **AMSU-A (Microwave Sounding Unit - A):** 15-channel MW radiometer for nearly-all-weather temperature sounding, resolution 48 km, swath 2340 km. See instrument sheet in Annex A3.1.
- **AMSU-B (Microwave Sounding Unit - B):** 5-channel MW radiometer for nearly-all-weather humidity sounding, resolution 16 km, swath 2250 km. Replaced on NOAA-N and NOAA-N' by **MHS (Microwave Humidity Sounder)**. See instrument sheets in Annex A3.1.
- **SBUV/2 (Solar Backscatter Ultraviolet - 2):** 12-channel UV spectro-radiometer for ozone profiling, resolution 170 km, nadir-only viewing. See instrument sheet in Annex A3.1.
- **SEM/2 (Space Environment Monitor)**, an instrument suite for *in situ* measurement of the energy of charged particle of the solar wind at orbital height (not on NOAA-15).
- **DCS/2 (Data Collection System – 2)**, also know as **Argos**, to collect data from automatic stations and localise the platform. Platform transmission frequency: 401.65 MHz.
- **SARSAT (Search and Rescue Satellite Aided Tracking System)**, location system for emergency calls from transmitters at 121.5 or 243 or 406 MHz.

Data transmission from NOAA satellites

The totality of the information from NOAA instruments is transmitted in real time, and only part is stored on board for successive transmission to:

- **Command and Data Acquisition stations (CDA)** in charge of global data recovery. Main features:
 - frequencies: 1702.5 MHz (left-hand circular polarisation) and 1698 or 1707 MHz (right-hand circular polarisation); bandwidth MHz, data rate 2.66 Mbps;
 - GAC (Global Area Coverage) all data from low-bit-rate instruments at full resolution and AVHRR images with resolution reduced to 4 km, for the full orbit (102 min);
 - LAC (Local Area Coverage) for up to 11 min of selected AVHRR full resolution image frames.

There are three types of transmission with different contents for different ground receiving stations.

- **HRPT (High Resolution Picture Transmission)**, for the whole information at full resolution in digital form at S-band frequencies. Main features:
 - frequencies: 1698 or 1707 MHz; bandwidth: 2.66 MHz; polarisation: right hand circular (backup: 1702.5 MHz, polarisation left hand circular)
 - antenna diameter ~ 2 m, G/T ~ 6.0 dB/K, data rate 665.4 kbps;
- **APT (Automatic Picture Transmission)**, for two image channels at reduced resolution (4 km) with correction of the panoramic distortion, in analogue form at VHF frequencies. Main features:
 - frequencies: 137.5 or 137.62 MHz; bandwidth: 34 kHz; polarisation: right hand circular
 - omni-directional antenna, G/T ~ -30 dB/K, base band 2.1 kHz (analogue);
- **DSB (Direct Sounder Broadcast)**, for low-bit instruments (but not AMSU), in digital form at VHF frequencies. Main features:
 - frequencies: 137.35 or 137.77 MHz; bandwidth: kHz; polarisation: right hand circular
 - antenna:, G/T ~ dB/K, data rate 8.32 kbps.

3.3 The DMSP programme (limited to MW sensors supportive of GOS)

Strictly speaking, the **DMSP (Defense Meteorological Satellite Program)** is not part of the GOS, but data from the Special Sensors in Microwave (SSM) are distributed from NOAA either to make up for the lack of MW imagers on NOAA satellites, or as a backup to the MW temperature/humidity sounders.

DMSP is a 3-axis stabilised satellite using the same platform as current NOAA satellites (see again Fig. 3.2.4). The DoD (Department of Defense) uses to have two satellites in orbit at any time, with LST 5.30 and 7.30 respectively. **Table 3.3.1** records the chronology of the DMSP limited to the period since the introduction of the SSM instruments.

Table 3.3.1 – Chronology of the DMSP/SSM programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST | Status (Sept 2006) | MW instruments |
|-----------------|--------------------|------------------------|---------------|----------------|--------------------|-----------------------|
| DMSP-F04 | 6 Jun 1979 | 29 Aug 1980 | 850 km | ???? | Inactive | SSM/T |
| DMSP-F07 | 18 Dec 1983 | 17 Oct 1987 | 850 km | ???? | Inactive | SSM/T |
| DMSP-F08 | 18 Jun 1987 | 13 Aug 1991 | 850 km | 06.05 d | Inactive | SSM/I, SSM/T |
| DMSP-F09 | 3 Feb 1988 | 3 Aug 1994 | 850 km | ???? | Inactive | SSM/T |
| DMSP-F10 | 1 Dec 1990 | 14 Nov 1997 | 850 km | 10.20 d | Inactive | SSM/I, SSM/T |
| DMSP-F11 | 28 Nov 1991 | 16 May 2000 | 850 km | 07.30 d | Inactive | SSM/I, SSM/T, SSM/T-2 |
| DMSP-F12 | 29 Aug 1994 | 31 Jul 2002 | 850 km | 05.45 d | Inactive | SSM/T, SSM/T-2 |
| DMSP-F13 | 24 Mar 1995 | expected ≥ 2006 | 850 km | 06.30 d | Operational | SSM/I, SSM/T |
| DMSP-F14 | 4 Apr 1997 | expected ≥ 2006 | 852 km | 06.40 d | Backup | SSM/I, SSM/T, SSM/T-2 |
| DMSP-F15 | 12 Dec 1999 | expected ≥ 2006 | 850 km | 08.40 d | Backup | SSM/I, SSM/T, SSM/T-2 |
| DMSP-S16 | 18 Oct 2003 | expected ≥ 2008 | 833 km | 08.10 d | Operational | SSMIS |
| DMSP-S17 | 2006 | expected ≥ 2009 | 833 km | 05.30 d | Close to launch | SSMIS |
| DMSP-S18 | 2008 | expected ≥ 2012 | 833 km | 08.00 d | Being built | SSMIS |
| DMSP-S19 | 2010 | expected ≥ 2014 | 833 km | 05.30 d | Planned | SSMIS |
| DMSP-S20 | 2012 | expected ≥ 2016 | 833 km | 05.30 d | Planned | SSMIS |

NOAA acquires and distribute (on request) data from the following instruments:

- **SSM/I (Special Sensor Microwave / Imager)**, for precipitation rate, sea-surface wind speed and sea ice; 4-frequency / 7-channel radiometer (double polarisation for three frequencies); conical scanning with resolution between 13 km at 85 GHz and 55 km at 19 GHz; useful swath 1400 km. See instrument sheet in Annex A3.1.
- **SSM/T (Special Sensor Microwave / Temperature)**, for nearly-all-weather temperature sounding; 7-channel radiometer operating in the 54 GHz band, resolution 200 km, cross-track scanning, 1500 km swath. See instrument sheet in Annex A3.1.
- **SSM/T-2 (Special Sensor Microwave / Humidity)**, for nearly-all-weather humidity sounding; 5-channel radiometer operating in the 183 GHz band, resolution 48 km, cross-track scanning, 1500 km swath. See instrument sheet in Annex A3.1.

Starting with DMSP-S16, SSM/I, SSM/T and SSM/T-2 are progressively being replaced by:

- **SSMIS (Special Sensor Microwave / Imager/Sounder)**, a 21-frequency / 24 channel radiometer (double polarisation for three frequencies); conical scanning with resolution between 13 km in the range 50-190 GHz and 55 km at 19 GHz; nominal swath 1700 km, useful 1400 km. See instrument sheet in Annex A3.1.

3.4 The NPOESS programme

As shown in Tables 3.2.1 and 3.3.1, the NOAA programme foresees the last launch in 2009 and DMSP in 2012. This is because the civilian NOAA and the military DMSP are due to merge into **NPOESS (National Polar-orbiting Operational Environmental Satellite System)**. NPOESS (Fig. 3.4.1) is based on two satellites with LST 5.30 and 13.30 respectively, coordinated with the European EPS/MetOp in the 9:30 orbit (see Section 3.5 next). To reduce the risks associated to newly-developed instruments, an **NPP (NPOESS Preparatory Project)** will precede the series. **Table 3.4.1** records the currently envisaged chronology of NPOESS, also showing that satellites in

different orbits may carry different instruments. However, the NPOESS programme is currently being restructured, therefore the table reports what is currently foreseen as a minimum, and (in brackets) what is in standby from the original payload complement.

Table 3.4.1 – Chronology of the NPOESS program (instrument distribution not consolidated)

| Satellite | Launch | End of service | Height | LST | Status (Sept 2006) | Instruments |
|-----------|--------|----------------------|--------|---------|--------------------|---|
| NPP | 2009 | expected \geq 2014 | 833 km | 13.30 a | Being built | VIIRS, CrIS, ATMS, OMPS-nadir |
| NPOESS-1 | 2013 | expected \geq 2018 | 833 km | 13.30 a | Planned | VIIRS, CrIS, ATMS, OMPS-nadir, ERBS/CERES, SESS/SEM, A-DCS, SARSAT (OMPS-limb, APS in standby list) |
| NPOESS-2 | 2016 | expected \geq 2021 | 833 km | 5.30 d | Planned | VIIRS, CMIS, A-DCS, SARSAT (CrIS, ATMS, TSIS in standby list) |
| NPOESS-3 | 2020 | expected \geq 2025 | 833 km | 13.30 a | Planned | VIIRS, CrIS, ATMS, CMIS, OMPS-nadir, SESS/SEM, A-DCS, SARSAT (ERBS/CERES, OMPS-limb, APS in standby list) |
| NPOESS-4 | 2022 | expected \geq 2027 | 833 km | 5.30 d | Planned | VIIRS, CMIS, A-DCS, SARSAT (CrIS, ATMS, TSIS in standby list) |



Fig. 3.4.1 – View of NPOESS.

Main payload of NPOESS

Not all instruments of NPOESS have been fully consolidated and, in addition, some are being fully re-considered. The following information is based on what was known before the re-structuring exercise, and provides indication of the current trend.

- **VIIRS (Visible/Infrared Imager Radiometer Suite)**, the successor of AVHRR: 22-channel VIS/IR radiometer for multipurpose imagery; resolution 400 m for four AVHRR-like channels and one day-night VIS channel, and 800 m for the remaining 17 channels; swath 3000 km. Baselined for NPP and all NPOESS's. See instrument sheet in Annex A3.1.
- **CrIS (Cross-track Infrared Sounder)**, the successor of HIRS/4, actually a totally different instrument based on an IR interferometer to provide high-vertical-resolution temperature/humidity sounding; 1302 channels with spectral resolution 0.625 to 2.5 cm⁻¹, resolution 14 km, swath 2200 km. Baselined for NPP, and NPOESS 1 and 3. Not baselined, but still considered, for NPOESS 2 and 4. See instrument sheet in Annex A3.1.
- **ATMS (Advanced Technology Microwave Sounder)**, the successor of AMSU-A and AMSU-B for nearly-all-weather temperature and humidity sounding; 22-channel MW radiometer with bands at 54 and 183 GHz, resolution 16 km at 183 GHz and 32 km at 54 GHz, swath 2200 km. Baselined for NPP, and NPOESS 1 and 3. Not baselined, but still considered, for NPOESS 2 and 4. See instrument sheet in Annex A3.1.
- **CMIS (Conical-scanning Microwave Imager/Sounder)**, the successor of the DMSP SSMIS for multi-purpose MW imagery and supporting temperature/humidity sounding; 63 frequencies, 77 channels (3 with double polarisation, 2 with four polarisations and 1 with six polarisations); resolution from 3 km at 89 GHz to 40 km at 6.6 GHz, swath 1700 km nominal (conical scanning), 1400 km useful. This instrument is being re-considered in view of a large descope. Baselined for NPOESS 2, 3 and 4. See instrument sheet in Annex A3.1.
- **OMPS (Ozone Mapping and Profiler Suite)**, the successor of SBUV/2, that adds to the nadir-view (best for vertical profile of ozone) the cross-track scanning capability (swath 2800 km) for total ozone mapping and limb sounding for high-vertical-resolution in the stratosphere. Tracked species: BrO, HCHO, NO₂, O₃, OClO, SO₂. Resolution 250 km (profiler), 50 km (mapper), 1-km vertical (limb). See instrument sheet in Annex A3.1. The limb component of OMPS is no longer baselined, but still considered.
- **APS (Aerosol Polarimetry Sensor)**, for tropospheric aerosol observation: 9-channel VIS/NIR/SWIR polarimeter scanning along-track within ± 60° and measuring polarisations at 0, 45, 90 and 135° to get the four Stokes components. Resolution 10 km. This instrument is no longer baselined, but still considered for NPOESS 1 and 3. See instrument sheet in Annex A3.1.
- **ERBS (Earth Radiation Budget Sensor)**, successor of ERBE and of CERES (Clouds and the Earth's Radiant Energy System), being flown on TRMM and EOS Terra/Aqua; 3 channels (two broad-band, one narrow), resolution 20 km, swath 3000 km. This instrument is baselined for NPOESS-1, actually to be implemented by a recurring **CERES**; and is not baselined, but still considered, for NPOESS-3. See instrument sheet in Annex A3.1.
- **SESS (Space Environment Sensor Suite)**, successor of SEM/2 for *in situ* measurements of charged particles of the solar wind. The instrument is baselined for NPOESS 1 and 3, actually to be implemented by recurring models of **SEM**.
- **TSIS (Total Solar Irradiance Sensor)**, for total irradiance and its fraction in the 0.2-2.0 μm range. This instrument is no longer baselined, but still is considered for NPOESS 2 and 4.
- **A-DCS (ARGOS Data Collection System)**, successor of DCS/2, with the additional capability of sending messages to the Data Collection Platform for the purpose of changing its configuration.
- **SARSAT (Search and Rescue Satellite Aided Tracking System)**, successor of previous one except that only the 406 MHz will be retained.

Data transmission from NPP and NPOESS

The full information from all instruments is stored on board and transmitted in Ka-band to a number of ground stations, according to the standard:

- **SMD (Stored Mission Data)**, frequency 25.65 GHz, bandwidth 300 MHz, data rate 150 Mbps.

Direct read-out is provided according to two systems, both digital:

- **HRD (High Rate Data)**, for full information in X-band. Main features:
 - frequencies: 7812 or 7830 MHz; bandwidth: 30.8 MHz; polarisation: right hand circular
 - antenna diameter ~ 2 m, G/T ~ dB/K, data rate 20 Mbps;
- **LRD (Low Rate Data)** for selected information in S-band. Main features:
 - frequency: 1706 MHz; bandwidth: 8 MHz; polarisation: right hand circular-
 - antenna diameter ~ 1 m, G/T ~ dB/K, data rate 3.88 Mbps

NPP will only use the HRD standard. The data rate will be 15 Mbps.

3.5 The EPS/Metop Programme

The European **EPS (EUMETSAT Polar System)** draws its origins from the 1980's, when the USA decided to reduce their involvement in the morning orbit for focusing on the afternoon one. ESA started with studying a very large satellite, called POEM (Polar Orbit Earth-observation Mission), based on the 3-axis stabilised "Polar Platform", another ESA programme. Thereafter (1993) the POEM mission was split in two missions: Envisat, focusing on science and environment, and **MetOp**, designed for operational meteorology to implement the EPS programme. The EPS Programme was finally approved by the EUMETSAT Council in 1999. Three MetOp flight models (**Fig. 3.5.1**) have been approved. **Table 3.5.1** records the chronology of the EPS/MetOp programme.

Table 3.5.1 – Chronology of the first three satellites (MetOp) of the EPS programme

| Satellite | Launch | End of service | Height | LST | Status (Sept 2006) | Instruments |
|-----------|-------------|-----------------|--------|---------|--------------------|---|
| MetOp-1 | 19 Oct 2006 | expected ≥ 2010 | 834 km | 09.30 d | Just launched | AVHRR/3, HIRS/4, AMSU-A, MHS, IASI, GOME-2, GRAS, ASCAT, SEM/2, A-DCS, SARSAT |
| MetOp-2 | Oct 2010 | expected ≥ 2015 | 834 km | 09.30 d | In storage | AVHRR/3, HIRS/4, AMSU-A, MHS, IASI, GOME-2, GRAS, ASCAT, SEM/2, A-DCS, SARSAT |
| MetOp-3 | Apr 2015 | expected ≥ 2020 | 834 km | 09.30 d | Being built | AVHRR/3, AMSU-A, MHS, IASI, GOME-2, GRAS, ASCAT, A-DCS |

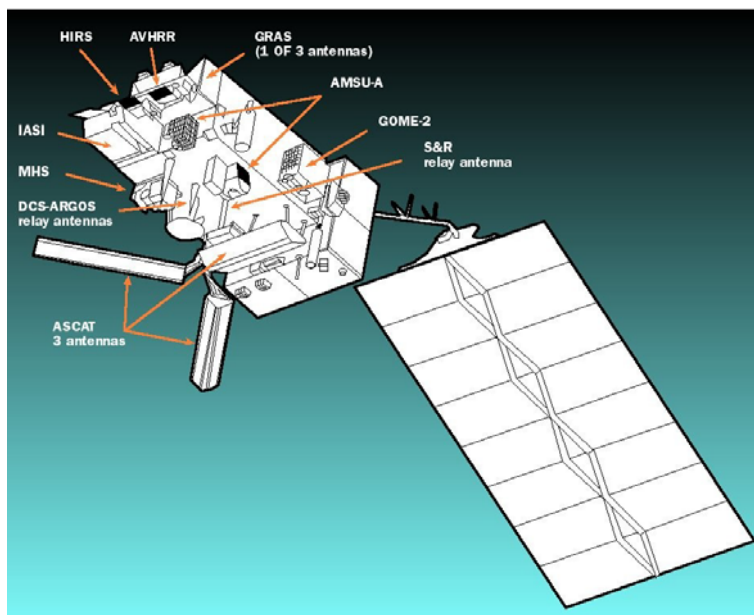


Fig. 3.5.1 – Sketch view of MetOp.

Payload of MetOp/EPS

- **AVHRR/3 (Advanced Very High Resolution Radiometer)**, provided by NOAA: 6-channel VIS/IR radiometer for multi-purpose imagery with 1.1 km resolution and 2930 km swath. Only 5 channels transmitted (1.6 μm and 3.7 μm are alternative, day and night respectively). See instrument sheet in Annex A3.1.
- **HIRS/4 (High-resolution Infrared Radiation Sounder)**, provided by NOAA: 20-channels IR radiometer (including one VIS) for temperature/humidity sounding, resolution 10 km and swath 2180 km. (NB: This instrument will not fly on MetOp-3). See instrument sheet in Annex A3.1.
- **AMSU-A (Advanced Microwave Sounding Unit - A)**, provided by NOAA: 15-channel MW radiometer for nearly-all-weather temperature sounding, resolution 48 km, swath 2070 km. See instrument sheet in Annex A3.1.
- **MHS (Microwave Humidity Sounder)**: 5-channel MW radiometer for nearly-all-weather humidity sounding, resolution 16 km, swath 2180 km. See instrument sheet in Annex A3.1.
- **IASI (Infrared Atmospheric Sounding Interferometer)**, cooperation with CNES: IR interferometer to provide high-vertical-resolution temperature/humidity sounding; 8461 channels with spectral resolution 0.25 cm^{-1} , resolution 12 km, swath 2130 km. See instrument sheet in Annex A3.1.
- **GOME-2 (Global Ozone Monitoring Experiment - 2)**, follow-on of the ERS-2 GOME: 4096-channel UV/VIS grating spectrometer (plus 200 polarisation channels) for ozone (total-column and profile) and other trace species (generally total-column). Tracked species: BrO, ClO, H₂O, HCHO, NO, NO₂, NO₃, O₂, O₃, O₄, OCIO, SO₂ and aerosol. Resolution 40 km for a 960 km swath or 80 km for a 1920 km swath. See instrument sheet in Annex A3.1.
- **GRAS (GNSS Receiver for Atmospheric Sounding)**, for all-weather high-vertical resolution temperature and humidity profile by observing the phase delay of GPS signals received during the occultation phase. 0.5-1 km vertical resolution, ~ 300 km horizontal resolution; 500 measurements/day. See instrument sheet in Annex A3.1.
- **ASCAT (Advanced SCATterometer)**, follow-on of the ERS 1/2 radar scatterometer for sea-surface wind. Frequency 5.255 GHz, resolution 25 km, two side swaths of 550 km either side of the sub-satellite track. See instrument sheet in Annex A3.1.
- **SEM/2 (Space Environment Monitor)**, provided by NOAA: an instrument suite for *in situ* measurement of the energy of charged particle of the solar wind at orbital height (NB: This instrument will not fly on MetOp-3).

- **A-DCS (Advanced Data Collection System)**, provided by NOAA and CNES, also known as **Argos**, to collect data from automatic stations and localise the platform. Platform transmission frequency: 401.65 MHz.
- **SARSAT (Search And Rescue Satellite-Aided Tracking System)**, provided by NOAA: location system for emergency calls from transmitters at 121.5 or 243 or 406.05 MHz. (NB: This instrument will not fly on MetOp-3).

Data transmission from EPS/Metop

The full information from all instruments is stored on board and transmitted in X-band as:

- **GDS (Global Data Stream)**: frequency 7800 MHz, bandwidth 63 MHz, data rate 70 Mbps.

Direct read-out is provided according to two systems, both digital:

- **AHRPT (Advanced High Resolution Picture Transmission)**, for the whole information at full resolution in digital form at S-band frequencies. Main features:
 - frequencies: 1701.3 MHz; bandwidth: 4.5 MHz; polarisation: right-hand circular (backup: 1707 MHz, polarisation right-hand circular);
 - antenna diameter ~ 2 m, G/T ~ 6.0 dB/K, data rate 3.5 Mbps;
- **LRPT (Low Resolution Picture Transmission)**, for selected information (3 AVHRR channel JPEG-compressed and ATOVS data) in digital form at VHF frequencies. Main features:
 - frequency: 137.1 MHz; bandwidth: 150 kHz; polarisation: right-hand circular (backup: 137.9125 MHz, polarisation right-hand circular)
 - Yagi antenna, G/T ~ -22.4 dB/K, data rate 72 kbps.

Post-EPS

User Requirements for the EPS satellite series to replace MetOp have been established in the course of year 2005, and the first draft Mission Requirements are being established during 2006. Requirements are considered for an 'Atmospheric sounding mission', a 'Cloud, precipitation and land surface imagery mission', an 'Ocean mission', an 'Atmospheric chemistry mission' and (transversal) for Climate. The need date for the post-EPS element to replace MetOp-3 in the 9:30 orbit is ~ 2015.

3.6 The Meteor programme

The Russian **Meteor** programme, if considered inclusive of the experiments carried out on the multi-purpose **Cosmos** series, has origins nearly as long-standing as those of the American TIROS-ESSA-ITOS-NOAA-POES. However, the first satellite dedicated to operational meteorology is dated 1969. There have been three series, Meteor-1, Meteor-2 and Meteor-3, in non-sunsynchronous orbits whereas the current one, Meteor-3M, is sunsynchronous. The programme run through the following phases.

- **Meteor-1**, 25 flight models launched, 3-axis stabilised. Instruments:
 - TV camera (0.4-0.8 μm), resolution 1.25-3 km, swath 1000 km
 - IR radiometer (8-12 μm), resolution 15 km, swath 1000 km
 - AC, radiometer for Earth radiation budget (0.3-30 μm), resolution 45 km, swath 2500 km.
- **Meteor-2**, 21 flight models launched, 3-axis stabilised. Instruments:
 - TV camera (0.4-0.8 μm), resolution 1.25-3 km, swath 1000 km
 - IR radiometer (8-12 μm), resolution 15 km, swath 1000 km
 - SM, IR temperature and humidity sounder (see next)
 - RMK-2, *in situ* charged particles counters (see next).
- **Meteor-3**, 7 flight models launched, 3-axis stabilised. Instruments:
 - MR-2000M and MR-900B, two cameras (0.5-0.8 μm), one with resolution 1 km and swath 3100 km, the other with resolution 1.5 km and swath 2600 km;
 - Klimat, an IR radiometer (10.5-12.5 μm) with resolution 3 km and swath 3100 km;
 - SM, a 10-channel IR radiometer in the range 9.65-18.70 μm for temperature and humidity sounding; resolution 42 km, swath 1000 km;

- RMK-2, a suite of charged particle counters to in situ observe solar wind;
- TOMS (Total Ozone Mapping Spectrometer) (only on Meteor-3-6), a NASA-provided six-band UV spectrometer (0.31-0.38 μm) with resolution 47 km and swath 3100 km;
- ScaRaB (Scanner for Radiation Budget) (only on Meteor-3-7) a CNES-provided radiometer with two broad-band (0.2-4.0 μm and 0.2-50 μm) and two narrow-band (0.5-0.7 μm and 10.5-12.5 μm) channels; resolution 60 km, swath 3200 km.

The current series, **Meteor-3M**, is based on a 3-axis stabilised platform in a sunsynchronous orbit (see **Fig. 3.6.1**). The first flight model, currently **inactive**, was launched in December 2001. With the second flight model the name has been changed to **Meteor-M**. Two flight models of Meteor-M are being developed. **Table 3.6.1** records the chronology of the Meteor programme.

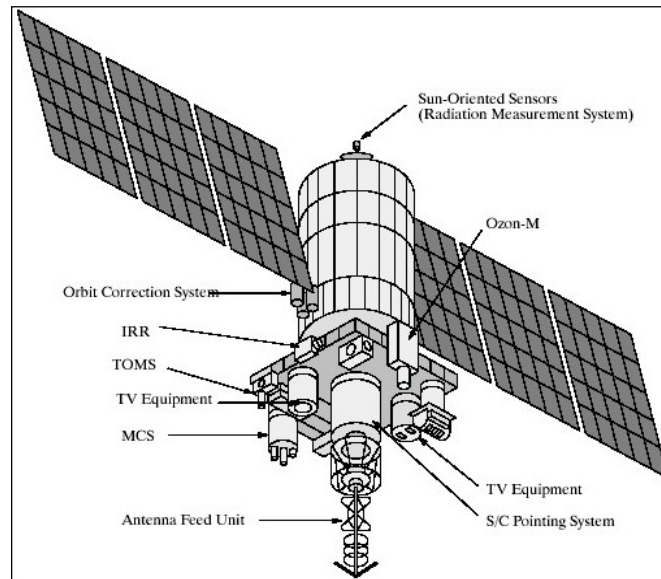


Fig. 3.6.1 – Sketch view of Meteor-3.

Table 3.6.1 – Chronology of the Meteor programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST or incl. | Status (Sept 2006) | Instruments |
|-------------|-------------|-----------------|---------|--------------|--------------------|---|
| Meteor-1-1 | 23 Mar 1969 | ~ 1970 | 680 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-2 | 6 Oct 1969 | ~ 1970 | 660 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-3 | 17 Mar 1970 | ~ 1971 | 650 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-4 | 28 Apr 1970 | ~ 1971 | 680 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-5 | 23 Jun 1970 | ~ 1971 | 880 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-6 | 15 Oct 1970 | ~ 1971 | 650 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-7 | 20 Jan 1971 | ~ 1972 | 650 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-8 | 17 Apr 1971 | ~ 1972 | 630 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-9 | 6 Jul 1971 | ~ 1972 | 630 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-10 | 29 Dec 1971 | ~ 1972 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-11 | 30 Mar 1972 | ~ 1973 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-12 | 30 Jun 1972 | ~ 1973 | 910 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-13 | 27 Oct 1972 | ~ 1973 | 900 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-14 | 20 Mar 1973 | ~ 1974 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-15 | 29 May 1973 | ~ 1974 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-16 | 5 Mar 1974 | ~ 1975 | 880 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-17 | 24 Apr 1974 | ~ 1975 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-19 | 28 Oct 1974 | ~ 1975 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-20 | 17 Dec 1974 | ~ 1975 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-21 | 1 Apr 1975 | ~ 1976 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-2-1 | 11 Jul 1975 | ~ 1976 | 890 km | 81.3° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-1-22 | 18 Sep 1975 | ~ 1976 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-23 | 25 Dec 1975 | ~ 1976 | 880 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-24 | 7 Apr 1976 | ~ 1977 | 880 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-1-26 | 5 Oct 1976 | ~ 1977 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-2-2 | 6 Jan 1977 | ~ 1978 | 910 km | 81.3° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-1-28 | 5 Apr 1977 | ~ 1978 | 890 km | 81.2° | Inactive | TV, IR, AC |
| Meteor-2-3 | 14 Dec 1977 | ~ 1979 | 890 km | 81.2° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-4 | 1 Mar 1979 | ~ 1980 | 880 km | 81.2° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-5 | 31 Oct 1979 | ~ 1980 | 890 km | 81.2° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-6 | 9 Sep 1980 | ~ 1981 | 890 km | 81.2° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-7 | 15 May 1981 | ~ 1982 | 890 km | 81.3° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-8 | 25 Mar 1982 | ~ 1983 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-9 | 15 Dec 1982 | ~ 1984 | 870 km | 81.3° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-10 | 28 Oct 1983 | ~ 1985 | 840 km | 81.2° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-11 | 5 Jul 1984 | ~ 1985 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-12 | 7 Feb 1985 | ~ 1986 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-3-1 | 24 Oct 1985 | ~ 1987 | 1250 km | 82.5° | Inactive | MR-2000M, MR-900B, Klimat, SM, RMK-2 |
| Meteor-2-13 | 6 Dec 1985 | ~ 1987 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-14 | 27 May 1986 | ~ 1987 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-15 | 5 Jan 1987 | ~ 1988 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-16 | 18 Aug 1987 | ~ 1988 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-17 | 30 Dec 1987 | ~ 1989 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-18 | 30 Jan 1988 | ~ 1989 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-3-3 | 26 Jul 1988 | ~ 1990 | 1210 km | 82.5° | Inactive | MR-2000M, MR-900B, Klimat, SM, RMK-2 |
| Meteor-2-19 | 28 Feb 1989 | ~ 1990 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-3-4 | 25 Oct 1989 | ~ 1992 | 1210 km | 82.5° | Inactive | MR-2000M, MR-900B, Klimat, SM, RMK-2 |
| Meteor-2-20 | 28 Jun 1990 | ~ 1992 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-2-21 | 28 Sep 1990 | ~ 2001 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-3-5 | 24 Apr 1991 | 2003 | 1210 km | 82.5° | Inactive | MR-2000M, MR-900B, Klimat, SM, RMK-2 |
| Meteor-3-6 | 15 Aug 1991 | ~ 1993 | 1210 km | 82.5° | Inactive | MR-2000M, MR-900B, Klimat, SM, RMK-2, TOMS |
| Meteor-2-22 | 31 Aug 1993 | 1994 | 960 km | 82.5° | Inactive | TV, IR, SM, RMK-2 |
| Meteor-3-7 | 25 Jan 1994 | 1995 | 1200 km | 82.5° | Inactive | MR-2000M, MR-900B, Klimat, SM, ScaRaB |
| Meteor-3M | 10 Dec 2001 | 2005 | 1020 km | 9.15 a | Inactive | MR-2000M1, Klimat, MIVZA, MTVZA, MSU-E, SAGE-III, SFM-2, KGI-4C, MSGI-5EI |
| Meteor-M-1 | 2007 | expected ≥ 2011 | 830 km | 10:20 a | Being built | MSU-MR, MTVZA, KMSS, Severjanin, GGAK-M |
| Meteor-M-2 | 2008 | expected ≥ 2012 | 830 km | 10:20 a | Planned | MSU-MR, IRFS-2, MTVZA, KMSS, Radiomet, Severjanin, GGAK-M, DCS |

Payload of Meteor-3M, operated until 2005.

- **MR-2000M1**, TV camera (0.5-0.8 μm), resolution 1 km, swath 3100 km. See instrument sheet in Annex A3.1.
- **Klimat**, IR radiometer (10.5-12.5 μm), resolution 3.0 km, swath 3100 km. See instrument sheet in Annex A3.1.
- **MIVZA**, 3-frequencies / 5 channels (double polarisation at two frequencies) MW conical-scanning radiometer, resolution 25 km at 94 GHz, 100 km at 20 GHz, swath 1500 km. There is no evidence that the instrument has been actually flown.
- **MTVZA**, a 20-frequency / 26-channel radiometer (double polarisation for six frequencies), for multi-purpose MW imagery and nearly-all-weather temperature/humidity sounding; conical scanning with resolution between 14 km at 183.31 GHz and 90 km at 18.7 GHz, swath 1500 km. See instrument sheet in Annex A3.1.
- **MSU-E**, 3-channels VIS/NIR radiometer (0.5-0.6, 0.6-0.7, 0.8-0.9 μm) for high-resolution (38 m) limited swath imagery (46 km with possible pointing within 430 km). See instrument sheet in Annex A3.1.
- **SAGE-III (Stratospheric Aerosol and Gas Experiment - III)**, a NASA-provided grating spectrometer in 9 bands of the 290-1550 nm range in solar or lunar occultation. Species: H₂O, NO₂, NO₃, O₃, OClO and aerosol. Resolution ~ 300 km (horizontal), 1-2 km (vertical) in the range 10-85 km. See instrument sheet in Annex A3.1.
- **SFM-2**, a UV spectrometer for ozone during solar occultation. Spectral range 0.2-0.51 μm , resolution ~ 300 km (horizontal), 1-2 km (vertical) in the range 10-60 km. There is no evidence that the instrument has been actually flown.
- **KGI-4C** and **MSGI-5EI**, suite of charged particles counters for *in situ* observation of solar wind.

Payload of Meteor-M, next operational series to come.

- **MSU-MR**, replacing MR-2000M1 + Klimat for multi-purpose imagery: 6-channel VIS/IR radiometer, resolution 1.0 km, swath 2800 km. See instrument sheet in Annex A3.1.
- **MTVZA**, a 21-frequency / 29-channel radiometer (double polarisation for eight frequencies), with 3 more channels than on Meteor-3M, for multi-purpose MW imagery and nearly-all-weather temperature/humidity sounding; conical scanning with resolution between 14 km at 183.31 GHz and 130 km at 10.6 GHz, swath 1500 km. See instrument sheet in Annex A3.1.
- **IRFS-2**, IR interferometer for high-vertical-resolution temperature/humidity sounding, about 4000 channels with spectral resolution 0.5 cm^{-1} , resolution 35 km, swath 1000 km to 2500 km. IRFS-2 is planned for Meteor-M-2. See instrument sheet in Annex A3.1.
- **KMSS**, replacing MSU-E for multi-purpose imagery: 4-channel imaging system, resolution 50 or 100 m, swath 400 or 900 km. See instrument sheet in Annex A3.1.
- **Radiomet**, for all-weather very-high-vertical resolution temperature and humidity profile by observing the phase delay of GPS signals received during the occultation phase. 0.5-1 km vertical resolution, ~ 300 km horizontal resolution; 500 measurements/day. Radiomet is planned for Meteor-M-2. See instrument sheet in Annex A3.1.
- **Severjanin**, a Synthetic Aperture Radar (SAR): X-band (9.623GHz), resolution either 400 or 1000 m, swath up to 600 km. See instrument sheet in Annex A3.1.
- **GGAK-M**, replacing KGI-4C + MSGI-5EI for *in situ* observation of charged particles in solar wind.
- **DCS (Data Collection System)**, to collect and relay data from automatic stations (on Meteor-M-2); uplink: frequency 402.1-402.5 MHz, data rate 400 or 1200 bps.

Data transmission from Meteor-M

Global data are stored on board and transmitted in X-band to:

- **Data Acquisition station (DA):** 2 frequencies: 8128 & 8320 MHz, bandwidth 32-250 MHz, data rate: 15.36, 30.72, 61.44 or 122.88 Mbps.

Meteor-M direct-read-out will comply with standards similar to NOAA:

- **HRPT (Advanced High Resolution Picture Transmission)**, for the whole information at full resolution in digital form at S-band frequencies. Main features-
 - frequency: 1700 MHz; bandwidth: 2.0 MHz; polarisation: right-hand circular
 - antenna diameter ~ 2 m, G/T ~ 6.0 dB/K, data rate 665 kbps.
- **LRPT (Low Resolution Picture Transmission)**, for selected information. Main features:
 - frequencies: 137.89 or 137.1 MHz; bandwidth: 150 kHz; polarisation: right-hand circular
 - Yagi antenna, G/T ~ -22.4 dB/K, data rate 72 kbps.

In addition, Meteor-M-2 will provide relay of data from DCP's and other sources through:

- **Onboard radio-complex** in the frequency band 1690-1710 MHz, bandwidth 2 MHz, polarisation right-hand circular, data rate 400 or 1200 bps.

3.7 The FY-1 and FY-3 programmes

The Chinese **FY-1** and **FY-3** series⁴ started in 1988. The first two satellites (FY-1A and FY-1B) were using the ITOS platform (see section 3.2 and Fig. 3.2.3), the next two (FY-1C and FY-1D) a new platform (**Fig. 3.7.1**). The FY-3 series is being developed and include 7 flight models. All satellites are 3-axis stabilised, in sunsynchronous orbit. **Table 3.7.1** records the chronology of the FY-1 / FY-3 programme.

Table 3.7.1 – Chronology of the FY-1/FY-3 programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST | Status (Sept 2006) | Instruments |
|--------------|--------------------|------------------------|---------------|---------------|--------------------|--|
| FY-1A | 7 Sep 1988 | 16 Oct 1988 | 900 km | 11.30 d | Inactive | MVISR, SEM |
| FY-1B | 3 Sep 1990 | 5 Aug 1991 | 900 km | 16.00 a | Inactive | MVISR, SEM |
| FY-1C | 10 May 1999 | 26 April 2004 | 862 km | 6.45 d | Inactive | MVISR, SEM |
| FY-1D | 15 May 2002 | expected ≥ 2006 | 866 km | 8.20 d | Operational | MVISR, SEM |
| FY-3A | 2007 | expected ≥ 2010 | 836 km | 10.00 d | Being built | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| FY-3B | 2009 | expected ≥ 2013 | 836 km | 14.00 a | Planned | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| FY-3C | 2012 | expected ≥ 2015 | 836 km | 10.00 d | Planned | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| FY-3D | 2014 | expected ≥ 2017 | 836 km | 14.00 a | Planned | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| FY-3E | 2016 | expected ≥ 2019 | 836 km | 10.00 d | Planned | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| FY-3F | 2018 | expected ≥ 2021 | 836 km | 14.00 a | Planned | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| FY-3G | 2020 | expected ≥ 2023 | 836 km | 10.00 d | Planned | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |

⁴ FY = *Feng-Yun*, “Wind and Cloud”.

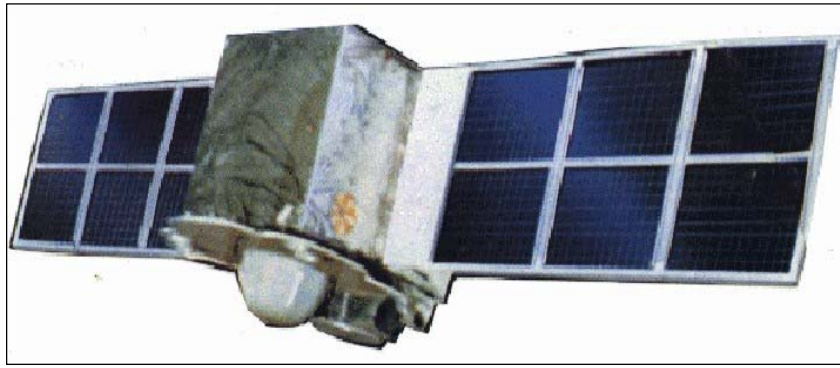
Payload of FY-1

Fig. 3.7.1 – View of FY-1.

From April 2004, the only operational satellite is **FY-1D**, launched in 2002. It embarks the following instruments:

- **MVISR (Multichannel Visible and Infrared Scanning Radiometer)**, VIS/IR radiometer for multi-purpose imagery, resolution 1.1 km, swath 2800 km. On FY-1A and FY-1B MVISR had 5 channels (0.48-0.53, 0.53-0.58, 0.58-0.68, 0.725-1.10 e 10.5-12.5 μm). On FY-1C and FY-1D there are 10 channels. See instrument sheet in Annex A3.1.
- **SEM (Space Environment Monitoring)** for *in situ* observation of charged particles in solar wind.

Data transmission from FY-1

Global data are stored on board and transmitted in S-band as:

- **China Delayed Picture Transmission (CDPT)**: MVISR imagery with resolution reduced to 4 km; frequency 1708.5 MHz (backup 1695.5 MHz, bandwidth 5.6 MHz, data rate 1.33 Mbps.

As for direct read-out, there is:

- **CHRPT (China High Resolution Picture Transmission)**, for the whole information at full resolution in digital form at S-band frequencies. Main features:
 - frequencies: 1700.5 MHz (backup 1704.5 MHz); bandwidth: 5 MHz; polarisation: right-hand circular;
 - antenna diameter ~ 2 m, G/T ~ 6.0 dB/K, data rate 1.33 kbps.

Payload of FY-3

- **VIRR (Visible and Infra Red Radiometer)**, close to MVISR except that the water vapour channel at 932 nm is replaced by 1360 nm; 10-channel VIS/IR radiometer for multi-purpose imagery, resolution 1.1 km, swath 2800 km. See instrument sheet in Annex A3.1.
- **MERSI (Medium Resolution Spectral Imager)**, 20-channel radiometer (19 in VIS/NIR/SWIR + one TIR at 10.0-12.5 μm) for ocean colour and vegetation indexes; resolution 250 m for 4 VIS/NIR and the TIR channel, 1 km for all other channels; swath 2800 km. See instrument sheet in Annex A3.1.
- **MWRI (Micro-Wave Radiation Imager)**, 6-frequencies / 12 channels (all frequencies in double polarisation) for multi-purpose MW imagery. Conical-scanning radiometer, resolution 9.5 x 15 km at 90 GHz, 30 x 50 km at 19 GHz, swath 1400 km. See instrument sheet in Annex A3.1.
- **IRAS (Infra Red Atmospheric Sounder)**, 26-channel IR radiometer (including one VIS) for temperature/humidity sounding, resolution 17 km, swath 2250 km. See instrument sheet in Annex A3.1.
- **MWTS (Micro-Wave Temperature Sounder)**, 4-channel MW radiometer for nearly-all-weather temperature sounding, 54 GHz band, resolution 70 km, cross-track scanning, swath 2200 km. See instrument sheet in Annex A3.1.

- **MWHS (Micro-Wave Humidity Sounder)**, 4-frequency / 5-channel (one frequency in double polarisation) MW radiometer for nearly-all-weather humidity sounding, 183 GHz band, resolution 15 km, cross-track scanning, swath 2700 km. See instrument sheet in Annex A3.1.
- **TOU/SBUS (Total Ozone Unit and Solar Backscatter Ultraviolet Sounder)**, a suite of two UV spectro-radiometers, one (TOU) with 6 channels in the 308-360 nm range, resolution 50 km, swath 3000 km, for total ozone; the other one (SBUS) with 12 channels in the range 252-340 nm, resolution 200 km, nadir viewing, for ozone profile. See instrument sheet in Annex A3.1.
- **SEM (Space Environment Monitoring)** for *in situ* observation of charged particles in solar wind.

Data transmission from FY-3

The data rate of the MERSI instrument requires moving to X-band, both for global data recovery and for full information real-time transmission. Global data stored on board are transmitted as:

- **Delayed Picture Transmission (DPT)**: frequency: 8146 MHz; bandwidth: 149 MHz; data rate: 93 Mbps.

Direct read-out is provided according to two systems:

- **MPT (Medium-resolution Picture Transmission)**, for full information in X-band. Main features:
 - frequency: 7775 MHz; bandwidth: 45 MHz; polarisation: right hand circular
 - antenna diameter ~ 3 m, G/T ~ 21.4 dB/K, data rate 18.7 Mbps;
- **AHRPT (Advanced High Resolution Picture Transmission)** for selected information in S-band. Main features:
 - frequency: 1704.5 MHz; bandwidth: 6.8 MHz; polarisation: right hand circular
 - antenna diameter ~ 3 m, G/T ~ 6.8 dB/K, data rate 4.2 Mbps.

3.8 Coverage provided by sunsynchronous satellites in 2006 and 2008

In this Section the compliance of the constellation of sunsynchronous meteorological satellites with WMO requirements is evaluated. Since the requirement calls for four satellites at optimally-spaced LST, **Table 3.8.1** identifies eight time sectors each wide 3 hours. In addition, since three major satellites are expected to be launched in 2006 and 2007 (Metop-1, Meteor-M-1 and FY-3A), the perspective situation in year 2008 is shown in **Table 3.8.2**.

Table 3.8.1 - Coverage from sunsynchronous satellites as of September 2006 (CGMS XXXIV)

| Time | Satellite | LST | Instruments |
|-------|-----------|---------|---|
| 00-03 | NOAA-18 | 01.40 d | AVHRR/3, HIRS/3, AMSU-A, M, SBUV/2, SEM/2, Argos, SARSAT |
| 03-06 | NOAA-16 | 03.30 d | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |
| | NOAA-15 | 05.30 d | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SEM/2, Argos, SARSAT |
| 06-09 | DMSP F13 | 06.30 d | SSM/I, SSM/T + others not available |
| | DMSP F14 | 06.40 d | SSM/I, SSM/T, SSM/T-2 + others not available |
| | DMSP S16 | 08.10 d | SSMIS |
| | FY-1D | 08.20 d | MVISR, SEM |
| | DMSP F15 | 08.40 d | SSM/I, SSM/T, SSM/T-2 + others not available |
| 09-12 | NOAA-17 | 10.20 d | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |
| 12-15 | NOAA-18 | 13.40 a | AVHRR/3, HIRS/3, AMSU-A, MHS, SBUV/2, SEM/2, Argos, SARSAT |
| 15-18 | NOAA-16 | 15.30 a | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |
| | NOAA-15 | 17.30 a | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SEM/2, Argos, SARSAT |
| 18-21 | DMSP F13 | 18.30 a | SSM/I, SSM/T + others not available |
| | DMSP F14 | 18.40 a | SSM/I, SSM/T, SSM/T-2 + others not available |
| | DMSP S16 | 20.10 a | SSMIS |
| | FY-1D | 20.20 a | MVISR, SEM |
| 21-24 | DMSP F15 | 20.40 a | SSM/I, SSM/T, SSM/T-2 + others not available |
| | NOAA-17 | 22.20 a | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |

Table 3.8.2 - Coverage from sunsynchronous satellites as expected in 2008

| Time | Satellite | LST | Instruments |
|-------|------------|---------|---|
| 00-03 | NOAA-18 | 01.40 d | AVHRR/3, HIRS/3, AMSU-A, MHS, SBUV/2, SEM/2, Argos, SARSAT |
| 03-06 | DMSP S17 | 05.30 d | SSMIS |
| 06-09 | DMSP S16 | 08.10 d | SSMIS |
| | FY-1D | 08.20 d | MVISR, SEM |
| 09-12 | Metop-1 | 09.30 d | AVHRR/3, HIRS/4, AMSU-A, MHS, IASI, GOME-2, GRAS, ASCAT, SEM/2, Argos, SARSAT |
| | FY-3A | 10.00 d | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| | Meteor-M-1 | 10.20 a | MSU-MR, MTVZA, KMSS, Severjanin, GGAK-M |
| | NOAA-17 | 10.20 d | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |
| 12-15 | NOAA-18 | 13.40 a | AVHRR/3, HIRS/3, AMSU-A, MHS, SBUV/2, SEM/2, Argos, SARSAT |
| 15-18 | DMSP S17 | 17.30 a | SSMIS |
| 18-21 | DMSP S16 | 20.10 a | SSMIS |
| | FY-1D | 20.20 a | MVISR, SEM |
| 21-24 | Metop-1 | 21.30 a | AVHRR/3, HIRS/4, AMSU-A, MHS, IASI, GOME-2, GRAS, ASCAT, SEM/2, Argos, SARSAT |
| | FY-3A | 22.00 a | VIRR, MERSI, MWRI, IRAS, MWTS, MWHS, TOU/SBUS, SEM |
| | Meteor-M-1 | 22.20 d | MSU-MR, MTVZA, KMSS, Severjanin, GGAK-M |
| | NOAA-17 | 22.20 a | AVHRR/3, HIRS/3, AMSU-A, AMSU-B, SBUV/2, SEM/2, Argos, SARSAT |

Table 3.8.3, Table 3.8.4 and **Table 3.8.5** highlight the situation of orbital parameters in respect of the VIS/IR imagery mission, the IR/MW sounding mission and for MW conical scanners, respectively. The role of these Tables is to identify the time of the day when gaps occur because of the orbital configuration of the constellation. The **gaps**, instead, arise from the combined effect of the orbital configuration and the instrument swaths (assumed ~ 2900 km for VIS/IR imagery, ~ 2200 km for IR/MW sounding and ~ 1400 km for MW conical scanners).

Table 3.8.3 – Coverage of the VIS/IR imagery mission (cells with Δ LST > 3 h are highlighted)

| 2006 | NOAA-18 | NOAA-16 | NOAA-15 | FY-1D | NOAA-17 | NOAA-18 | NOAA-16 | NOAA-15 | FY-1D | NOAA-17 | NOAA-18 |
|--------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| LST | 01.40 d | 03.30 d | 05.30 d | 08.20 d | 10.20 d | 13.40 a | 15.30 a | 17.30 a | 20.20 a | 22.20 a | 01.40 d |
| Δ LST | 1 h 50' | 2 h 00' | 2 h 50' | 2 h 00' | 3 h 20' | 1 h 50' | 2 h 00' | 2 h 50' | 2 h 00' | 3 h 20' | |

| 2008 | NOAA-18 | FY-1D | Metop-1 | FY-3A | Meteor-M-1 | NOAA-17 | NOAA-18 | FY-1D | Metop-1 | FY-3A | Meteor-M-1 | NOAA-17 | NOAA-18 |
|--------------|---------|---------|---------|---------|------------|---------|---------|---------|---------|---------|------------|---------|---------|
| LST | 01.40 d | 08.20 d | 09.30 d | 10.00 d | 10.20 a | 10.20 d | 13.40 a | 20.20 a | 21.30 a | 22.00 a | 22.20 d | 22.20 a | 01.40 d |
| Δ LST | 6 h 40' | 1 h 10' | 0 h 30' | 0 h 20' | 0 h 00' | 3 h 20' | 6 h 40' | 1 h 10' | 0 h 30' | 0 h 20' | 0 h 00' | 3 h 20' | |

Analysis of Table 3.8.3

- **2006** - close to optimal; the 3-h gap is exceeded, marginally (3 h 20'), only in two cases, around noon and midnight;
- **2008** - severe lack of satellite availability (6 h 40') in early morning and late-afternoon; marginal gaps (3 h 20') around noon and midnight; great overlap in mid-morning and early night.

Table 3.8.4 – Coverage of the IR/MW sounding mission (cells with Δ LST > 3 h are highlighted)

| 2006 | NOAA-18 | NOAA-16 | NOAA-15 | NOAA-17 | NOAA-18 | NOAA-16 | NOAA-15 | NOAA-17 | NOAA-18 |
|--------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| LST | 01.40 d | 03.30 d | 05.30 d | 10.20 d | 13.40 a | 15.30 a | 17.30 a | 22.20 a | 01.40 d |
| Δ LST | 1 h 50' | 2 h 00' | 4 h 50' | 3 h 20' | 1 h 50' | 2 h 00' | 4 h 50' | 3 h 20' | |

| 2008 | NOAA-18 | Metop-1 | FY-3A | NOAA-17 | NOAA-18 | Metop-1 | FY-3A | NOAA-17 | NOAA-18 |
|--------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|
| LST | 01.40 d | 09.30 d | 10.00 d | 10.20 d | 13.40 a | 21.30 a | 22.00 a | 22.20 a | 01.40 d |
| Δ LST | 7 h 50' | 0 h 30' | 0 h 20' | 3 h 20' | 7 h 50' | 0 h 30' | 0 h 20' | 3 h 20' | |

Analysis of Table 3.8.4

- **2006** - the 3-hourly requirement is largely missed (4 h 50') in the mid-morning and in the evening and marginally missed (3 h 20') around noon and midnight.
- **2008** - severe lack of satellite availability (7 h 50') in early morning and late-afternoon; marginal gaps (3 h 20') around noon and midnight; great overlap in mid-morning and early night

Table 3.8.5 – Coverage of MW conical scanners (cells with $\Delta LST > 3$ h are highlighted)

| | | | | | | | | | |
|--------------------------------|----------|----------|----------|------------|----------|----------|----------|------------|----------|
| 2006 | DMSP F13 | DMSP F14 | DMSP S16 | DMSP F15 | DMSP F13 | DMSP F14 | DMSP S16 | DMSP F15 | DMSP F13 |
| LST | 06.30 d | 06.40 d | 08.10 d | 08.40 d | 18.30 a | 18.40 a | 20.10 a | 20.40 a | 06.30 d |
| ΔLST | 0 h 10' | 1 h 30' | 0 h 30' | 9 h 50' | 0 h 10' | 1 h 30' | 0 h 30' | 9 h 50' | |
| 2008 | DMSP S17 | DMSP S16 | FY-3A | Meteor-M-1 | DMSP S17 | DMSP S16 | FY-3A | Meteor-M-1 | DMSP S17 |
| LST | 05.30 d | 08.10 d | 10.00 d | 10.20 a | 17.30 a | 20.10 a | 22.00 a | 22.20 d | 05.30 d |
| ΔLST | 2 h 40' | 1 h 50' | 0 h 20' | 7 h 10' | 2 h 40' | 1 h 50' | 0 h 20' | 7 h 10' | |

Analysis of Table 3.8.5

- **2006** - severe lack of satellite availability (9 h 50') cross most of the day except around 8 and 20 h.
- **2008** - severe lack of satellite availability (7 h 10') cross most of the day except around 9 and 21 h.

The coverage from the various satellites, accounting for the swath typical of the various instruments, is shown in **Fig. 3.8.1**, **Fig. 3.8.2** and **Fig. 3.8.3** for the VIS/IR imagery mission, the IR/MW sounding mission and MW conical scanners respectively. The figures on the left hand refer to the situation in September 2006, those on the right hand to the situation expected in 2008. The colours highlight the quality of the instrument (see Section 3.9 next). The figures are built assuming that all satellites cross the equatorial node in ascending phase exactly at 12 UTC. In real situations, the actual positions of the orbital ground track will float around those shown in the figures by $\pm 12.6^\circ$, therefore the position of the gaps will have (limited) variations of geographical location and time of the day.

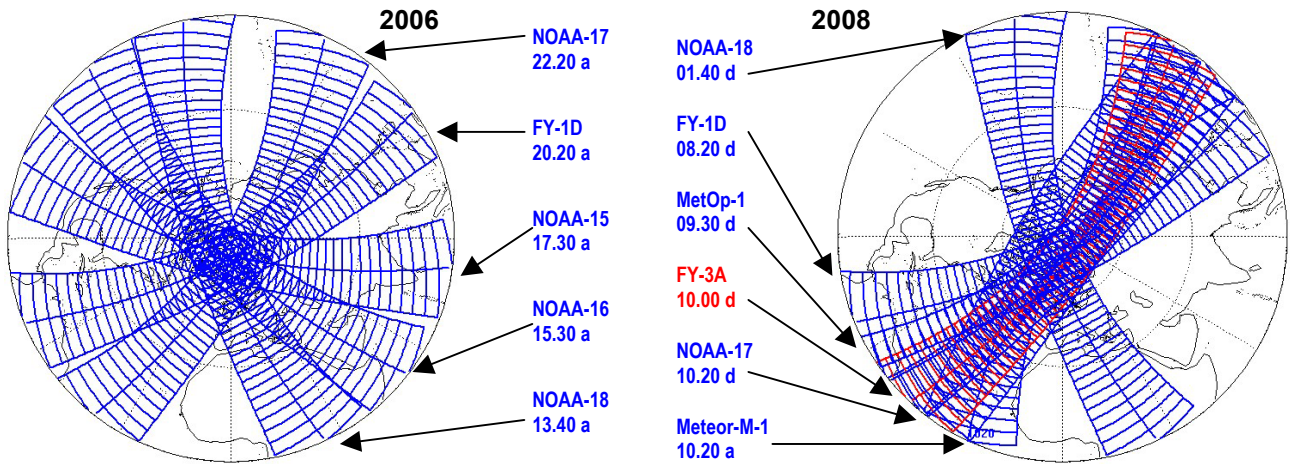


Fig. 3.8.1 – One-orbit coverage from VIS/IR imagers. Swath: 2900 km. All satellites assumed to cross the equator at 12 UTC in the ascending phase. Left: September 2006. Right: 2008. Colour code: 'blue' for NOAA and MetOp AVHRR, FY-1D MVISR and Meteor-M MSU-MR; 'red' for FY-3A MERIS+VIRR.

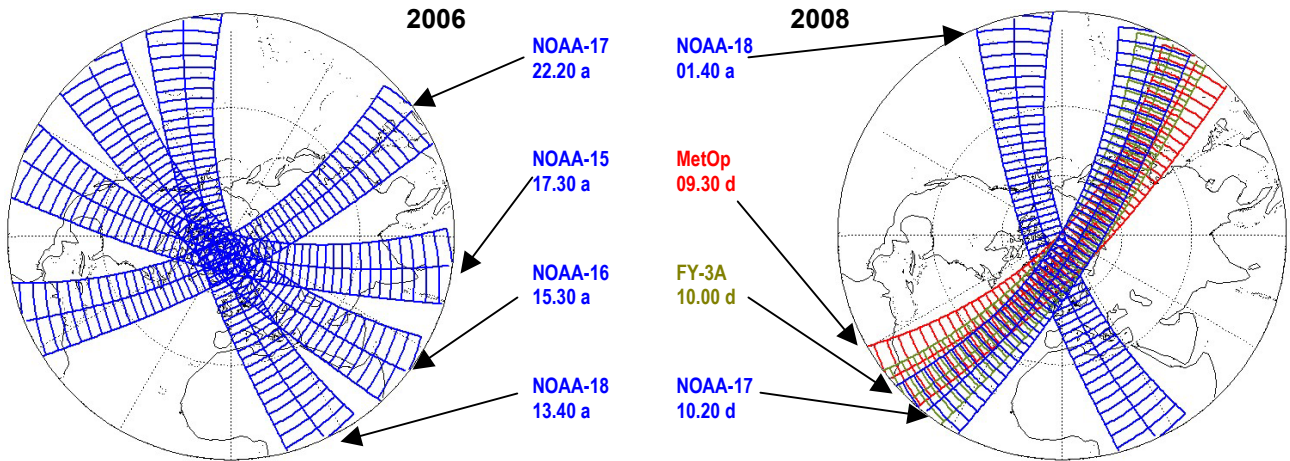


Fig. 3.8.2 – One-orbit coverage from IR/MW sounders. Swath: 2200 km. All satellites assumed to cross the equator at 12 UTC in the ascending phase. Left: September 2006. Right: 2008. Colour code: 'green' for FY-3A IRAS+MWTS+MWHS; 'blue' for NOAA ATOVS; 'red' for MetOp ATOVS+IASI.

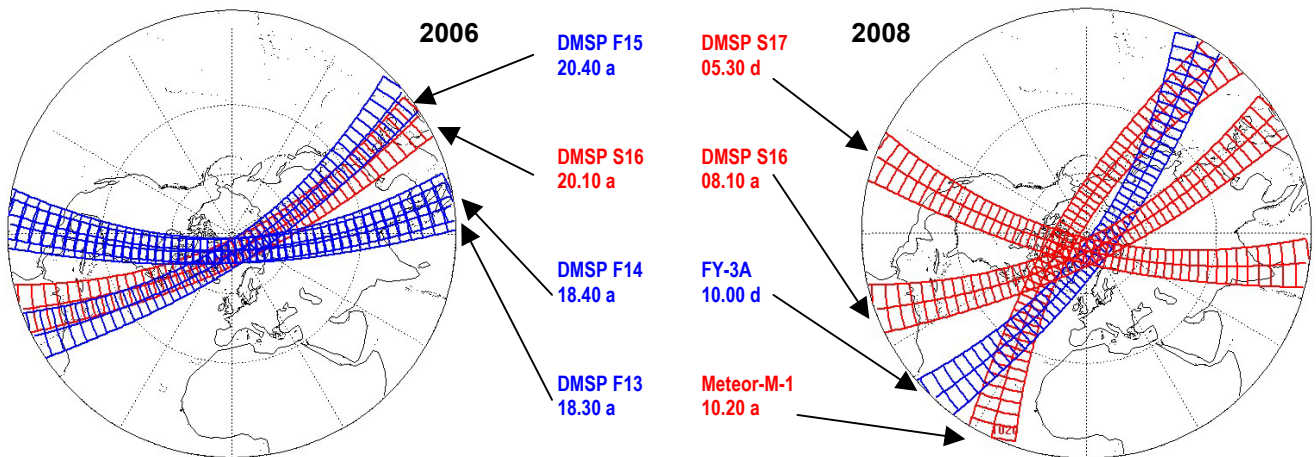


Fig. 3.8.3 – One-orbit coverage from MW conical scanners. Swath: 1400 km. All satellites assumed to cross the equator at 12 UTC in the ascending phase. Left: September 2006. Right: 2008. Colour code: 'blue' for DMSP SSM/I and FY-3A MWRI; 'red' for imaging-sounders DMSP SSMIS and Meteor-M MTVZA.

3.9 Comparative instrument performances

In addition to the coverage, the system also must provide homogeneous performances in terms of data quality, that depends on the instruments. **Table 3.9.1** compares the main features of imagers being operational or at least solidly defined in September 2006.

Table 3.9.1 – Comparative performances of imagers on-board sun-synchronous satellites

| NOAA & Metop AVHRR/3 | | NPP VIIRS | | Meteor-M-1 MSU- MR | | FY-1D MVISR | | FY-3A VIRR | | FY-3A MERSI | |
|-------------------------|--------------------|--|--------------------|-----------------------|--------------------|---------------------|--------------------|---------------------|--------------------|------------------------|--------------------|
| λ | $\Delta\lambda$ | λ | $\Delta\lambda$ | λ | $\Delta\lambda$ | λ | $\Delta\lambda$ | λ | $\Delta\lambda$ | λ | $\Delta\lambda$ |
| | | 412 nm | 20 nm | | | | | | | 412 nm | 20 nm |
| | | 445 nm | 18 nm | | | 455 nm | 50 nm | 455 nm | 50 nm | 443 nm | 20 nm |
| | | | | | | | | | | 470 nm * | 50 nm |
| | | 488 nm | 20 nm | | | 505 nm | 50 nm | 505 nm | 50 nm | 490 nm | 20 nm |
| | | | | | | | | | | 520 nm | 20 nm |
| | | 555 nm | 20 nm | | | 555 nm | 50 nm | 555 nm | 50 nm | 550 nm * | 50 nm |
| | | | | | | | | | | 565 nm | 20 nm |
| | | | | | | | | | | 650 nm | 20 nm |
| 630 nm | 100 nm | 640 nm * | 80 nm | 600 nm | 200 nm | 630 nm | 100 nm | 630 nm | 100 nm | 650 nm * | 50 nm |
| | | 672 nm | 20 nm | | | | | | | 685 nm | 20 nm |
| | | 700 nm * | 400 nm | | | | | | | | |
| | | 746 nm | 15 nm | | | | | | | 765 nm | 20 nm |
| | | 865 nm | 39 nm | | | | | | | 865 nm | 20 nm |
| 862 nm | 275 nm | 865 nm * | 39 nm | | | 865 nm | 50 nm | 865 nm | 50 nm | 865 nm * | 50 nm |
| | | | | | | | | | | 905 nm | 20 nm |
| | | | | 950 nm | 300 nm | 932 nm | 65 nm | | | 940 nm | 20 nm |
| | | | | | | | | | | 980 nm | 20 nm |
| | | 1240 nm | 20 nm | | | | | | | 1030 nm | 20 nm |
| | | 1378 nm | 15 nm | | | | | 1360 nm | 70 nm | | |
| | | 1610 nm | 60 nm | | | | | | | | |
| 1610 nm | 60 nm | 1610 nm * | 60 nm | 1700 nm | 200 nm | 1600 nm | 90 nm | 1600 nm | 90 nm | 1640 nm | 50 nm |
| | | 2250 nm | 50 nm | | | | | | | 2130 nm | 50 nm |
| | | 3.70 μm | 0.18 μm | | | | | | | | |
| 3.74 μm | 0.38 μm | 3.74 μm * | 0.38 μm | 3.80 μm | 0.6 μm | 3.74 μm | 0.4 μm | 3.74 μm | 0.4 μm | | |
| | | 4.05 μm | 0.16 μm | | | | | | | | |
| | | 8.55 μm | 0.30 μm | | | | | | | | |
| 10.80 μm | 1.00 μm | 10.76 μm | 1.00 μm | 11.00 μm | 1.00 μm | 10.80 μm | 1.00 μm | 10.80 μm | 1.00 μm | | |
| | | 11.45 μm * | 1.90 μm | | | | | | | 11.25 μm * | 2.50 μm |
| 12.00 μm | 1.00 μm | 12.01 μm | 0.95 μm | 12.00 μm | 1.00 μm | 12.00 μm | 1.00 μm | 12.00 μm | 1.00 μm | | |
| 6 channels | | 22 channels | | 6 channels | | 10 channels | | 10 channels | | 20 channels | |
| Swath: 2900 km | | Swath: 3000 km | | Swath: 3000 km | | Swath: 2800 km | | Swath: 2800 km | | Swath: 2900 km | |
| IFOV: 1.1 km | | IFOV: 800 m (* 400 m) ch. 700 nm: day/night | | IFOV: 1.0 km | | IFOV: 1.1 km | | IFOV: 1.1 km | | IFOV: 1.0 km (* 250 m) | |

It may be observed that there are two typologies of VIS/IR imagers:

- AVHRR/3 on NOAA and Metop, MSU-MR on Meteor-M, MVISR on FY-1D;
- advanced imagers: VIIRS on NPP, MERSI+VIRR on FY-3A.

In Fig. 3.8.1 the coverage from these different classes of instruments is marked by different colours (blue: common current technology; red: advanced instruments). The figure shows that:

- in 2006, although the coverage is rather regular, there is no advanced imager;
- in 2008, in addition to the problem of the gap of coverage in the early-morning / late afternoon timeframes, only one advanced imager is expected (FY-3A MERSI); for a second one, it is necessary to wait for the NPP VIIRS due for launch in 2009. The orbits will be sufficiently distinct (FY-3A at 10.00 LST, NPP at 13.30 LST).

Table 3.9.2 compares the main features of sounders being operational or at least solidly defined in September 2006. The Table collects information on the IR component (radiometer or spectrometer) and the MW component.

Table 3.9.2 – Comparative performances of sounders on-board sun-synchronous satellites

| IR sounders | | | | MW cross-track sounders | | | | | |
|--|-----------------------|---------------------|-----------------------|--|-------------------|------------------------------------|-------------------|---|-------------------|
| NOAA & Metop HIRS/3 & HIRS/4 | | FY-3A IRAS | | NOAA & Metop AMSU-A & AMSU-B / MHS | | FY-3A MWTS & MWHS | | NPP ATMS | |
| Central λ | Bandwidth | Central λ | Bandwidth | ν (GHz) | $\Delta\nu$ (MHz) | ν (GHz) | $\Delta\nu$ (MHz) | ν (GHz) | $\Delta\nu$ (MHz) |
| 14.95 μm | 3 cm^{-1} | 14.95 μm | 3 cm^{-1} | 23.800 | 270 | | | 23.800 | 270 |
| | | 14.80 μm | 3 cm^{-1} | 31.400 | 180 | | | 31.400 | 180 |
| 14.71 μm | 10 cm^{-1} | 14.71 μm | 10 cm^{-1} | 50.300 | 180 | 50.300 | 180 | 50.300 | 180 |
| 14.49 μm | 12 cm^{-1} | 14.49 μm | 12 cm^{-1} | | | | | 51.760 | 400 |
| 14.22 μm | 16 cm^{-1} | 14.22 μm | 16 cm^{-1} | 52.800 | 400 | | | 52.800 | 400 |
| 13.97 μm | 16 cm^{-1} | 13.97 μm | 16 cm^{-1} | 53.596 \pm 0.115 | 170 | 53.596 \pm 0.115 | 340 | 53.596 \pm 0.115 | 170 |
| 13.64 μm | 16 cm^{-1} | 13.64 μm | 16 cm^{-1} | 54.400 | 400 | | | 54.400 | 400 |
| 13.35 μm | 16 cm^{-1} | 13.35 μm | 16 cm^{-1} | 54.940 | 400 | 54.94 | 400 | 54.940 | 400 |
| 12.47 μm | 16 cm^{-1} | | | 55.500 | 330 | | | 55.500 | 330 |
| 11.11 μm | 35 cm^{-1} | 11.11 μm | 35 cm^{-1} | $f_0 = 57.290344$ | 330 | 57.290 | 330 | $f_0 = 57.290344$ | 330 |
| 9.71 μm | 25 cm^{-1} | 9.71 μm | 25 cm^{-1} | $f_0 \pm 0.217$ | 78 | | | $f_0 \pm 0.217$ | 78 |
| | | 8.16 μm | 25 cm^{-1} | $f_0 \pm 0.3222 \pm 0.048$ | 36 | | | $f_0 \pm 0.3222 \pm 0.048$ | 36 |
| 7.33 μm | 40 cm^{-1} | 7.33 μm | 40 cm^{-1} | $f_0 \pm 0.3222 \pm 0.022$ | 16 | | | $f_0 \pm 0.3222 \pm 0.022$ | 16 |
| 6.52 μm | 55 cm^{-1} | 6.52 μm | 80 cm^{-1} | $f_0 \pm 0.3222 \pm 0.010$ | 8 | | | $f_0 \pm 0.3222 \pm 0.010$ | 8 |
| 4.57 μm | 23 cm^{-1} | 4.57 μm | 23 cm^{-1} | $f_0 \pm 0.3222 \pm 0.0045$ | 3 | | | $f_0 \pm 0.3222 \pm 0.0045$ | 3 |
| 4.52 μm | 23 cm^{-1} | 4.52 μm | 23 cm^{-1} | 89 | 6000 | | | | |
| 4.47 μm | 23 cm^{-1} | 4.47 μm | 23 cm^{-1} | 89 (*) | 1000 (*) | | | 89.5 | 5000 |
| 4.45 μm | 23 cm^{-1} | 4.40 μm | 23 cm^{-1} | 89 (**) | 2800 (**) | 150.0 | 1000 | | |
| 4.13 μm | 28 cm^{-1} | 4.20 μm | 23 cm^{-1} | 150 (*) | 1000 (*) | | | | |
| 4.00 μm | 35 cm^{-1} | 4.00 μm | 35 cm^{-1} | 157.0 (**) | 2800 (**) | | | 165.5 | 3000 |
| 3.76 μm | 100 cm^{-1} | 3.76 μm | 100 cm^{-1} | 183.31 \pm 7.0 (*) | 2000 (*) | 183.31 \pm 7.0 | 2000 | | |
| | | 1.64 μm | 450 cm^{-1} | 183.31 \pm 7.0 (**) | 2800 (**) | | | 183.31 \pm 7.0 | 2000 |
| | | 1.24 μm | 650 cm^{-1} | 183.31 \pm 3.0 (*) | 1000 (*) | 183.31 \pm 3.0 | 1000 | 183.31 \pm 4.5 | 2000 |
| | | 0.94 μm | 200 cm^{-1} | 183.31 \pm 3.0 (**) | 2000 (**) | | | 183.31 \pm 3.0 | 1000 |
| | | 0.94 μm | 550 cm^{-1} | 183.31 \pm 1.0 (*) | 500 (*) | 183.31 \pm 1.0 | 500 | 183.31 \pm 1.8 | 1000 |
| 0.69 μm | 1000 cm^{-1} | 0.885 μm | 385 cm^{-1} | 183.31 \pm 1.0 (**) | 1000 (**) | | | 183.31 \pm 1.0 | 500 |
| | | 0.69 μm | 1000 cm^{-1} | 193.31 (**) | 2000 (**) | | | | |
| | | | | (*) AMSU-B, (**) MH | | | | | |
| 20 channels | | 26 channels | | 15 + 5 channels | | 4 + 5 channels | | 22 channels | |
| Swath: 2200 km | | Swath: 2250 km | | Swath: 2200 km | | Swath: 2250 km | | Swath: 2300 km | |
| IFOV: 18 km (HIRS-3) 10 km (HIRS-4) | | IFOV: 17 km | | IFOV: 48 km (AMSU-A) 16 km (AMSU-B) | | IFOV: 70 km (MWTS) 15 km (MWHS) | | IFOV: 32 km (temperature) 16 km (humidity) | |

| Advanced IR sounders | | | |
|-------------------------------|--|--|---|
| Parameter | Metop IASI | NPP CrIS | Meteor-M-2 IRFS-2 |
| Spectral range | 3.62-15.5 μm (645-2760 cm^{-1}) | 3.92-15.4 μm (650-2550 cm^{-1}) | 5-15 μm (665-2000 cm^{-1}) |
| Bands and spectral resolution | 8.26-15.50 μm , 0.25 cm^{-1} | 9.13-15.40 μm , 0.625 cm^{-1} | 0.5 cm^{-1} |
| | 5.00-8.26 μm , 0.25 cm^{-1} | 5.71-8.26 μm , 1.25 cm^{-1} | |
| | 3.62-5.00 μm , 0.25 cm^{-1} | 3.92-4.64 μm , 2.5 cm^{-1} | |
| Channels | 8460 | 1300 | 4000 |
| NE Δ T | 0.2-0.35 K @ 280 K | 0.1-0.5 K @ 250 K | 0.5 K @ 300 K |
| IFOV at s.s.p. | 12 km | 14 km | 35 km |
| Sampling | 2 x 2 IFOVs in 48 x 48 km^2 | 3 x 3 IFOVs in 48 x 48 km^2 | 1 IFOV in 100 x 100 km^2 |
| Swath | 2230 km (30 FOV's/scan) | 2230 (30 FOV's/scan) | 2500 km (30 FOV's/scan) |

It may be observed that there are three typologies of sounding systems, depending on the IR component being a radiometer or a spectrometer, and the MW sounder being of the MSU or the AMSU class:

- TOVS-like: IRAS + MWTS + MWHS on FY-3A;
- ATOVS: HIRS + AMSU-A + AMSU-B/MHS on NOAA and Metop;

- advanced sounders: ATOVS + IASI on Metop, CrIS + ATMR on NPP, IRFS-2 + MTVZA on Meteor-M-2.

In Fig. 3.8.2 the coverage from these different classes of instruments is marked by different colours (green: TOVS-like; blue: ATOVS; red: advanced instruments). The figure shows that:

- in 2006, in addition to the problem of the gap of coverage in the early-morning / late afternoon timeframes, there is no advanced imager;
- in 2008, in addition to the (enhanced) problem of the gap of coverage in the early-morning / late afternoon timeframes, only one advanced imager is expected (MetOp ATOVS+IASI); for a second one, it is necessary to wait for Meteor-M-2 IRFS/2+MTVZA (launch in 2008 but operational in 2009), since Meteor-M-1 is not going to be equipped with IRFS-2. However, the orbits of MetOp and Meteor-M are rather close (LST 9.30 and 10.20 respectively) The next would be NPP CrIS+ATMR in 2009, in an orbit sufficiently distinct (13.30).

Table 3.9.3 compares the main features of conical scanning MW radiometers being operational or at least solidly defined in September 2006.

Table 3.9.3 - Comparative performances of MW conical scanners (imagers and imaging/sounders)

| FY-3A MWRI | | | DMSP SSM/I | | | DMSP SSMIS | | | Meteor-M MTVZA | | |
|----------------|------------------|------|--------------------|------------------|------|------------------------------|------------------|------|----------------------------|------------------|------|
| v (GHz) | Δv (MHz) | Pol. | v (GHz) | Δv (MHz) | Pol. | v (GHz) | Δv (MHz) | Pol. | v (GHz) | Δv (MHz) | Pol. |
| 10.65 | 180 | V, H | | | | | | | | | |
| 18.7 | 200 | V, H | 19.35 | 400 | V,H | 19.35 | 400 | V,H | 18.7 | 800 | V,H |
| 23.8 | 400 | V, H | 22.235 | 400 | V | 22.235 | 400 | V | 22.235 | 1600 | V |
| | | | | | | | | | 33.0 | 2000 | V,H |
| 36.5 | 900 | V, H | 37.0 | 1500 | V,H | 37.0 | 1500 | V,H | 36.5 | 2000 | V,H |
| | | | | | | | | | 42.0 | 2000 | V,H |
| | | | | | | 50.3 | 400 | H | 48.0 | 2000 | V,H |
| | | | | | | 52.8 | 400 | H | 52.80 | 400 | V |
| | | | | | | 53.596 | 400 | H | 53.30 | 400 | V |
| | | | | | | 54.4 | 400 | H | 53.80 | 400 | V |
| | | | | | | | | | 54.64 | 400 | V |
| | | | | | | 55.5 | 400 | H | 55.63 | 400 | V |
| | | | | | | $f_0 = 57.29$ | 350 | - | $f_0 = 57.29$ | | |
| | | | | | | 59.4 | 250 | - | $f_0 \pm 0.3222 \pm 0.1$ | 50 | H |
| | | | | | | $f_1 = 60.792668$ | | | $f_0 \pm 0.3222 \pm 0.05$ | 20 | H |
| | | | | | | $f_1 \pm 0.357892 \pm 0.050$ | 120 | V+H | $f_0 \pm 0.3222 \pm 0.025$ | 10 | H |
| | | | | | | $f_1 \pm 0.357892 \pm 0.016$ | 32 | V+H | $f_0 \pm 0.3222 \pm 0.01$ | 5 | H |
| | | | | | | $f_1 \pm 0.357892 \pm 0.006$ | 12 | V+H | $f_0 \pm 0.3222 \pm 0.005$ | 3 | H |
| | | | | | | $f_1 \pm 0.357892 \pm 0.002$ | 6 | V+H | | | |
| | | | | | | $f_1 \pm 0.357892$ | 3 | V+H | | | |
| | | | | | | 63.283248 ± 0.285271 | 3 | V+H | | | |
| 89 | 4600 | V, H | 85.5 | 3000 | V,H | 91.655 | 3000 | V,H | 91.65 | 3000 | V,H |
| 150 | 3000 | V, H | | | | 150 | 1500 | H | | | |
| | | | | | | 183.31 ± 6.6 | 1500 | H | 183.31 ± 7.0 | 1500 | V |
| | | | | | | 183.31 ± 3.0 | 1000 | H | 183.31 ± 3.0 | 1000 | V |
| | | | | | | 183.31 ± 1.0 | 500 | H | 183.31 ± 1.0 | 500 | V |
| 12 channels | | | 7 channels | | | 24 channels | | | 29 channels | | |
| Swath: 1400 km | | | Swath: 1400 km | | | Swath: 1700 km | | | Swath: 2200 km | | |
| 12 km @ 89 GHz | | | 12.5 km @ 85.5 GHz | | | 12.5 km @ 91.655 GHz | | | 17 km @ 91.65 GHz | | |

It may be observed that there are two typologies of MW conical scanners:

- imagers in window channels: SSM/I on DMSP, MWRI on FY-3A;
- imaging/sounders: SSMIS on DMSP, MTVZA on Meteor-M.

In Fig. 3.8.3 the coverage from these different classes of instruments is marked by different colours (blue: SSM/I-like imagers; red: advanced imager/sounders). The figure shows that:

- in 2006, although there are four active satellites, most of the day is uncovered; in essence, there are only two distinct orbits, around 6.30 and 8.30, with two redundant satellites in each. Only one of the four (DMSP-S16) has an advanced imager-sounder (SSMIS);
- in 2008, there will be still four satellites, in orbits somewhat better split, although the gap of coverage will continue to be very large. Three satellites out of four will be equipped with advanced imager-sounders. The coverage will be improved in 2009 with the launch of FY-3B carrying MWRI in the 14.00 orbit.

4. R&D PROGRAMMES OF GOS INTEREST

4.1 Generalities

The interest of GOS for R&D programmes, or single-launch satellites, or instruments on satellites, may stem from two motivations: i) the usefulness of data from R&D programmes/satellites/instruments in operational or research meteorology when they are being flown, even if long-term continuity is not guaranteed, data availability is not in real- or near-real time, and data quality is not fully characterised; and/or ii) the mission intends to provide demonstration of a new capability that can be later-on moved to an operational status.

It is reminded that the “*Implementation Plan for Evolution of Space and Surface-based Sub-systems of the GOS*” developed by the CBS Open Programme Area Group on the Integrated Observing Systems (OPAG-IOS) (WMO/TD No. 1267 dated April 2005), as concerns development in polar orbit of future operational interest has recommended the following:

- *LEO Doppler Winds - Wind profiles from Doppler lidar technology demonstration programme (such as Atmospheric Dynamics Mission - Aeolus) should be made available for initial operational testing; a follow-on long-standing technological programme is solicited to achieve improved coverage characteristics for operational implementation.*
- *GPM - The concept of the Global Precipitation Measurement Missions (combining active precipitation measurements with a constellation of passive microwave imagers) should be supported and the data realized should be available for operational use, thereupon, arrangements should be sought to ensure long-term continuity to the system.*
- *RO-Sounders - The opportunities for a constellation of radio occultation sounders should be explored and operational implementation planned. International sharing of ground network systems (necessary for accurate positioning in real time) should be achieved to minimize development and running costs.*
- *LEO MW - The capability to observe ocean salinity and soil moisture for weather and climate applications (possibly with limited horizontal resolution) should be demonstrated in a research mode (as with ESA’s SMOS and NASA’s OCE) for possible operational follow-on. Note that the horizontal resolution from these instruments is unlikely to be adequate for salinity in coastal zones and soil moisture on the mesoscale.*
- *LEO SAR - Data from SAR should be acquired from R&D satellite programmes and made available for operational observation of a range of geophysical parameters such as wave spectra, sea ice, land surface cover.*
- *LEO Aerosol - Data from process study missions on clouds and radiation as well as from R&D multi-purpose satellites addressing aerosol distribution and properties should be made available for operational use.*
- *Cloud Lidar - Given the potential of cloud lidar systems to provide accurate measurements of cloud top height and to observe cloud base height in some instances (stratocumulus, for example), data from R&D satellites should be made available for operational use.*
- *LEO Far IR - An exploratory mission should be implemented, to collect spectral information in the Far IR region, with a view to improve understanding of water vapour spectroscopy (and its effects on the radiation budget) and the radiative properties of ice clouds.*
- *Limb Sounders - Temperature profiles in the higher stratosphere from already planned missions oriented to atmospheric chemistry exploiting limb sounders should be made operationally available for environmental monitoring.*

- *Active Water Vapour Sensing* - There is need for an exploratory mission demonstrating high-vertical resolution water vapour profiles by active remote sensing (for example by DIAL) for climate monitoring and, in combination with hyper-spectral passive sensing, for operational NWP.

4.2 ESA programmes

ESA EO programmes have several activity lines:

- Earth Watch missions
- the ERS-2 / Envisat programmes
- Earth Explorer missions
- GMES
- International Charter on Space and Major Disasters
- EarthNet / Third Party Missions.

4.2.1 Earth Watch missions

Earth Watch missions, are intended to develop operational series. Prior to formalising this activity as part of the EO Envelope programme, ESA had already developed:

- the **Meteosat Programme** (Meteosat-1/2/3, first launched in 1977) including launch and operations;
- the space segment of the **Meteosat Operational Programme (MOP)** (Meteosat-4/5/6/7, the last also known as Meteosat Transition Programme or MTP), was under the finance responsibility of EUMETSAT as from early 1987. The handover of operations from ESA to EUMETSAT took place in late 1995;
- the space segment of **Meteosat Second Generation (MSG)** (Meteosat-8 to be followed by 9/10/11) in partnership with EUMETSAT and providing *GERB* as an Announcement of Opportunity instrument for Meteosat-8.

Currently, ESA is cooperating with EUMETSAT for the definition of **Meteosat Third Generation (MTG)**. Target launch date is 2015.

Information on all these components of the Meteosat programme is provided under Chapter 2.2 (The Meteosat programme)

As for the sunsynchronous orbit, ESA has already developed:

- the space segment of the three **MetOp** satellites constituting the first series of the EUMETSAT Polar System (EPS) in partnership with EUMETSAT.

Information on the MetOp/EPS programme is provided under Chapter 3.5 (The EPS/MetOp programme).

Currently, ESA is cooperating with EUMETSAT for the definition of the **post-EPS programme**. Target launch date is 2019.

4.2.2 The ERS 1/2 and Envisat programmes

After the initial involvement in meteorology, with Meteosat, ESA moved to multi-disciplinary programmes with **ERS (European Remote-Sensing satellite)**. After ERS-1, launched on 17 July 1991, the spare model was refurbished and launched as ERS-2 in 1995 with additional payload (*GOME*).

Envisat (the largest Earth Observation satellite ever launched) is in fact a totally new programme but it is worth to list it in the same context of ERS since provides continuity to most of ERS instruments and closes a type of space mission approach (large multi-purpose satellites). The three satellites are 3-axis stabilised, placed in similar sunsynchronous orbits. **Table 4.2.1** records the chronology of ERS-1, ERS-2 and Envisat. **Fig. 4.2.1** and **Fig. 4.2.2** show the aspects of ERS-2 and Envisat respectively.

Table 4.2.1 – Chronology of ERS and Envisat (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST | Status (Sept 2006) | Instruments |
|----------------|--------------------|------------------------|---------------|--------------|--------------------|---|
| ERS-1 | 17 Jul 1991 | 10 Mar 2000 | 785 km | 10.30 | Inactive | AMI, RA, ATSR, MWR, LRR, PRARE |
| ERS-2 | 21 Apr 1995 | expected ≥ 2008 | 785 km | 10.30 | Operational | AMI, RA, ATSR-2, MWR, GOME, LRR, PRARE |
| Envisat | 1 Mar 2002 | expected ≥ 2010 | 800 km | 10.00 | Operational | ASAR, RA-2, AATSR, MWR, MERIS, MIPAS, GOMOS, SCIAMACHY, LRR, DORIS |

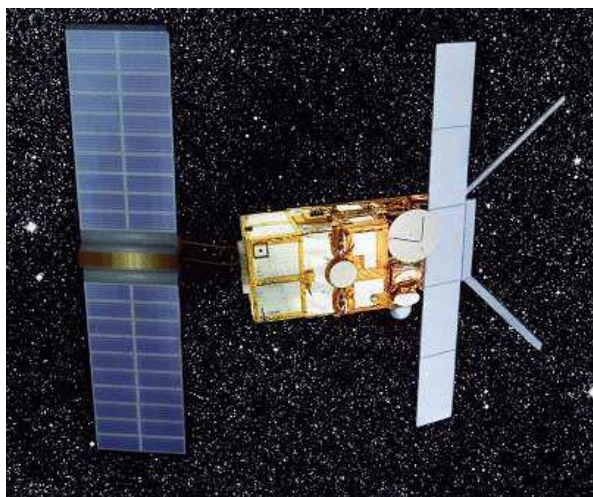


Fig. 4.2.1 – Sketch view of ERS-2.



Fig. 4.2.2 - Sketch view of Envisat.

ERS-2 is still operating after 11 years from launch, although its nominal life time was 5 years. All instruments are working, but the global on-board recording failed in June 2003, so now LBR data is available on ESA station's visibility and a network of receiving stations. In one overlapping period with ERS-1 (9 months across 1995-1996) the two satellites were operated in "tandem" mode to increase the frequency of coverage and provide a large dataset for SAR interferometry (e.g., for Digital Elevation Model updating). The ERS SAR production continues to increase, in response to users requests.

Envisat has been operating for over 4 years now. Most instruments are working at nominal performance. Exceptions: some degradation of *MIPAS* and *GOMOS*. A series of anomalies affected the Radar Altimeter in early 2006; workaround solutions are being implemented.

Payload of ERS-2 (including all of ERS-1 + ATSR improvement and addition of GOME)

- **AMI (Active Microwave Instrument)**: a C-band (5.3 GHz) package that shares operations among:
 - imaging **SAR (Synthetic Aperture Radar)**, swath 100 km, resolution 30 m, duty cycle 12%;
 - **wind scatterometer (SCAT)**, swath 500 km, resolution 50 km (sampling 25 km), duty cycle any time when the SAR imaging mode in not active, thus up to 88 %;
 - **SAR wave mode**, activated each 200 or 300 km, to observe 5 x 5 km² *imagettes* of 30 m resolution where spectra of the echoes are retrieved to determine wave power, direction and length; duty cycle 70 %, possible simultaneously with the SCAT mode.
- **RA (Radar Altimeter)**: a Ku-band radar (13.8 GHz) to measure significant wave height, wind speed, ocean topography and ice topography; nadir-pointing, resolution 20 km along-track.
- **MWR (Micro-Wave Radiometer)**: two-frequency radiometer (23.8 and 36.5 GHz) to measure total-column water vapour over the ocean necessary to provide wet tropospheric path delay correction for RA; nadir-pointing, resolution 20 km along-track.
- **ATSR-2 (Along-Track Scanning Radiometer - 2)**: 7-channel VIS/IR radiometer (4-channels in ERS-1/ATSR) for multi-purpose imagery (with special emphasis on very accurate sea-surface temperature); swath 500 km, conical scanning for cross-nadir and forward views, resolution 1km.

- **GOME (Global Ozone Monitoring Experiment):** 4096-channel grating spectrometer. Spectral range 240-790 nm with spectral resolution 0.2 nm in UV and 0.4 nm in VIS. Tracked species: O₃, O₂, O₄, NO, NO₂, NO₃, H₂O, BrO, ClO, OCIO, HCHO, SO₂ and aerosol. Resolution 40 km along-track, 320 km cross-track for a 960 km swath or 40 km for a 120 km swath.
- **PRARE (Precise Range And Range-rate Equipment) and LRR (Laser Retro-Reflector):** for precision orbit determination, specifically useful for the topographic applications of RA.

Instruments sheets are provided in Annex A3.2 for AMI, RA, MWR, ATSR-2 and GOME.

Payload of Envisat

- **ASAR (Advanced Synthetic Aperture Radar):** still operating in C-band (5.3 GHz). In the “**stripmap mode**” it operates similarly to the ERS-1/2 SAR, except that the 100 km swath may be selected among 7 possibilities within a viewing area of 485 km, the polarisation may be either HH or VV, and the “**wave mode**” is activated at 100 km intervals. The resolution is still 30 m. In the “**scanSAR mode**” more modes are available:
 - *alternating polarisation* over the same image strips of the strip map mode
 - *wide swath* over 405 km with resolution degraded to 150 m
 - *global monitoring* over 405 km swath with 1 km resolution, active > 70 % of the time whereas all other modes (stripmap, alternating polarisation, wider swath) can only be active < 30 %.
- **RA-2 (Radar Altimeter - 2):** improved over ERS-1/2 RA by complementing the basic Ku-band frequency (13.6 GHz) by an S-band frequency (3.2 GHz) for better atmospheric corrections.
- **AATSR (Advanced Along-Track Scanning Radiometer),** re-designed after the ERS-2 ATSR-2.
- **MERIS (Medium Resolution Imaging Spectrometer):** 15-channel VIS/NIR spectroradiometer for ocean colour, vegetation and aerosol; swath 1150 km, resolution 300 m or 1200 m.
- **MWR (Micro-Wave Radiometer),** re-designed after the ERS-1/2 MWR.
- **MIPAS (Michelson Interferometer for Passive Atmospheric Sounding):** limb-scanning interferometer for atmospheric chemistry. Spectral range 4.15-14.6 μm with spectral resolution 0.035 cm⁻¹. Tracked species: O₃, NO, NO₂, HNO₃, HNO₄, N₂O₅, ClONO₂, COF₂, HOCl, CH₄, H₂O, N₂O, CFC's (F11, F12, F22, CCl₄, CF₄), CO, OCS, C₂H₂, C₂H₆, SF₆ and aerosol. Vertical resolution 3 km in the range 5-150 km.
- **GOMOS (Global Ozone Monitoring by Occultation of Stars):** limb-viewing grating spectrometer for atmospheric chemistry by occultation of 25-40 stars per orbit. Spectral range 250-950 nm with spectral resolution 0.89 nm (UV/VIS) and 0.12 nm (NIR). Tracked species: O₃, H₂O, NO₂, NO₃, OCIO, BrO, ClO and aerosol. Vertical resolution 1.7 km in the range 20-100 km.
- **SCIAMACHY (Scanning Imaging Absorption Spectrometer for Atmospheric Cartography):** grating spectrometer for atmospheric chemistry exploiting both limb and cross-nadir scanning. Solar and lunar occultation are possible as well. Spectral range 240-2380 nm with spectral resolution 0.24 to 1.48 nm. Tracked species: O₃, O₂, O₄, NO, NO₂, NO₃, N₂O, CO, CO₂, CH₄, H₂O, BrO, ClO, OCIO, HCHO, SO₂ and aerosol. Vertical resolution (limb mode) 3 km in the range 10-100 km, horizontal resolution (cross-nadir mode) 16 x 32 km² over a 1000 km swath.
- **DORIS (Doppler Orbitography and Radiopositioning Integrated by Satellite) and LRR (Laser Retro-Reflector):** for precision orbit determination, especially useful for the topographic applications of RA-2 and limb sounders' navigation.

Instrument sheets are provided in Annex A3.2 for ASAR, RA-2, MERIS, MIPAS, SCIAMACHY and GOMOS, in addition to those of AATSR (= ATSR-2) and MWR provided under ERS-2.

Data availability for the purpose of GOS

An Announcement of Opportunity (AO) specific for the use of ERS and Envisat data for WMO members was released in January 2003. Proposals can also be submitted at any time through the ESA web site (see detailed information at <http://eopi.esa.int>).

Several data from ERS-2 and Envisat are available in Near-Real-Time (NRT), i.e. within 3 h from data acquisition, for the purpose of operational meteorology.

Early since ERS-1, low-bit-rate data (significant wave height and wind speed from *RA*, sea-surface winds from *AMI-SCAT*, wave spectra from *AMI-Wave*) are distributed, BUFR-coded, via the Global Telecommunication System (GTS) through the Rome Regional Telecommunication Hub (RTH) of the Italian Meteorological Service.

During the lifetime of ERS-2, *GOME* data centralisation and processing times have been gradually reduced, so that products such as ozone total-column are now made available in NRT on ftp sites from the German space agency (DLR) and the Dutch Meteorological Institute (KNMI).

For Envisat, a BUFR-coded “meteorological package” is made freely available in NRT on ftp servers (password needed: see the procedure at <http://eopi.esa.int>). The package includes: significant wave height and wind speed from *RA-2 + MWR*, wave spectra from *ASAR-wave*, sea-surface temperatures from *AATSR*, cloud thickness and water vapour from *MERIS*, ozone profiles from *GOMOS* and columnar amounts of several trace gases from *SCIAMACHY*.

The other (high-rate) data are available from the network of Processing & Archiving Facilities (PAF, for ERS) or Centres (PAC, for Envisat) of the ERS/Envisat Ground Segment.

4.2.3 The Earth Explorer missions

The Earth Explorers, part of the EO Envelope programme, is a framework designed to develop single missions, either small (“opportunity missions”) or medium (“core missions”). The mission purposes address the study of a particular process, or the demonstration of a new observation capability. Core missions are selected following a “Call for Ideas”, Opportunity mission are selected following a “Call for Proposal”. So far, three Calls for Ideas have been processed; and two Calls for Proposals. **Table 4.2.2** provides essential information on the missions so far selected (in order of expected launch date):

- **CryoSat** (“opportunity mission”)
- **GOCE (Gravity Field and Steady-State Ocean Circulation Explorer)** (“core mission”)
- **SMOS (Soil Moisture and Ocean Salinity)** (“opportunity mission”)
- **ADM-Aeolus (Atmospheric Dynamics Mission - Aeolus)** (“core mission”)
- **Swarm (The Earth’s Magnetic Field and Environment Explorers)** (“opportunity mission”)
- **Earth-CARE (Earth Clouds, Aerosol and Radiation Explorer)** (“core mission”)

Table 4.2.2 – List of selected Earth Explorer missions as of September 2006

| Satellite | Launch | Life | Orbit | Main instruments | Mission |
|-----------------------------|------------|---------------|---|--|--|
| CryoSat | 8 Oct 2005 | Launch failed | Non-sunsynchronous, 717 km, inclination 92° | SIRAL (SAR/Interferometric Radar Altimeter) | Ice thickness and topography |
| GOCE | May-2007 | 1.3 y | Sunsynchronous, 250 km, LST 06/18 | Gravity Gradiometer, 12-channel GPS receiver | Gravity field anomalies and accurate geoid |
| SMOS | Sep-2007 | ≥ 3 y | Sunsynchronous, 763 km, LST 06/18 | MIRAS (Microwave Imaging Radiometer using Aperture Synthesis) | Large-scale salinity and soil moisture |
| ADM-Aeolus | Sep-2008 | 3 y | Sunsynchronous, 400 km, LST 06/18 | ALADIN (Atmospheric Laser Doppler Instrument) | Wind profile in clear air |
| CryoSat-2 | Mar-2009 | 3.5 y | Non-sunsynchronous, 717 km, inclination 92° | SIRAL (SAR/Interferometric Radar Altimeter) | Ice thickness and topography |
| Swarm (3 satellites) | Feb-2010 | 4.5 y | 2 sats at 450 km, 87.4° 1 sat at 530 km, 86.8° | Magnetometers (scalar and vector), Electric Field, Accelerometer | Earth interior through geomagnetic field |
| Earth-CARE | Dec-2012 | 2-3 y | Sunsynchronous, 450 km, LST 10:30 | ATLID (Atmospheric Lidar), CPR (Cloud Profiling Radar), MSI (Multi-Spectral Imager), BBR (Broad-Band Radiometer) | Cloud microphysics, radiation, aerosol |

From the last Call for ideas, six mission concepts are under assessment, until end 2007:

- **BIOMASS**, aiming at quantifying the forest biomass, the extend of forest and deforested areas and the delimitation of flooded forests. Based on P-band SAR;
- **TRAQ**, to observe primary constituents for air quality in the troposphere;
- **PREMIER**, to provide high resolution measurements, using mm-wave and IR limb sounding, aimed to study processes in the upper troposphere and lower stratosphere;
- **FLEX**, to produce global scale maps of vegetation photosynthetic activity, to contribute to biosphere and global C cycle studies;
 - **SCOPE**, to map the source and sink of CO₂ on a scale of 500 km or better. It will use the DIAL sensor.
 - **CoReH₂O**, to estimate snow water equivalent and depth on land and sea ice, by X-band SAR.

Data from Earth Explorer missions may be released for use within the GOS. Specifically, ADM-Aeolus data will need intensive evaluation in view of a possible operational follow-on. Data from SMOS and Earth-CARE also could be used to improve modelling and parameterisation in NWP.

4.2.4 GMES

The **Global Monitoring for Environment and Security (GMES)** initiative led by the European Commission and ESA represents the major milestone for future European efforts in EO. The ESA GMES Space Component programme Phase 1 activities have been initiated. The **Sentinels** missions under study are:

- **Sentinel-1**: provision of continuity of C-band SAR; launches: June 2011 and 2013
- **Sentinel-2**: provision of superspectral optical imagery; launches: Nov 2011 and 2013
- **Sentinel-3**: provision of oceanographic services; launches: Feb 2012 and 2014
- **Sentinel-4**: atmospheric chemistry from geostationary orbit; launches TBD
- **Sentinel-5**: atmospheric chemistry from low earth orbit; launches TBD.

A fire-infrared element will be flown on several spacecraft of the Sentinel-2 and Sentinel-3 families.

4.2.5 International Charter on Space and Major Disasters

Following the UNISPACE III conference held in Vienna, Austria in July 1999, the European and French space agencies (ESA and CNES) initiated the International Charter "Space and Major Disasters", with the Canadian Space Agency (CSA) signing the Charter on October 20, 2000. Since its signing, the International Charter on Space and Major Disasters has been providing important EO satellite data input to natural hazards post-crisis management around the world, with both increasing Charter activations and participating space agencies as data providers.

4.2.6 EarthNet / Third Party Missions

This programme element has been running for almost 30 years. It enables harmonised access to non-ESA missions for the benefit of European users. Currently, ESA provides access to data from 17 Third Party Missions and 24 instruments.

4.3 NASA programmes

The number of Earth Observation NASA programmes or missions is very large. We limit this report to those that have or have had largest impact on the evolution of the Global Observing System (GOS). The selection, somewhat disputable, includes:

- the Nimbus programme, SeaSat, ERBS, UARS;
- the Landsat programme;
- the EOS programme;
- the Earth System Science Pathfinder programme;
- a selection of other missions relevant for GOS.

The TIROS programme has been reported as precursor of NOAA/POES under Section 3.2, the ATS programme as precursor of GOES under Section 2.3. NASA assists NOAA for installing the

POES and GOES satellites and is partner of NOAA and the DoD for implementing NPOESS (Section 3.4).

4.3.1 The Nimbus programme, SeaSat, ERBS and UARS

In this Section we collect historical information on those large R&D programmes that have been basic for testing remote sensing principles and demonstrating instrumentation thereafter utilised in operational programmes. **Table 4.3.1** reports the chronology of the Nimbus, SeaSat, ERBS and UARS programmes. **Fig. 4.3.1** and **Fig. 4.3.2** show the aspects of Nimbus-7 and UARS respectively.

Table 4.3.1 – Chronology of Nimbus, SeaSat, ERBS and UARS satellites

| Satellite | Launch | End of service | Height | LST / incl. | Instruments |
|-----------|-------------|----------------|---------|-------------|---|
| Nimbus-1 | 28 Aug 1964 | 23 Sep 1964 | 680 km | 12:00 | HRIR, AVCS, APT |
| Nimbus-2 | 15 May 1966 | 17 Jan 1969 | 1140 km | 11:30 | HRIR, AVCS, APT, MRIR |
| Nimbus-3 | 13 Apr 1969 | 22 Jan 1972 | 1100 km | 12:00 | HRIR, IDCS, MRIR, IRIS-B, SIRS, MUSE, IRLS |
| Nimbus-4 | 8 Apr 1970 | 30 Sep 1980 | 1100 km | 12:00 | THIR, IDCS, IRIS-D, SIRS-B, FWS, SCR, MUSE, BUV, IRLS |
| Nimbus-5 | 10 Dec 1972 | 29 Mar 1983 | 1100 km | 12:00 | THIR, SCMR, ESMR, ITPR, SCR, NEMS |
| Nimbus-6 | 12 Jun 1975 | 29 Mar 1983 | 1100 km | 12:00 | THIR, ESMR, HIRS, PMR, SCAMS, LRIR, ERB, TWERLE |
| Nimbus-7 | 24 Oct 1978 | ????? 1994 | 947 km | 12:00 | THIR, CZCS, SMMR, LIMS, SAM-II, SAMS, SBUV, TOMS, ERB |
| SeaSat | 27 Jun 1978 | 10 Oct 1978 | 785 km | 108° | SAR, SMMR, ALT, SASS, VIRR, LTR |
| ERBS | 5 Oct 1984 | 14 Oct 2005 | 610 km | 57° | ERBE, SAGE-II |
| UARS | 12 Sep 1991 | 14 Dec 2005 | 700 km | 57° | CLAES, ISAMS, HALOE, MLS, SOLSTICE, SUSIM, HRDI, WINDII, ACRIM-2, PEM |

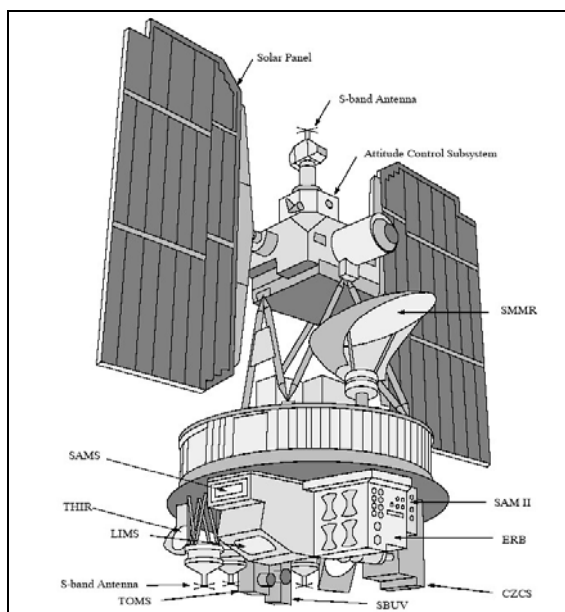


Fig. 4.3.1 – Sketch view of Nimbus-7.



Fig. 4.3.2 - Sketch view of UARS.

4.3.1.1 Instrument evolution through the Nimbus programme

The Nimbus programme was the engine of proof-of-concepts and instrument development in support of the meteorological operational systems. We provide here a shortest review of the full instruments list.

Evolution of VIS/IR imagers

- **APT (Automatic Picture Transmission)** [Nimbus-1/2], and thereafter **IDCS (Image Dissector Camera System)** [Nimbus-3/4], were single-channel (VIS) cameras, resolution 2.5 km s.s.p., swath 2200 km, with real-time transmission capability that established a standard for certain aspects still valid nowadays. It was then used in ESSA satellites.

- **AVCS (Advanced Vidicon Camera System)** [Nimbus-1/2] had higher resolution (0.9 km s.s.p.) and 3500 km swath achieved by three side-to-side cameras. It was then used on ESSA satellites.
- **HRIR (High Resolution Infrared Radiometer)** [Nimbus-1/2/3] introduced cross-track mechanical scanning for IR imagery. Single channel (3.5-4.1 μm), resolution 9 km s.s.p., effective swath 3000 km, real-time transmission capability. On Nimbus-3 a second channel was added (0.7-1.3 μm).
- **THIR (Temperature-Humidity Infrared Radiometer)** [Nimbus-4/5/6/7] had two channels, 6.5-7.0 μm (resolution 22 km s.s.p.) and 10.5-12.5 μm (resolution 8 km s.s.p.), effective swath 3000 km, real-time transmission on Nimbus-4 (discontinued on Nimbus 5/6/7).
- **SCRM (Surface Composition Mapping Radiometer)** [Nimbus-5], designed for distinguishing acidic and basic rocks, soils and sediments, had three channels, 0.8-1.1 μm , 8.3-9.3 μm and 10.2-11.2 μm ; resolution 660 m s.s.p., swath 800 km.
- **CZCS (Coastal Zone Colour Scanner)** [Nimbus-7], prototype of follow-on instruments for ocean colour monitoring, had 6 channels centred on 0.443, 0.52, 0.55, 0.67, 0.75 and 11.5 μm , resolution 825 m s.s.p., swath 1600 km.

Evolution of MW imagers

- **ESMR (Electrically Scanning Microwave Radiometer)** [Nimbus-5/6] on Nimbus-5 was working at 19.35 GHz, best suited for ocean ice and heavy precipitation over ocean, with resolution 25 km s.s.p. and swath 3100 km electrically scanned. On Nimbus-6 the frequency was changed to 37 GHz, more suitable for snow mapping and sensitive to light rain. Two polarisations were provided by conical (still electrical) scanning, with resolution 30 km (quadratic average) and swath 1270 km.
- **SMMR (Scanning Multichannel Microwave Radiometer)** [Nimbus-7] was a conical mechanical scanning radiometer with 5 frequencies (6.6, 10.7, 18, 21 and 37 GHz) all in double polarisation. Resolution (quadratic average) ranging from 22 km at 37 GHz to 120 km at 6.6 GHz, swath 780 km.

Evolution of IR sounders

- **IRIS (Infra-Red Interferometer Spectrometer)** [Nimbus-3/4] placed the foundation not only for the IR sounding mission, but also for the selection of channels for IR imagers. On Nimbus-3 the spectral range was 5-20 μm and the spectral resolution 2.5 cm^{-1} (unapodised); on Nimbus-4 the spectral range was 5-25 μm and the spectral resolution 1.4 cm^{-1} (unapodised). Nadir-only viewing, with resolution 150 km (Nimbus-3) or 94 km (Nimbus-4).
- **SIRS (Satellite Infra-Red Spectrometer)** [Nimbus-3/4] was differing from IRIS in so far as it was aiming at a more robust configuration suitable for future operational concepts. Though based on a grating spectrometer, a relatively small number of radiometric channels were drawn: in Nimbus-3, 8 channels in the range 11-15 μm , in Nimbus-4 further 6 channels were added, in the rotational band of water vapour, 18-36 μm . The resolution was 220 km, nadir-only in Nimbus-3, with 3 cross-track spots for Nimbus-4 (total swath 1800 km).
- **FWS (Filter Wedge Spectrometer)** [Nimbus-4] experienced the spectral scan method based on alternating filters, still in use on the current *HIRS* of POES and Metop. Two bands, 3.2-6.4 μm and 1.2-2.4 μm , spectral resolution 0.6-1.2 %, horizontal resolution 70 km, nadir-only view.
- **ITPR (Infrared Temperature Profile Radiometer)** [Nimbus-5] used parallel telescopes for better radiometric budget and higher resolution (36 km s.s.p. over a 1700 km swath). Seven channels in the range 3.7-19.7 μm , bandwidth around 2 %.
- **HIRS (High-resolution Infra-Red Sounder)** [Nimbus-6], embarked in 1975, is still in use on POES and Metop satellites after several upgradings. At that time it had 16 IR channels covering the range 3.7-15 μm + 1 VIS channel, bandwidths around 1 %, 24 km resolution, 1800 km swath.
- **SCR (Selective Chopper Radiometer)** [Nimbus-4/5] was designed for profiles in the stratosphere, using filter cell differently pressurised so as to change the height of the weighting

function peak. On Nimbus-4 there were 6 channels around 15 μm , resolution 130 or 220 km; on Nimbus-5 16 channels including the rotational water vapour band up to 50 μm , resolution 29 or 42 km. Nadir-only view.

- **PMR (Pressure Modulator Radiometer)** [Nimbus-6] was an upgrade of SCR, changing the height of the weighting function peak between 40 and 90 km by modulating the pressure in only two cells. It was the predecessor of the SSU (*Stratospheric Sounding Unit*) operationally flown up to NOAA-14. Resolution 500 km, nadir-only view.

Evolution of MW sounders

- **NEMS (Nimbus-E Microwave Sounder)** [Nimbus-5] had five channels, 3 in the 54 GHz band, then 22.2 and 31.4 GHz. Resolution 190 km, nadir-only view.
- **SCAMS (Scanning Microwave Spectrometer)** [Nimbus-6] had the same channels as NEMS, but cross-nadir scanning capability; resolution 145 km s.s.p., swath 2400 km. It was the predecessor of MSU (*Microwave Scanning Unit*) operationally flown up to NOAA-14.

Radiometers for earth radiation budget

- **MRIR (Medium Resolution Infrared Radiometer)** [Nimbus-2/3] had 5 channels, two broad-band (0.2-4.0 μm and 5-30 μm), three narrow-band (6.4-6.9 μm , 10-11 μm and 14-16 μm), to observe integrated short-wave (SW) and long-wave (LW) radiation from Earth to Space and its main components (water vapour, window, CO₂). Resolution 55 km s.s.p., swath 3000 km. On Nimbus-3 the LW channel was replaced by 20-23 μm .
- **ERB (Earth Radiation Budget)** [Nimbus-6/7] had 10 SW channels between 0.243 and 5.0 μm to measure incoming solar radiation, 4 non-scanning wide-angle (3300 km centred on nadir) earth-viewing channels between 0.2 and 50 μm , and 8 scanning channels for multi-angle observation (4 in SW, 4 in LW) with resolution 80 km s.s.p. over the 3300 km swath.

UV monitoring

- **BUV (Backscatter Ultraviolet Spectrometer)** [Nimbus-4] was measuring UV backscattered radiation in 12 narrow-band channels (1 nm) between 250 and 340 nm to derive ozone total-column and gross profile. Resolution 220 km, nadir-only view. **SBUV (Solar Backscatter Ultraviolet Spectrometer)** [Nimbus-7] was quite similar, and through several updating is still been used on POES satellites.
- **TOMS (Total Ozone Mapping Spectrometer)** [Nimbus-7] had 6 channels in the range 310-380 nm, 1 nm bandwidth, for total-column ozone. Resolution 50 km, swath 2700 km. It was re-flown on Meteor-3-6 (1991) and ADEOS-1 (1996), and as a dedicated mission (**TOMS Earth Probe**, 1996).
- **MUSE (Monitor of Ultraviolet Solar Energy)** [Nimbus-3/4] was measuring incoming solar radiation at 5 wavelengths in the range 115-300 nm during the sun occultation at each orbit.

Limb sounders

- **LRIR (Limb Radiance Inversion Radiometer)** [Nimbus-6] was a 4-channel radiometer measuring temperature (two channels in the 15 μm band), ozone (9.6 μm) and water vapour (25 μm) in the range 15-60 km, with vertical resolution 3 km. **LIMS (Limb Infrared Monitor of the Stratosphere)** [Nimbus-7] was the LRIR evolution, moving the water vapour channel from 25 with 6.2 μm and adding two channels, one for NO₂ (6.3 μm), one for HNO₃ (11.3 μm).
- **SAMS (Stratospheric and Mesospheric Sounder)** [Nimbus-7] was measuring profiles of temperature, water vapour, CH₄, CO, N₂O and NO, and by exploiting the filter cell pressure modulation technique of SCR and PMR in the limb geometry. There were 8 channels in the range 2.7-15 μm + one in the range 25-100 μm . Vertical resolution 5 km in the range 15-140 km.
- **SAM-II (Stratospheric Aerosol Measurement - II)** [Nimbus-7] was measuring aerosol profiles by sun occultation in a single channel at 1.0 μm . Vertical resolution 1 km in the range 10-40 km.

Data collection missions

- **IRLS (Interrogation, Recording and Location System)** [Nimbus-3/4] and **TWERLE (Tropical Wind Energy-conversion and Reference Level Experiment)** [Nimbus-6] were data collection (upon interrogation) and location systems. The **TWERLE** mission was associated to 300 floating balloons.

4.3.1.2 The SeaSat mission

SeaSat only lasted 106 days in orbit (70 useful for data generation), but this was sufficient to demonstrate the capabilities of active MW in all modes: SAR, altimetry, scatterometry. Instruments:

- **SAR (Synthetic Aperture Radar)**, first SAR in space, used L-band (1.275 GHz); swath 100 km, resolution 25 m, duty cycle ... %;
- **ALT (Radar Altimeter)** was a Ku-band radar (13.5 GHz) to measure significant wave height, wind speed, ocean topography and ice topography; nadir-pointing, resolution 12 km along-track. It was supported by **LTR (Laser Tracking Reflector)** for precision orbit determination.
- **SASS (SeaSat-A Scatterometer System)** was a Ku-band radar (14.6 GHz) for sea-surface winds; swath 1000 km (two side strips each 500 km wide), resolution 50 km.
- **SMMR (Scanning Multichannel Microwave Radiometer)**, same as on Nimbus-7, with resolution and swath scaled by a factor 700/950, consequence of different heights.
- **VIRR (Visible and Infra-Red Radiometer)**, supportive of the MW passive and active instruments, had two channels, 0.49-0.94 μm (resolution 2.3 km s.s.p.) and 10.5-12.5 μm (resolution 4.4 km s.s.p.), swath 3000 km.

4.3.1.3 The ERBS mission

ERBS (Earth Radiation Budget Satellite) performed a coordinated mission with NOAA-9 (1984-1998) in p.m. orbit and NOAA-10 (1986-2001) in a.m. orbit. It was in a drifting orbit to cover all Local Solar Times (LST's) during the year. It carried two instruments:

- **ERBE (Earth Radiation Budget Experiment)**, derived from **ERB**. The non-scanning channels had wide-angle (2000 km) and medium-angle (110 km). The scanning channels had resolution 40 km.
- **SAGE-II (Stratospheric Aerosol and Gas Experiment - II)**, follow-on of the NIMBUS-7 **SAGE-I**, operating in limb-mode during sun or moon occultation. 7-channel radiometer in the range 0.385-1.020 μm . Vertical resolution 1 km in the range 10-40 km. A **SAGE-III** follow-on was embarked on Meteor-3M-N1 (see Section 3.6) and instrument template in Annex A3.1.

4.3.1.4 The UARS mission

UARS (Upper Atmosphere Research Satellite) was mostly addressing atmospheric chemistry and dynamics in the stratosphere and mesosphere. When launched (1991) was by far the largest Earth Observation satellite ever in orbit (6800 kg). Instruments:

- **CLAES (Cryogenic Limb Array Etalon Spectrometer)** operating in four spectral ranges, 3.5, 6, 8 and 12.7 μm to observe CF_2Cl_2 , CF_4 , CFCl_3 , CH_4 , ClO , ClONO_2 , CO_2 , H_2O , HCl , HNO_3 , N_2O , NO , NO_2 , O_3 and temperature. Limb sounder with vertical resolution 2.5 km in the range 10-60 km.
- **ISAMS (Improved Stratospheric and Mesospheric Sounder)**, successor of **SAMS** on Nimbus-7. Now 8 channels in the range 4.6-16.6 μm . Species: CH_4 , CO , H_2O , HNO_3 , N_2O , N_2O_5 , NO , O_3 and aerosol. Limb sounder with vertical resolution 2.4 km in the range 15-140 km.
- **HALOE (Halogen Occultation Experiment)**, gas filter correlation spectrometer working in sun occultation in the range 2.43-10.25 μm . Species: CH_4 , H_2O , HCl , HF , NO , NO_2 , O_3 and pressure. Limb sounder with vertical resolution 1.6 km in the range 10-40 km.

- **MLS (Microwave Limb Sounder)** operating in three bands at frequencies 63 GHz, 183 GHz (2 channels) and 205 GHz (3 channels). Species: ClO, H₂O, H₂O₂, O₃ and pressure. Limb sounder with vertical resolution 4 km in the range 5-85 km.
- **SOLSTICE (Solar/Stellar Irradiance Comparison Experiment)**, grating spectrometer to compare solar and stellar irradiance in the range 115-430 nm with spectral resolution 0.12-0.25 nm.
- **SUSIM (Solar Ultraviolet Spectral Irradiance Monitor)**, dispersion spectrometer to measure solar irradiance in the range 120-400 nm with spectral resolution 0.1 nm.
- **HRDI (High-Resolution Doppler Imager)**, 13-bands Fabry-Perot interferometer operating in the 557-776 nm range with spectral resolution 0.05 cm⁻¹ to measure stratospheric winds by Doppler shift of O₂ lines. Limb sounder with vertical resolution 2.5 km in the range 10-115 km.
- **WINDII (Wind Doppler Imaging Interferometer)**, a Michelson interferometer measuring Doppler shift and broadening of several lines of ionised and molecular oxygen and OH in the 557-764 nm range with spectral resolution cm⁻¹. Limb sounder with vertical resolution 20 km in the range 80-300 km.
- **ACRIM-2 (Active Cavity Radiometer Irradiance Monitor)** to measure total solar irradiance.
- **PEM (Particle Environment Monitor)** to *in situ* monitor charged particles and magnetic field.

4.3.2 The Landsat programme and follow-on

The first land observation satellite, initially named *ERTS (Earth Resources Technology Satellite)*, thereafter re-named **Landsat-1**, was launched in 1972. It was followed by further 6 flight models that, in practise, provided nearly-uninterrupted service till nowadays. **Table 4.3.2** reports the chronology of the Landsat programme and follow-on activities. **Fig. 4.3.3** shows the aspect of Landsat-7. It is noted that the ~ 900 km height of Landsat 1 to 3 provides a repeat cycle of 18 days whereas the ~ 700 km height of Landsat 4 to 7 provides a 16-day repeat cycle.

Table 4.3.2 – Chronology of the Landsat programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST | Status (Sept 2005) | Instruments |
|------------------|--------------------|------------------------|---------------|--------------|--------------------------------|---------------------------|
| Landsat-1 (ERTS) | 23 Jul 1972 | 2 Jan 1978 | 907 km | 10:00 | Inactive | RBV, MSS, DCS |
| Landsat-2 | 22 Jan 1975 | 25 Feb 1982 | 908 km | 10:00 | Inactive | RBV, MSS, DCS |
| Landsat-3 | 5 Mar 1978 | 31 Mar 1983 | 915 km | 10:00 | Inactive | RBV, MSS, DCS |
| Landsat-4 | 16 Jul 1982 | 15 Jun 2001 | 705 km | 10:00 | Inactive | MSS, TM, GPS |
| Landsat-5 | 1 Mar 1984 | expected ≥ 2008 | 705 km | 10:00 | Operational (partially) | MSS, TM, GPS |
| Landsat-6 | 5 Oct 1993 | Failed at launch | - | - | Inactive | ETM |
| Landsat-7 | 15 Apr 1999 | expected ≥ 2009 | 705 km | 10:00 | Operational | ETM+ |
| NMP EO-1 | 21 Nov 2000 | expected ≥ 2007 | 705 km | 10:15 | Operational | ALI, LAC, Hyperion |
| LDCM | ~ 2010 | N/A | TBD | TBD | Being studied | OLI |

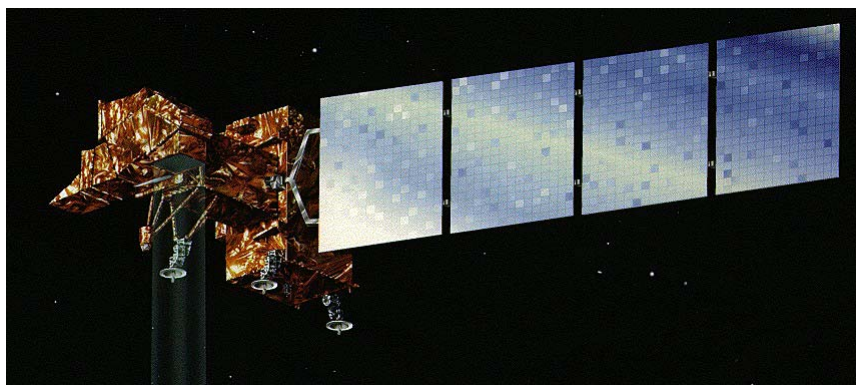


Fig. 4.3.3 – Sketch view of Landsat-7.

Landsat instruments

- **RBV (Return-Beam Vidicon camera)** [Landsat-1/2/3] consisted in three co-aligned cameras, one for each channel centred on 0.53, 0.63 and 0.76 μm respectively. Frames of 185 x 185 km^2 , resolution 40 m.
- **MSS (Multi-Spectral Scanner)** [Landsat 1 to 5] was a 4-channel radiometer (0.55, 0.65, 0.75 and 0.95 μm). Swath 185 km, resolution 80 m.
- **TM (Thematic Mapper)** [Landsat-4/5] had 7 channels, 6 in SW (0.48, 0.56, 0.66, 0.83, 1.65, 2.20 μm) with resolution 30 m, one in IR (10.4-12.5 μm) with resolution 120 m. Swath 185 km.
- **ETM (Enhanced Thematic Mapper)** [Landsat-6] was similar to *TM*, but a panchromatic channel (0.5-0.9 μm) was added, with resolution 15 m.
- **ETM+ (Enhanced Thematic Mapper +)** [Landsat-7] is similar to *ETM*, but the resolution of the IR channel has been improved to 60 m.
- **DCS (Data Collection System)** [Landsat-1/2/3] was to receive and relay data from ground-based stations.
- **GPS (Global Positioning System)** [Landsat-4/5] was a receiver for precise navigation and orbit determination.

The **NMP EO-1 (New Millennium Program – Earth Observing -1)** mission is aimed at developing extremely advanced technologies for more performing and less resource-demanding instruments. The instruments are:

- **ALI (Advanced Land Imager)**, similar to *ETM+* except that the IR channel is dropped and three channels are added (0.44, 0.87 and 1.25 μm). The resolution of the panchromatic channel is 10 m. As compared to *ETM+*, mass and electrical power are reduced by a factor 4.
- **LAC (LEISA Atmospheric Corrector)** (*LEISA = Linear Etalon Imaging Spectrometer Array*), supportive of *ALI* for providing atmospheric correction: same 185 km swath, 250 m resolution, spectral coverage 0.89-1.6 μm with spectral resolution 2-6 nm.
- **Hyperion**, an hyperspectral imager with 220 channels of 10 nm bandwidth in the range 0.4-2.5 μm , resolution 30 m over a narrow 7.5 km swath.

An **LDCM (Landsat Data Continuity Mission)** is now being defined. It will consist of a new dedicated satellite series. The notion has been introduced of:

- **OLI (Operational Land Imager)**, currently thought after *ALI*.

Instrument sheets from this Section 4.3.2 are provided for *MSS*, *TM*, *ETM+*, *ALI*, *OLI* (assumed similar to *ALI*), *LEISA* and *Hyperion*.

For the purpose of data access in support of GOS, Landsat data can be received in real-time only by appointed ground station. Otherwise, data are distributed by the **EROS Data Centre (EDC) of the US Geological Survey (USGS)**. Data latency may be less than 24 h for data acquired at the Landsat Ground Station, to 1-2 weeks for data acquired at other USGS stations. Other distributors exist, including ESA/ESRIN.

4.3.3 The EOS programme

The original aim of the **Earth Observing System (EOS)** was based on four series of three satellites each to cover 15 years of continuous observations: a multi-purpose mission in a.m. orbit (AM), one in p.m. orbit (PM), a chemistry mission (CHEM) and an altimetry mission (ALT). With the advent of NPOESS, that took over the long-term continuity of operational missions, EOS has been re-structured as one-shot missions, three large (Terra, Aqua and Aura), others single-payload. This Section includes the three main missions and a selection of others (SeaStar, QuickSCAT, Coriolis and ICESat), considered most relevant for the GOS. The chronology of these missions is reported in **Table 4.3.3**. Ocean altimetry missions are reported under Section 4.3.5. **Figures 4.3.4, 4.3.5 and 4.3.6** provide sketch views of EOS-Terra, EOS-Aqua and EOS Aura respectively.

Table 4.3.3 – Chronology of the EOS programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST/incl. | Status (Sept 2006) | Instruments |
|-----------|-------------|----------------------|--------|-----------|--------------------|--|
| SeaStar | 1 Aug 1997 | expected \geq 2007 | 705 km | 12:00 d | Operational | SeaWiFS |
| QuikSCAT | 19 Jun 1999 | expected \geq 2007 | 803 km | 06:00 d | Operational | SeaWinds |
| EOS-Terra | 18 Dec 1999 | expected \geq 2007 | 705 km | 10:30 d | Operational | MODIS, CERES, ASTER, MISR, MOPITT |
| EOS-Aqua | 4 May 2002 | expected \geq 2008 | 705 km | 13:30 a | Operational | MODIS, CERES, AIRS, AMSU-A, HSB, AMSR-E, |
| Coriolis | 6 Jan 2003 | expected \geq 2008 | 830 km | 06:00 d | Operational | WindSat |
| ICESat | 12 Jan 2003 | expected \geq 2007 | 600 km | 94° | Operational | GLAS |
| EOS-Aura | 15 Jul 2004 | expected \geq 2010 | 705 km | 13:45 a | Operational | HIRDLS, EOS-MLS, OMI, TES |



Fig. 4.3.4 - Sketch view of Terra.

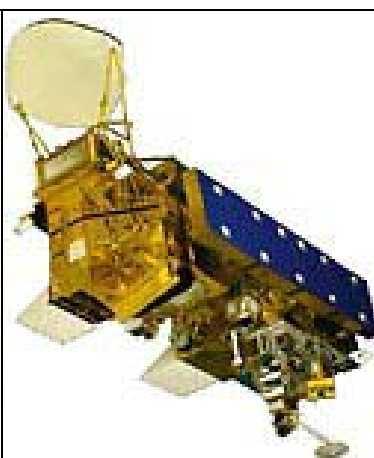


Fig. 4.3.5 - Sketch view of Aqua.

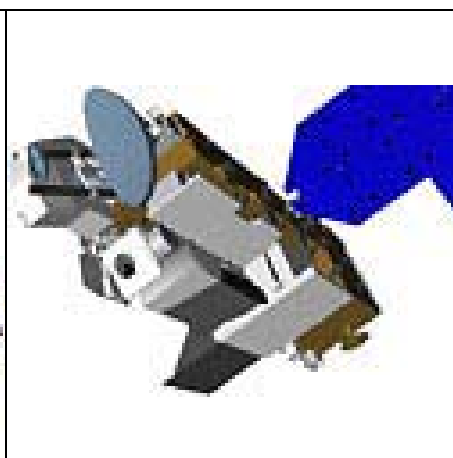


Fig. 4.3.6 - Sketch view of Aura.

SeaStar was launched to provide continuity of ocean colour observation after the end of the Nimbus-7 CZCS (1994). It was actually a NASA data-purchase undertaking, since the satellite, also known as **OrbView-2**, was owned by the *OrbImage* Company. It has a single payload:

- **SeaWiFS (Sea-viewing Wide Field-of-view Sensor)**, 8-channel radiometer, range 400-890 nm, narrow bandwidths to observe ocean colour and aerosol; resolution 1.1 km s.s.p., swath 2800 km.

QuikSCAT (Quick Scatterometer Mission) was launched to provide continuity to the NASA Scatterometer (NSCAT) of ADEOS-I, failed in 1997. The instrument, considerably different from NSCAT, was also re-flown on ADEOS-II (2002-2003). Single payload:

- **SeaWinds**, radar scatterometer in Ku-band (13.4 GHz) with two beams and conical scanning so as to view each spot four times under different angles. Resolution 50 km, swath 1800 km.

Coriolis was launched as a proof-of concept mission, to demonstrate that wind direction, in addition to wind speed, can be observed by passive radiometry by exploiting multi-polarisation instead of active system (radar). In fact, it is considered as a risk-reduction mission for the NPOESS CMIS. Payload:

- **WindSat**, 22-channel MW radiometer with frequencies 6.8, 10.7, 18.7, 23.8 and 37 GHz and full polarimetric observation (i.e. 6 polarisations) at frequencies 10.7, 18.7 and 37 GHz and two polarisations at frequencies 6.8 and 23.8 GHz. Resolution 25 km, swath 1000 km. Of course, WindSat can also observe sea-surface temperature, precipitation, ice, snow and soil moisture index.

ICESat (Ice, Cloud and land Elevation Satellite) was launched to measure polar ice elevation with unprecedented accuracy as allowed by using a laser altimeter. Of course, it can also measure cloud top height and land elevation. Payload:

- **GLAS (Geoscience Laser Altimeter System)**, a dual-wavelength lidar, 532 and 1064 nm; nadir-only view with sampling at 170 m intervals for along-track near-continuous profiling.

Cross-track, in 183 days (the orbital repeat cycle) global coverage is achieved with 15-km gaps at the equator and 2.5 km gaps at 80° latitude.

EOS-Terra is a multi-purpose satellite to serve most environmental areas. Payloads:

- **MODIS (Moderate-resolution Imaging Spectro-radiometer)**, 36-channel radiometer covering the range 0.4-14.4 μm , split in several groups with different resolution (250, 500 and 1000 m), bandwidths and radiometric accuracy, depending on the addressed application (ocean colour, vegetation, clouds, aerosol, atmosphere). Swath 2330 km.
- **CERES (Clouds and the Earth's Radiant Energy System)**, actually two sub-units to scan cross-track and conically for bi-directional reflectance. 3 broad-band channels (0.3-100 μm , 0.3-5.0 μm , 8-12 μm). Resolution 20 km s.s.p., swath 3000 km.
- **ASTER (Advanced Spaceborne Thermal Emission and Reflection radiometer)**, joint USA-Japan instrument. 14-channel radiometer covering the range 0.5-11.7 μm , with 3 channels in VNIR (resolution 15 m), 6 in SWIR (resolution 30 m) and 5 in TIR (resolution 90 m). Swath 60 km.
- **MISR (Multi-angle Imaging Spectro-Radiometer)**, using 9 cameras to view under 9 different along-track angles (nadir, $\pm 26.1^\circ$, $\pm 45.6^\circ$, $\pm 60.0^\circ$ and $\pm 70.5^\circ$), each view in 4 channels (0.446, 0.558, 0.672 and 0.866 μm), to measure the BRDF (Bidirectional Reflectance Distribution Function). Resolution selectable among 275, 550 and 1.1 km s.s.p., swath 360 km.
- **MOPITT (Measurement Of Pollution In The Troposphere)**, provided by Canada. Gas correlation spectrometer in bands around 2.26, 2.33 and 4.62 μm to measure CO profile and CH₄ total-column. Resolution 22 km s.s.p., swath 640 km.

EOS-Aqua primarily serves operational meteorology by advanced instrumentation. Payload:

- **MODIS**, same as on EOS-Terra.
- **CERES**, same as on EOS-Terra.
- **AIRS (Atmospheric Infra-Red Sounder)**, 2378-channel grating spectrometer in the range 3.74-15.4 μm with resolving power ($\lambda/\Delta\lambda$) 1200 (0.55 cm^{-1} at 15 μm), for temperature, humidity and ozone profiling; supporting 4 channels in the range 0.4-1.0 μm . Resolution 13.5 km s.s.p., swath 1650 km.
- **AMSU-A**, same as on NOAA-15/19 and Metop.
- **HSB (Humidity Sounder for Brazil)**, provided by Brazil: 4-channel MW radiometer, 3 in the H₂O 183 GHz band, one at 150 GHz, resolution 13.5 km s.s.p., swath 1650 km.
- **AMSR-E (Advanced Microwave Scanning Radiometer - EOS)**, provided by Japan, modified from AMSR on ADEOS-II: 12-channel MW radiometer, 6 frequencies (6.9, 10.7, 18.7, 23.8, 36.5 and 89 GHz) all with two polarisations, for sea-surface temperature, sea-surface wind speed, precipitation, ice, snow, soil moisture index. Resolution ranging from 5 km (at 89 GHz) to 60 km (at 6.9 GHz), conical scanning, swath 1400 km.

EOS-Aura is dedicated to atmospheric chemistry. Payload:

- **HIRDLS (High-Resolution Dynamics Limb Sounder)**, joint USA-UK instrument. 21-channel radiometer covering the range 6-18 μm . Species: CFC-11, CFC-12, CH₄, ClONO₂, H₂O, HNO₃, N₂O, N₂O₅, NO₂, O₃, temperature and aerosol. Limb sounding also including scanning at 6 different azimuth angles for a swath of 2000-3000 km; vertical resolution 1 km in the range 10-100 km.
- **MLS (Microwave Limb Sounder)**, improved from MLS on UARS. Five bands at frequencies 118 GHz (9 channels), 190 GHz (6 channels), 240 GHz (7 channels), 640 GHz (9 channels) and 2500 GHz (5 channels) Species: BrO, ClO, CO, H₂O, HCl, HCN, HNO₃, HO₂, HOCl, N₂O, O₃, OH, SO₂, temperature and pressure. Vertical resolution 1.5 km in the range 5-120 km.
- **OMI (Ozone Monitoring Instrument)**, provided by The Netherlands and Finland. A 1560-channel grating imaging spectrometer covering the spectral range 270-500 nm with spectral

resolution 0.4-0.6 nm. Species: BrO, NO₂, O₃, OClO, SO₂ and aerosol. Cross-nadir electronic scanning, resolution 13 x 24 km², swath 2600 km; zoom mode available, with resolution 13 x 12 km² and swath 725 km.

- **TES (Tropospheric Emission Spectrometer)**, imaging interferometer for both limb and cross-nadir scanning, covering the spectral range 3.3-15.4 μm with a spectral resolution of 0.06 cm⁻¹ (cross-nadir) or 0.015 cm⁻¹ (in limb mode). Species: CFC-11, CFC12, CH₄, CO, CO₂, H₂O, HCl, HDO, HNO₃, N₂, N₂O, NH₃, NO, NO₂, O₃, OCS, SO₂ and aerosol. Limb mode: vertical resolution 2.3 km in the range 0-37 km; cross-nadir: horizontal resolution 0.53 x 53 km² s.s.p. over a 5.3 x 8.5 km² area that can be pointed anywhere within a swath of 885 km.

Instrument sheets are provided in Annex A3.2 for all instruments described in this Section 4.3.3.

All data from NASA missions are available from **EOSDIS (Earth Observing System - Data and Information System)** with variable delay from observation taking. For the purpose of the Global Observing System (GOS), the following real-time or near-real time access modes are noted:

- SeaWiFS: may be received in real-time by a HRPT station upon authorisation granted by ORBIMAGE or NASA;
- QuickSCAT data are distributed by NOAA within 3 hours from observation;
- Coriolis/WindSat data are distributed by NOAA within 3 hours from observation;
- ICESat data are distributed by the US National Snow and Ice Data Center (NSIDC);
- EOS-Terra provides real-time access to MODIS data in X-band by authorised stations;
- EOS-Aqua provides real-time access to all sensor data in X-band by authorised stations;
- EOS-Aura could in principle be received in real-time in X-band.

4.3.4 The Earth System Science Pathfinder programme

The ESSP programme is based on single-shot satellites selected at ~ 2-year intervals according to the principle “small, fast, cheap”. Missions are selected for process study purposes. **Table 4.3.4** provides essential information on the missions so far selected (in order of expected launch date):

- **GRACE (Gravity Recovery and Climate Experiment)** (USA-Germany)
- **CALIPSO (Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observations)** (USA-France)
- **CloudSat**
- **OCO (Orbiting Carbon Observatory)**
- **Aquarius** (USA-Argentina)

Table 4.3.4 – List of selected ESSP missions as of September 2006

| Satellite | Launch | Life | Orbit | Main instruments | Mission |
|-----------------------------|-------------|------|--|--|---|
| GRACE (2 satellites) | 17 Mar 2002 | 5 y | 2 sats dephased 100-500 km, height 300-500 km, 89° | SuperSTAR Accelerometers, K-band satellite-to-satellite ranging | Gravity field anomalies and accurate geoid |
| CALIPSO | 28 Apr 2006 | 3 y | Sunsynchronous, 705 km, LST 13:30 a | Two-wavelength (532 and 1024 nm) polarisation-sensitive lidar, 3-channel imager (8.7, 10.5 and 12 μm), wide-field camera | Cloud microphysics and radiative properties, cirrus clouds, aerosol |
| CloudSat | 28 Apr 2006 | 2 y | Sunsynchronous, 705 km, LST 13:30 a | 94 GHz Cloud Profiling Radar (CPR) | Cloud profile and radiative properties |
| OCO | 2008 | 2 y | Sunsynchronous, 705 km, LST 13:15 a | 3 grating spectrometers covering bands 0.76, 1.61 and 2.06 μm | CO ₂ profile |
| Aquarius | 2009 | 3 y | Sunsynchronous, 657 km, LST 06:00 d | L-band radiometer/scatterometer with polarimetric capability | Global sea-surface salinity |

Data from ESSP missions may be released for use within the GOS to improve modelling and parameterisation in NWP.

4.3.5 Selection of other missions relevant to GOS

In this Section a selection of other missions relevant to GOS are reported, often implemented through international cooperation, mainly bilateral. The following areas are considered:

- observation of precipitation
- sounding missions exploiting GPS radio-occultation

whereas ocean altimetry missions in cooperation with CNES are reported under Section 4.5.

Table 4.3.5 reports the main features of the missions that will be shortly described.

Table 4.3.5 – Chronology of international missions (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST/incl. | Status (Sept 2006) | Instruments |
|------------------------------|-------------|----------------------|--------|-----------|--------------------|----------------------------------|
| TRMM | 27 Nov 1997 | expected \geq 2008 | 402 km | 35° | Operational | PR, TMI, LIS, VIRS, CERES |
| GPM "core" | 2012 | expected \geq 2017 | 407 km | 65° | Planned | DPR, GMI |
| Microlab-1 | 1 Apr 1995 | 2001 | 785 km | 70° | Inactive | OTD, GPS/MET |
| SAC-C | 21 Nov 2000 | 2005 | 705 km | 10:15 d | Inactive | GOLPE + others |
| CHAMP | 15 Jul 2000 | expected \geq 2006 | 450 km | 87° | Operational | BlackJack + others |
| COSMIC (6 satellites) | 14 Apr 2006 | expected \geq 2010 | 800 km | 71° | Operational | IGOS |

4.3.5.1 TRMM and the GPM

The **Tropical Rainfall Measuring Mission (TRMM)** is implemented in cooperation of USA and Japan as a main contribution to the Global Energy and Water-cycle Experiment (GEWEX). It carries the following instruments:

- **PR (Precipitation Radar)**, provided by Japan. An imaging radar operating at 13.8 GHz to measure precipitation profiles. Resolution 4.3 km s.s.p. (horizontal), 250 m (vertical); electronic scanning, swath 215 km.
- **TMI (TRMM Microwave Imager)**, derived from the DMSP SSM/I. Five frequencies (10.65, 19.35, 21.3, 37.0 and 85.5 GHz), all with two polarisations except 21.3 GHz. Conical scanning, resolution ranging from 6 km (at 85.5 GHz) to 50 km (at 10.65 GHz), swath 760 km.
- **LIS (Lightning Imaging Sensor)**, CCD camera with special filter at 777.4 nm (O-1 line) to detect lightning intensity and flash rate during the \sim 90 s when a spot is imaged onto the CCD. Resolution 4 km s.s.p. (horizontal), 2 ms (temporal), swath 600 km.
- **VIRS (Visible and Infra-Red Scanner)**, derived from AVHRR. 5-channel radiometer (0.63, 1.6, 3.75, 10.8 and 12 μ m), resolution 2 km s.s.p., swath 720 km.
- **CERES (Clouds and the Earth's Radiant Energy System)**, simplified from the one on EOS Terra and Aqua in so far it only includes the cross-track scanning unit. 3 broad-band channels (0.3-50 μ m, 0.3-5.0 μ m, 8-12 μ m), resolution 10 km s.s.p., swath 1800 km.

The **GPM (Global Precipitation Measurement mission)** is being prepared within an international context. Its objective is to provide global coverage of precipitation data at 3-hour intervals, the basic instrument being a MW conical scanning radiometer of the TRMM-type (**TMI**) or better. Due to the limited swath of conical scanners, the 3-h frequency requires 8 satellites in regularly de-phased near-polar orbits. Of these, three will consist of the NPOESS satellites, specifically by the **CMIS** radiometer, whose performance exceeds by far the minimum requirement. Other contributions are being considered by other space agency (one by NASA itself). In addition, the constellation include a "**GPM core**" satellite that provides high-quality information to "calibrate" the other satellites of the constellation, being equipped with:

- **DPR (Dual-frequency Precipitation Radar)**, to be provided by Japan. Two frequencies, 13.6 and 35.55 GHz for heavy and light precipitation respectively. Resolution 5.0 km s.s.p. (horizontal), 250 m (vertical); electronic scanning, swath 245 km at 13.6 GHz, 120 km at 35.55 GHz.
- **GMI (GPM Microwave Imager)**, with improved resolution in respect of **TMI**. Five frequencies (10.65, 18.7, 23.8, 36.5 and 89 GHz), all with two polarisations except 23.8 GHz. Option for channels at 166.5 GHz (two polarisations) and 183 GHz (two channels) are considered. Conical scanning, resolution ranging from 5.5 km (at 89 GHz) to 25 km (at 10.65 GHz), swath 850 km.

Instrument sheets are provided in Annex A3.2 for all instruments described in this Section 4.3.5.1.

For the purpose of data access in support of GOS, the current practise is to make available precipitation products on ftp sites. The latency time is few hours.

4.3.5.2 Radio-occultation sounding missions

Microlab-1, thereafter re-named **OrbView-1**, carried out the demonstration of the GPS radio-occultation technique to observe high-vertical-resolution temperature-humidity-pressure profiling. Payload:

- **GPS/MET (Global Positioning System / Meteorology)**, collecting about 200 occultation events/day by tracking GPS satellites during setting (antenna pointing aft-, i.e. anti-velocity).
- **OTD (Optical Transient Detector)**, precursor of the TRMM *LIS* for mapping lightning events. CCD camera with special filter at 777.4 nm. Resolution 10 km s.s.p. (horizontal), 2 ms (temporal), swath 1300 km.

On the Argentinean **SAC-C (Satélite de Aplicaciones Científicas - C)**, carrying several instruments, NASA provided:

- **GOLPE (GPS Occultation and Passive reflection Experiment)**, improved in respect of *GPS/MET*, collecting about 500 occultation events/day by tracking GPS satellites during both setting and rising (two antennas pointing aft- and fore-).

On **CHAMP (Challenging Mini-Satellite Payload)**, a Germany-USA cooperative mission carrying several instruments, NASA provided:

- **BlackJack**, same instrument as *GOLPE* except that there is a single occultation antenna that points aft- (thus for setting) collecting about 230 occultation events/day.

To greatly increase the number of occultation events per day, **COSMIC (Constellation Observing System for Meteorology, Ionosphere & Climate)** has been launched in April 2006. The constellation includes 6 satellites launched at once, thereafter displaced in more orbital planes in a one-year time span. *COSMIC* is a cooperative USA-Taiwan mission, also called **FormoSat-3**. The payload is:

- **IGOS (Integrated GPS Occultation Receiver)**, based on *BlackJack* with antennas pointing fore- and aft- for both setting and rising occultation events (about 500 events/day per satellite). With 6 satellites, 3000 occultations/day are collected, providing a daily global coverage with an average sampling distance of 400 km.

Instrument sheet relative to this Section 4.3.5.2 is provided in Annex A3.2 only for *BlackJack*, that is the basis for all configurations, generally differing only for the antennas number and accommodation.

For the purpose of data access in support of GOS, the current practise is to make available the products on ftp sites. The latency time is several days.

4.4 The JAXA programmes

JAXA (Japan Aerospace Exploration Agency) and the preceding **NASDA (National Space Development Agency)**, in addition to supporting the Japan Meteorological Agency (JMA) for implementing the GMS and MTSAT programmes (see Section 2.4), have developed remote sensing satellites starting with MOS-1 in 1987. Since then, several missions have been implemented, each one building on the previous one, with evolutionary payloads. **Table 4.4.1** reports the chronology of NASDA/JAXA remote sensing satellites. **Fig. 4.4.1** shows the aspect of ADEOS-2. In addition, Japan has provided instruments and/or launch service for several bilateral missions such as:

- TRMM (*PR* and launch service) (see Section 4.3.5.1)
- *ASTER* on EOS-Terra (see Section 4.3.3)
- *AMSR-E* on EOS-Aqua (see Section 4.3.3);

and plans to provide:

- the *Dual-frequency Precipitation Radar* on the “core” GPM satellite (see Section 4.3.5.1)
- the *Cloud Radar* on Earth-CARE (see Section 4.2.3).

Table 4.4.1 – Chronology of NASDA/JAXA remote sensing satellites (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST | Status (Sept 2006) | Instruments |
|-------------|--------------------|--|---------------|----------------|--------------------|--|
| MOS-1 | 19 Feb 1987 | 29 Nov 1995 | 908 km | 10:15 d | Inactive | MESSR, VTIR, MSR |
| MOS-1B | 7 Feb 1990 | 25 Apr 1996 | 908 km | 10:33 d | Inactive | MESSR, VTIR, MSR |
| JERS | 11 Feb 1992 | 11 Oct 1998 | 568 km | 10:45 d | Inactive | SAR, OPS |
| ADEOS-1 | 17 Aug 1996 | 30 Jun 1997 | 797 km | 10:30 d | Inactive | OCTS, AVNIR, NSCAT, TOMS, POLDER, IMG, ILAS, RIS |
| ADEOS-2 | 14 Dec 2002 | 25 Oct 2003 | 812 km | 10:30 d | Inactive | AMSR, GLI, SeaWinds, ILAS-II, POLDER, DCS |
| ALOS | 24 Jan 2006 | expected \geq 2010 | 692 km | 10:30 d | Operational | PRISM, AVNIR-2, PALSAR |
| GOSAT | Aug 2008 | expected \geq 2013 | 666 km | 13:00 d | Planned | TANSO-FTS, TANSO-CAI |

**Fig. 4.4 - Sketch view of ADEOS-2.**

Two flight models of **MOS (Marine Observatory Satellite)**⁵ were launched, **MOS-1** and **MOS-1B**, equipped with:

- **MESSR (Multi-spectral Electronic Self-Scanning Radiometer)**, two parallel 4-channel VIS/NIR push-broom instruments, for vegetation observation (0.51-0.59, 0.61-0.69, 0.73-0.80 and 0.80-1.10 μm), resolution 50 m, swath 185 km for the coupled instruments.
- **VTIR (Visible and Thermal Infrared Radiometer)**, 4-channel radiometer for cloud observation, resolution 0.9 km s.s.p. in channel 0.5-0.7 μm , and 2.7 km s.s.p. in channels 6.0-7.0, 10.5-11.5 and 11.5-12.5 μm ; swath 1500 km.
- **MSR (Microwave Scanning Radiometer)**, two-channel radiometer with frequencies 23.8 and 31.4 GHz for total-column water vapour over the ocean; resolution 23 km at 31 GHz, 32 km at 23 GHz, swath 320 km.

JERS (Japanese Earth Resources Satellite)⁶ was equipped with two rather important instruments:

- **SAR (Synthetic Aperture Radar)**, operating in L-band (1.275 GHz) best suited for soil moisture and ocean-surface small-scale features. Resolution 18 m, swath (side looking) 75 km, duty cycle ... %.
- **OPS (Optical Sensor)**, an 8-channel push-broom radiometer in the range 0.52 to 2.40 μm for vegetation type and land use; resolution 20 m, swath 75 km; one channel with fore-viewing (15.33°) for stereoscopy.

⁵ Original name: **Momo**, that means “Peach tree”.

⁶ Original name: **Fuyo**, a Japanese flower.

Two flight models of **ADEOS (Advanced Earth Observing Satellite)**⁷ were launched, equipped with many instruments to comply with a multi-purpose mission:

- **OCTS (Ocean Color and Temperature Scanner)** [ADEOS-1], evolution of *VTIR*: a 12-channels radiometer, 8 narrow-bandwidth in the range 0.40-0.89 μm for ocean colour and vegetation, 4 in the range 3.5-12.7 μm ; resolution 700 m s.s.p., swath 1400 km.
- **AVNIR (Advanced Visible and Near-Infrared Radiometer)** [ADEOS-1], evolution of *MESSR*: a 5-channel radiometer for vegetation (0.42-0.50, 0.52-0.60, 0.61-0.69, 0.76-0.89 and the panchromatic 0.52-0.69 μm), resolution 16 m (8 m the panchromatic); electronic scanning covering a swath of 80 km at s.s.p., possible to be pointed cross-track.
- **GLI (Global Imager)** [ADEOS-2], evolution of *OCTS*, a 36-channel spectroradiometer covering the range 0.38-12.0 μm , split in several groups with different resolution (250 and 1000 m), bandwidths and radiometric accuracy, depending on the addressed application (ocean colour, vegetation, clouds, aerosol, atmosphere). Swath 1600 km.
- **NSCAT (NASA Scatterometer)** [ADEOS-1], radar scatterometers for sea-surface wind provided by NASA, frequency 14 GHz, resolution 25 km or (for more accurate products) 50 km, two swaths of 600 km on each side cross-track.
- **SeaWinds** [ADEOS-2], radar scatterometers for sea-surface wind provided by NASA, operating in Ku-band (13.4 GHz) with two beams and conical scanning so as to view each spot four times under different angles. Resolution 50 km, swath 1800 km. Also flown as a single mission on the NASA QuickSCAT, still operational (see Section 4.3.3). See instrument sheet in Annex A3.2.
- **AMSR (Advanced Microwave Scanning Radiometer)** [ADEOS-2], 14-channel MW radiometer, 6 frequencies (6.9, 10.7, 18.7, 23.8, 36.5 and 89 GHz) all with two polarisations, plus two (50.2 and 53.8 GHz) with one polarisation; for sea-surface temperature and wind speed, precipitation, ice, snow, soil moisture. Resolution ranging from 5 km (at 89 GHz) to 60 km (at 6.9 GHz); conical scanning, swath 1600 km. Also flown on EOS-Aqua as *AMSR-E*, still operational (see Section 4.3.3). See instrument sheet in Annex A3.2.
- **POLDER (Polarization and Directionality of the Earth's Reflectances)** [ADEOS-1/2], provided by CNES: a 9-wavelength radiometer with narrow-bandwidths in the range 443-910 nm and three polarisations at three wavelengths for a total of 15 channels; for aerosol, ocean colour and vegetation. Resolution 6.5 km s.s.p., electronic scanning, swath 2200 km, more viewing angles.
- **TOMS (Total Ozone Mapping Spectrometer)** [ADEOS-1], provided by NASA: 6 channels in the range 310-380 nm, 1 nm bandwidth, for total-column ozone. Resolution 50 km, swath 2700 km. It was flown on Nimbus-7 (1978), Meteor-3-6 (1991) and as a dedicated mission, TOMS Earth Probe (1996) (see Section 4.3.1.1).
- **IMG (Interferometric Monitor for Greenhouse gases)** [ADEOS-1], operating in three spectral ranges, 3.3-4.3 μm , 4.3-5.0 μm and 5.0-16.7 μm , with spectral resolution 0.05 cm^{-1} (unapodised). Species: CFC-11, CFC12, CH₄, CO, CO₂, H₂O, HCl, HDO, HNO₃, N₂, N₂O, NH₃, NO, NO₂, O₃, OCS, SO₂ and aerosol. Resolution 8 km, nadir-only view.
- **ILAS (Improved Limb Atmospheric Spectrometer)** [*ILAS-I* on ADEOS-1, *ILAS-II* on ADEOS-II], *ILAS-I* had two grating spectrometers in the ranges 6.21-11.77 μm (44 channels) and 0.753-0.784 μm (1024 channels). Species: CFC-11, CH₄, H₂O, HNO₃, N₂O, NO₂, O₃ and aerosol. *ILAS-II* had two further bands in the ranges 3.0-5.7 μm (22 channels) and 12.78-12.85 μm (22 contiguous channels of spectral resolution 0.2 cm^{-1}). Further species: CFC-12 and ClONO₂. Limb sounder operating in sun occultation. Resolution: ~ 300 km (horizontal), 1 km (vertical) in the range 10-60 km.
- **RIS (Retroreflector In Space)** [ADEOS-1], corner cube reflector for atmospheric absorption measurement in the path ground-satellite-ground. Spectral range: 0.4-14 μm . Species: CFC-

⁷ Original name: *Midori*, that means "Green".

12, CH₄, CO, HNO₃, O₃ and aerosol. Observation obtained when the satellite flies over the laser station.

- **DCS (Data Collection System)** [ADEOS-2], joint NASDA/CNES development following the NOAA/POES DCS/Argos (see Section 3.2).

ALOS (Advanced Land Observing Satellite) is addressing land observation by advanced instruments:

- **PRISM (Panchromatic Remote-sensing Instrument for Stereo Mapping)**, a single-channel (0.52-0.77 μm) radiometer with three views, fore-, nadir and aft-, for stereoscopic imagery aiming at accurate Digital Elevation Model (DEM). Resolution 2.5 m, electronic scanning of a swath 35 km wide (70 km for the nadir observation). See instrument sheet in Annex A3.2.
- **AVNIR-2 (Advanced Visible and Near-Infrared Radiometer - 2)**, evolution of the ADEOS-1 AVNIR: a 4-channel radiometer for vegetation (0.42-0.50, 0.52-0.60, 0.61-0.69 and 0.76-0.89); resolution 10 m; electronic scanning covering a swath of 70 km at s.s.p., possible to be pointed cross-track. See instrument sheet in Annex A3.2.
- **PALSAR (Phased-Array L-band Synthetic Aperture Radar)**, evolution of SAR on JERS: an L-band SAR (1.27 GHz) for soil moisture and ocean-surface small-scale features. Several modes are possible by selecting polarisations, side pointing and consequently changing resolution and swath:
 - *high resolution mode* over a swath 40-70 km, with either 7-44 m resolution and single polarisation mode, or 14-89 m resolution and two polarisation modes;
 - *scanSAR mode* over a swath 250-350 km, with 100 m resolution and one polarisation mode;
 - *polarimetry mode* over a swath 30 km with resolution 24-89 m and four polarisation modes.
 The instrument duty cycle is 17.5 %. See instrument sheet in Annex A3.2.

GOSAT (Green-house gas Observing Satellite) is a mission specifically addressing key green-house gases for implementing the Kyoto protocol. Two instruments are foreseen:

- **TANSO-FTS. (Thermal And Near-infrared Sensor for carbon Observations - Fourier Transform Spectrometer)**, a 4-band interferometer (three in the range 0.75-2.1 μm, one in the range 5.5-14.3 μm), with spectral resolution 0.2 cm⁻¹ (0.5 cm⁻¹ in band 1 centred on 0.76 μm), to track CO₂, CH₄ and other species. Resolution 10.5 km, swath 790 km. See instrument sheet in Annex A3.2.
- **TANSO-CAI (Thermal And Near-infrared Sensor for carbon Observations - Cloud and Aerosol Imager)**, a pushbroom 4-channel narrow-band imager (380, 674, 870 and 1600 nm) to detect and correct the cloud and aerosol interference from TANSO-FTS. Resolution 0.5 km s.s.p. (1.5 km for channel 1600 nm), swath 1000 km. See instrument sheet in Annex A3.2.

For the purpose of data access in support of GOS, the following is noted. JAXA has organised a full scheme for ALOS data distribution. The instrument output data are collected through a Data Relay Satellite (240 Mbps) or by direct read-out (120 Mbps) to the JAXA Earth Observation Center (EOC) and several ALOS Data Nodes (ADN), ideally one in each continent. The ADN are also responsible for processing, distributing and archiving data in their area.

4.5 The CNES programmes

CNES has provided or provides instruments for several bilateral missions such as:

- *Argos* and *A-DCS* on POES (see Section 3.2) and *Metop/EPS* (see Section 3.5)
- the platform (*Proteus*) and the infrared imager for *CALIPSO* (see Section 4.3.4)
- *ScaRaB* on *Meteor-3-7* (see Section 3.6) and on *Resurs-O1-4* (see Section 4.7)
- *DORIS* on *Envisat* (see Section 4.2.2)
- *POLDER* on *ADEOS-1/2* (see Section 4.4)
- *IASI* on *Metop/EPS* (see Section 3.5).

To be fair with history, record should also be kept of:

- the initiating role of CNES for the *Meteosat* programme across years 1970-72;

- the EOLE mission in 1971 to study the southern hemisphere circulation at the altitude 10-15 km by constant-level balloons tracked by a data collection and location satellite.

We group here the CNES main Earth Observation programmes under two headings:

- land observation
- ocean and atmosphere missions.

4.5.1 Land observing missions

SPOT (Satellite Pour l'Observation de la Terre) is the main CNES Earth Observation programme, dated 1986 and progressively evolved both as platform and instrumentation (see **Fig. 4.5.1**). **Table 4.5.1** records the chronology of the SPOT programme and introduces its successor, **Pléiades**.

Table 4.5.1 – Chronology of CNES land observation missions (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST/incl. | Status (Sept 2006) | Instruments |
|---------------|--------------------|------------------------|---------------|----------------|---------------------------|--|
| SPOT-1 | 22 Feb 1986 | ??????? | 822 km | 10:30 d | ??????? | HRV |
| SPOT-2 | 22 Jan 1990 | expected ≥ 2006 | 822 km | 10:30 d | Partly operational | HRV, DORIS |
| SPOT-3 | 26 Sep 1993 | 14 Nov 1996 | 822 km | 10:30 d | Inactive | HRV, POAM-2, DORIS |
| SPOT-4 | 24 Mar 1998 | expected ≥ 2007 | 822 km | 10:30 d | Operational | HRVIR, Vegetation, POAM-3, SILEX, PASTEC, DORIS |
| SPOT-5 | 4 May 2002 | expected ≥ 2008 | 822 km | 10:30 d | Operational | HRG, HRS, Vegetation, DORIS |
| Pléiades-1 | end-2008 | expected ≥ 2013 | 694 km | 10:15 d | Under development | HR |
| Pléiades-2 | early 2010 | expected ≥ 2015 | 694 km | 10:15 d | Planned | HR |

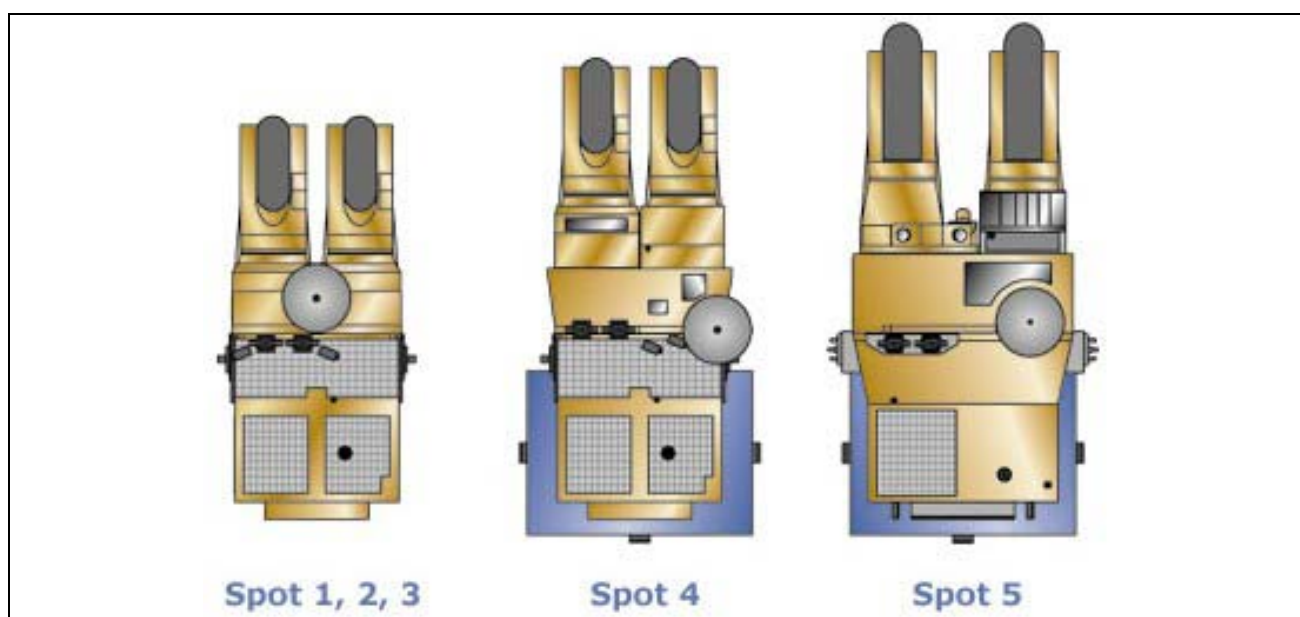


Fig. 4.5.1 – Evolution of the SPOT satellites.

The **SPOT instrumentation** has evolved with time, progressively improving the resolution and the operational flexibility, as described below:

- **HRV (Haut Résolution dans le Visible)** [SPOT-1/2/3] is actually composed of two bushroom scanning parallel instruments to image either two adjacent strips for a composite swath of 117 km (60 km + 60 km with some overlap), or two off-nadir strips up to 900 km apart, each one up to 80 km wide. The off-nadir pointing capability enables more frequent observation of a target area and possibility of stereoscopy in between successive orbits. Two operation modes are available: multispectral (0.50-0.59 μm , 0.61-0.68 μm , 0.79-0.89 μm) with 20 m resolution, or panchromatic (0.51-0.73 μm) with 10 m resolution. See instrument sheet in Annex A3.2.
- **HRVIR (Haut Résolution dans le Visible et l'Infra-Rouge)** [SPOT-4] improves over **HRV** in so far as a SWIR channel is added (1.58-1.75 μm) and the panchromatic function is provided

by the 0.61-0.68 μm channel. The multispectral and the panchromatic functions may now work at the same time. The two instruments can be pointed independently. See instrument sheet in Annex A3.2.

- **HRG (*Haut Résolution Géométrique*)** [SPOT-5] is a further improvement. The resolution of three basic channels (now 0.49-0.61 μm , 0.61-0.68 μm , 0.78-0.89 μm) is improved to 10 m whereas channel 1.58-1.75 μm remains 20 m. The panchromatic channel (now 0.49-0.69 μm) has now 5 m resolution and is doubled, with a small offset between the two images. On the ground, the two 5-m images are co-processed to obtain a 2.5-km image (*super-mode*). See instrument sheet in Annex A3.2.
- **HRS (*Haut Résolution Stéréoscopique*)** [SPOT-5] is designed to implement stereoscopy in-orbit instead of between successive orbits. The *HRV* panchromatic channel (0.51-0.73 μm) with 10 m resolution is re-introduced, with sampling at 5-m intervals along track. The swath is stretched to 120 km. Fore- and aft- images are taken, $\pm 20^\circ$ off-nadir. See instrument sheet in Annex A3.2.
- **Végétation** [SPOT-4/5] is designed for frequent medium-resolution observation at global scale. It has 4 channels similar to *HRVIR* and *HRG*: 0.43-0.47 μm , 0.61-0.68 μm , 0.78-0.89 μm and 1.58-1.75 μm , but the resolution is 1.15 km s.s.p. and the swath 2200 km, for near-daily global coverage. See instrument sheet in Annex A3.2.
- **POAM (*Polar Ozone and Aerosol Measurement*)** [SPOT-3/4], provided by the U.S. Naval Research Laboratory: a 9-channel limb sounding solar occultation radiometer in the range 350-1060 nm), slightly different in SPOT-3 (*POAM-2*) and SPOT-4 (*POAM-3*). Species: H_2O , NO_2 , O_2 , O_3 and aerosol. Vertical resolution 0.6 km, range 10-60 km. See instrument sheet in Annex A3.2.
- **SILEX (*Semiconductor Intersatellite Link Experiment*)** [SPOT-4], provided by ESA: a laser-based experimental satellite-to-satellite communication package (with the geostationary ARTEMIS).
- **PASTEC (*Technology Demonstration Passenger*)** [SPOT-4], a package of seven instruments for spacecraft and *in situ* environment monitoring.
- **DORIS (*Détermination d'Orbite et Radiopositionnement Intégrés par Satellite*)** [SPOT-2/3/4/5], for precision orbit determination.

The series to replace SPOT, **Pléiades**, is being developed. It will provide optical images in coordination with the Italian COSMO-SkyMed satellite constellation that will provide X-band SAR images, and the Argentinean SAOCOM satellite constellation equipped with L-band SAR. The Pléiades satellites will fly in formation to provide, thanks to the off-nadir pointing capability, the potential of observing any target area of the Earth's surface within one day. Each satellite will carry one main instrument:

- **HR (*Haut Résolution*)**, with 4 VIS/NIR channels (0.45-0.53 μm , 0.52-0.58 μm , 0.62-0.70 μm , 0.78-0.89 μm) at 2.8 m resolution s.s.p. and a panchromatic channels (0.48-0.90 μm) at 0.7 m resolution s.s.p., over a 20 km swath (when viewed at nadir). By combining all cross-track and along-track pointing capabilities it will be possible to implement composite images of 120 km x 120 km and stereoscopic images of 20 km x 300 km. See instrument sheet in Annex A3.2.

For the purpose of data access in support of GOS, the following is noted. SPOT data can be received in real time by X-band stations licensed by CNES and SPOT-Image. The data rate is 150 Mbps (for SPOT-5). Otherwise, a very efficient distribution system exists, managed by SPOT-Image.

It is supported by main CNES receiving stations in Kiruna and Toulouse and a network of over 20 local stations worldwide spread. To be noted that, due to the narrow instrument swaths and the pointing capability, observations of specific areas need to be booked in advance within the operations plan.

4.5.2 Ocean and atmosphere missions

Table 4.5.2 lists several CNES missions for atmosphere and ocean, generally implemented through bilateral or multi-lateral collaboration (all in the list, except PARASOL). **Fig. 4.5.2** shows the technological trend from TOPEX-Poseidon to Jason: equal performance with a satellite mass five times smaller. PARASOL, in **Fig. 4.5.3**, also is a mini-satellite.

Table 4.5.2 – Chronology of CNES ocean and atmosphere missions (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST/incl. | Status (Sept 2006) | Instruments |
|-----------------------|--------------------|--|---------|-----------|--------------------|-------------------------------|
| TOPEX-Poseidon | 10 Aug 1992 | expected \geq 2006 | 1336 km | 66° | Operational | NRA, SSALT, TMR, DORIS |
| JASON | 7 Dec 2001 | expected \geq 2008 | 1336 km | 66° | Operational | Poseidon-2, JMR, DORIS |
| OSTM (JASON-2) | 2008 | expected \geq 2015 | 1334 km | 66° | Planned | Poseidon-3, AMR, DORIS |
| PARASOL | 18 Dec 2004 | expected \geq 2007 | 705 km | 13:30 a | Operational | POLDER+ |
| Megha-Tropique | end-2009 | expected \geq 2014 | 867 km | 20° | Planned | MADRAS, SAPHIR, ScaRaB |

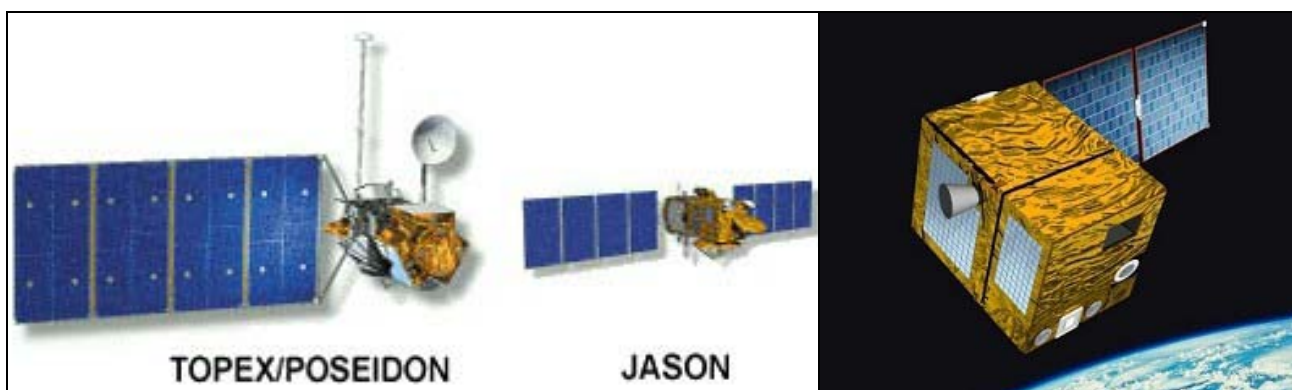


Fig. 4.5.2 - Size reduction from TOPEX-Poseidon to Jason.

Fig. 4.5.3 - Sketch view of PARASOL.

4.5.2.1 Ocean altimetry missions

TOPEX-Poseidon is a joint USA-France programme originated from merging the NASA *TOPEX* (*Topography Experiment*) and the CNES *Poseidon*. It carries the following instruments, complemented by a series of navigation facilities for precision orbitography:

- **NRA (NASA Radar Altimeter)** makes use of Ku-band (13.6 GHz) supported by S-band (5.3 GHz) for ionospheric correction. Resolution 25 km (Ku-band), 60 km (S-band), nadir-only view.
- **SSALT (Single-frequency Solid-state Altimeter)**, provided by CNES, makes use of Ku-band (13.65 GHz). It shares the same antenna of NRA, thus the resolution is 25 km. The antenna serves NRA 88 % of the time. SSALT and NRA have approximately the same accuracy (~ 2.5 cm), but the technology of SSALT enables large saving of mass and electrical power.
- **TMR (TOPEX Microwave Radiometer)**, provided by NASA, supports the altimeters by providing water vapour information for correction. 3 frequencies, 18, 21 and 37 GHz. Nadir-only view, resolution 35 km.
- **DORIS (Doppler Orbitography and Radiopositioning Integrated by Satellite)** and other navigation systems, essential for altimetry.

JASON (Joint Altimetry Satellite Oceanography Network) also is a NASA/CNES joint undertaking. The payload includes:

- **Poseidon-2**, provided by CNES, improves from SSALT by adding NRA capabilities: two frequencies, 13.5785 and 5.3 GHz, resolution 30 km (Ku-band), nadir-only view. With respect to NRA, performance is better (2 cm accuracy) and mass/power are reduced to one third.
- **JMR (JASON Microwave Radiometer)**, provided by NASA, is similar to TMR: channels at 18.7, 23.8 and 34 GHz, resolution 25 km at 23.8 GHz, nadir-only view.
- **DORIS** and other navigation systems for accurate orbitography.

OSTM (Ocean Surface Topography Mission), formerly known as *JASON-2*, is a joint NASA, CNES, NOAA and EUMETSAT programme. Payload:

- **Poseidon-3**, currently baselined as similar to *Poseidon-2*.
- **AMR (Advanced Microwave Radiometer)**, currently baselined as similar to *JMR*.
- **DORIS** and other navigation systems for accurate orbitography.

Instrument sheets relative to this Section 4.5.2.1 are provided in Annex A3.2 only for the JASON instruments *Poseidon-2* and *JMR*, representing the state-of-the-art.

For the purpose of data access in support of GOS, the current practise is to make available ocean topography products on ftp sites. The latency time is few hours for early products (wave height), several weeks for precision products (topography).

4.5.2.2 Atmospheric missions

PARASOL (Polarisation et Anisotropie des Réflectances au sommet de l'Atmosphère, couplées avec un Satellite d'Observation emportant un Lidar) is a mini-satellite co-flying in the so-called 'A-train', a satellite formation comprising EOS-Aqua and EOS-Aura (see Section 4.3.3), and CALIPSO, CloudSat and OCO (see section 4.3.4). It carries a single instrument, improved after *POLDER* on ADEOS-1/2:

- **POLDER (Polarization and Directionality of the Earth's Reflectances)**, a 9-wavelegth radiometer with narrow-bandwidths in the range 443-1020 nm and three polarisations at three wavelengths for a total of 15 channels; for aerosol, ocean colour and vegetation. Resolution 6 km s.s.p., electronic scanning, swath 2200 km, more viewing angles. See instrument sheet in Annex A3.2.

Data from PARASOL can be collected directly from CNES (<http://polder.cnes.fr>) for level 1 data and from Icare (<http://www-icare.univ-lille1.fr>) for level 2 and 3.

CALIPSO (Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observations) has been reported under the NASA mission (see Section 4.3.4) since it is part of the ESSP programme. CNES has provided the platform (*Proteus*) and the infrared imager.

Megha-Tropiques⁸ is a CNES/ISRO cooperative programme, contribution to the Global Precipitation Measurement mission (GPM, see section 4.3.5.1). It will provide frequent coverage of the tropical regions (each 1.5 hours, whereas the other 8 satellites of the GPM constellation, in sunsynchronous orbit, will provide global coverage at 3-hour intervals). ISRO will provide the platform and the launch service. The instruments will be:

- **MADRAS (Microwave Analysis & Detection of Rain & Atmospheric Structures)**, to be developed by ISRO with CNES contribution: a 5-frequencies (18.7, 23.8, 36.5, 89 and 157 GHz), 9-channel (double polarisation in all channels but 23.8 GHz) conical scanning microwave radiometer. Main objective: precipitation observation. Swath 1740 km. See instrument sheet in Annex A3.2.
- **SAPHIR (Sondeur Atmospherique du Profil d'Humidite Intertropicale par Radiometrie)**, a 6-channel MW radiometer in the 183.33 GHz band, for water vapour profiling. Cross-nadir scanning, 10 km s.s.p. resolution, 1700 km swath. See instrument sheet in Annex A3.2.
- **ScaRaB (Scanner for Radiation Budget)**, a 4-channel radiometer, two broad-band (0.2-4.0 μm and 0.2-50 μm), two narrow-band (0.55-0.65 μm and 10.5-12.5 μm), for Earth Radiation Budget at TOA. Resolution 40 km s.s.p., swath 3.200 km. See instrument sheet in Annex A3.2.

4.6 The ISRO programmes

ISRO is running the **IRS (Indian Remote-sensing Satellite)** programme since 1988. There are two series, IRS-1 and the follow-on IRS-P. **Table 4.6.1** records the chronology of the IRS

⁸ "Megha" is the Sanskrit word for "Cloud".

programme. **Fig. 4.6.1**, **Fig. 4.6.2** and **Fig. 4.6.3** show the aspects of three satellites of the IRS-P series.

Table 4.6.1 - Chronology of the IRS programme (in bold the satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST | Status (Sept 2006) | Instruments |
|-------------------------------|--------------------|------------------------|---------------|--------------|--------------------|------------------------------|
| IRS-1A | 17 Mar 1988 | 1992 | 904 km | 10:30 | Inactive | LISS-1, LISS-2-A/B |
| IRS-1B | 29 Aug 1991 | 2001 | 904 km | 10:30 | Inactive | LISS-1, LISS-2-A/B |
| IRS-1C | 28 Dec 1995 | ?????? | 817 km | 10:30 | ?????? | PAN, LISS-3, WiFS |
| IRS-1D | 29 Sep 1997 | ?????? | 784 km | 10:30 | | PAN, LISS-3, WiFS |
| IRS-1E = IRS-P1 | 20 Sep 1993 | Launch failed | - | - | Inactive | LISS-1, MEOS |
| IRS-P2 | 15 Oct 1994 | 1997 | 817 km | 10:30 | Inactive | LISS-2-M |
| IRS-P3 | 21 Mar 1996 | 2004 | 817 km | 10:30 | Inactive | WiFS, MOS, X-AE |
| IRS-P4 (OceanSat-1) | 26 May 1999 | expected ≥ 2007 | 720 km | 12:00 | Operational | OCM, MSMR |
| IRS-P5 (CartoSat-1) | 5 May 2005 | expected ≥ 2010 | 618 km | 10:30 | Operational | PAN-A, PAN-F |
| IRS-P6 (ResourceSat-1) | 17 Oct 2003 | expected ≥ 2009 | 817 km | 10:30 | Operational | LISS-3, LISS-4, AWiFS |
| OceanSat-2 | 2008 | expected ≥ 2013 | 720 km | 12:00 | Planned | OCM, MSMR |
| CartoSat-2 | 2010 | expected ≥ 2015 | 618 km | 10:30 | Planned | PAN-A, PAN-F |
| ResourceSat-2 | 2009 | expected ≥ 2014 | 817 km | 10:30 | Planned | LISS-3, LISS-4, AWiFS |

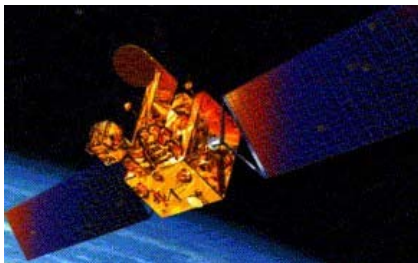


Fig. 4.6.1 - IRS-P4 (OceanSat)

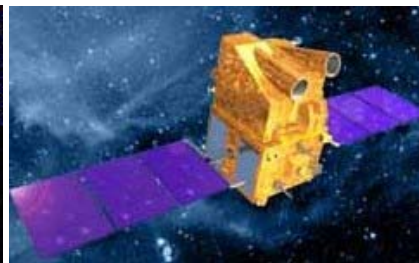


Fig. 4.6.2 - IRS-P5 (CartoSat)

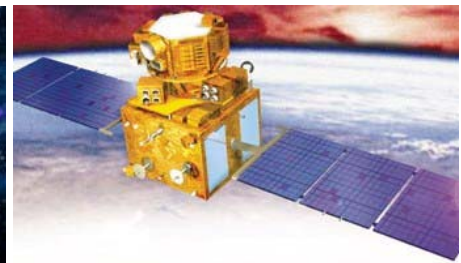


Fig. 4.6.3 - IRS-P6 (ResourceSat)

Instruments on IRS are shortly described in the following.

- LISS (Limb Imaging Self-Scanning Sensor)**, pushbroom radiometer for vegetation observation, has been flown in several versions. In **LISS-1** [IRS-1A, 1B, 1E/P1] and **LISS-2-A/B** [IRS-1A, 1B] there were 4 channels (0.46-0.52 μm , 0.52-0.59 μm , 0.62-0.68 μm and 0.77-0.86 μm). The resolution of LISS-1 was 72 m with a swath of 140 km, whereas LISS-2-A/B had 36 m and the same swath achieved by two parallel instruments (A and B) each with 36 km swath. **LISS-2M** [IRS-P2] combines the two instruments of LISS-2-A/B into a single one. In **LISS-3** [IRS-1C, 1D and P6] the “blue” channel 0.46-0.52 μm is replaced by a SWIR channels at 1.55-1.75 μm , with resolution 23 m (VNIR channels) and 70 m (SWIR channel), swath still 140 km. In **LISS-4** [IRS-P6] only the three VNIR channels 0.52-0.59 μm , 0.62-0.68 μm and 0.77-0.86 μm are retained, and the resolution is brought down to 5.8 m, with swath 24 km (multi-spectral) or 70 km (panchromatic). See instrument sheets of LISS-3 and 4 in Annex A3.2.
- PAN (Panchromatic Camera)** [IRS-1C, 1D], single-channel 0.50-0.75 μm , resolution 6 m with swath 70 km when pointing nadir, ≤ 10 m / 90 km when pointing side within a field of regard of 400 km. In IRS-P5 there are two instruments, **PAN-A** and **PAN-F**, view aft- and fore-respectively, for in-orbit stereoscopy. Pushbroom scanning with resolution 2.5 m, swath 30 km. See instrument sheet of PAN-A / PAN-F in Annex A3.2.
- WiFS (Wide Field Sensor)**, designed for vegetation indexes, was composed of two adjacent pushbroom cameras to cover a composite swath of 770 km with a resolution of 190 m. In IRS-1C and 1D there were two channels, 0.62-0.68 μm and 0.77-0.86 μm . In IRS-P3, a 1.55-1.75 μm channel was added.
- AWiFS (Advanced Wide Field Sensor)** [IRS-P6], is a further improvement. There are now four channels (0.52-0.59 μm , 0.62-0.68 μm , 0.77-0.86 μm and 1.55-1.75, i.e. the same as

LISS-3. Pushbroom scanning with resolution 56 m and swath 740 km. See instrument sheet in Annex A3.2.

- **MEOS (Monocular Electro-Optical Stereo Scanner)** [IRS-1E/P1] was a single-channel camera (0.57-0.70 μm) to take three simultaneous images, nadir, fore- and aft- for in-orbit stereoscopy. Pushbroom scanning resolution 150 m, swath 510 km. Not used because of launch failure.
- **MOS (Multispectral Opto-electronic Scanner)** [IRS-P3], provided by Germany, was an instrument complex for ocean colour, vegetation, aerosol and clouds. It included three subsystems: *MOS-A* with 4 channels in the oxygen band around 760 nm, *MOS-B* with 13 channels in the 408-1010 nm range, *MOS-C* with a channel at 1.6 μm . Resolution: *MOS-A* 1.5 km, *MOS-B* and *MOS-C* 0.5 km; swath 200 km.
- **OCM (Ocean Color Monitor)** [IRS-P4], an 8-channel radiometer with narrow bandwidths in the range 402-885 nm for ocean colour and aerosol. Pushbroom scanning, resolution 300 m, swath 1420 km. See instrument sheet in Annex A3.2.
- **MSMR (Multi-frequency Scanning Microwave Radiometer)** [IRS-P4], a 4-frequency, 8-channel MW radiometer (6.6, 10.65, 18 and 21 GHz, all with two polarisations) for surface temperature and wind and total-column water vapour over the sea. Conical scanning, resolution ranging from 27 km (at 21 GHz) to 85 km (at 6.6 GHz); swath 1360 km. See instrument sheet in Annex A3.2.
- **X-AE (X-ray Astronomy Experiment)** [IRS-P3], a package of two X-ray photon counters.

For the purpose of data access in support of GOS, the following is noted. IRS data can be received in real time by appointed X-band stations (data rate 150 Mbps), compatible with SPOT reception (minor modifications necessary). Otherwise, data are acquired and processed by the National Remote Sensing Agency (NRSA) and distributed by Antrix Corporation.

4.7 The RosKosmos programmes

Several R&D satellite series and single missions have been implemented and are planned by the Russian Space Agency, generally as Russia/Ukraine cooperation. For the purpose of GOS, we select here only the series **Resurs** (including the new Monitor-M), and **Okean** (including SICH). **Table 4.7.1** reports the chronology of the two programmes. **Fig. 4.7.1** shows the scheme of Resurs-O1 (similar to Meteor-3, see Fig. 3.6.1) and **Fig. 4.7.2** that one of Okean-O1.

Table 4.7.1 – Chronology of Resurs and Okean programmes (in bold satellites active in September 2006)

| Satellite | Launch | End of service | Height | LST/incl. | Status (Sept 2006) | Instruments |
|------------------|--------------------|--|---------------|----------------|--------------------|---|
| Resurs-O1-1 | 3 Oct 1985 | 11 Nov 1986 | 620 km | 10:15 a | Inactive | MSU-E, MSU-SK, SAR-Travers |
| Resurs-O1-2 | 20 Apr 1988 | 1 Jun 1999 | 650 km | 10:15 a | Inactive | MSU-E, MSU-SK |
| Resurs-O1-3 | 4 Nov 1994 | May 2001 | 675 km | 10:15 a | Inactive | MSU-E, MSU-SK, others |
| Resurs-O1-4 | 10 Jul 1998 | Jan 2002 | 835 km | 10:15 a | Inactive | MSU-E1, MSU-SK1, MP-900B, ScaRaB, others |
| Monitor-E | 26 Aug 2005 | expected \geq 2008 | 540 km | 10:30 a | Operational | PAN, MS |
| Resurs-DK | 15 Jun 2006 | expected \geq 2009 | 350 km | 70° | Operational | Geoton |
| Okean-O1-1 | 29 Jul 1986 | 1988 | 660 km | 82.5° | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor |
| Okean-O1-2 | 16 Jul 1987 | 1989 | 660 km | 82.5° | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor, Trasser |
| Okean-O1-3 | 5 Jul 1988 | 1990 | 660 km | 82.5° | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor, Trasser |
| Okean-O1-4 | 9 Jun 1989 | launch failed | - | - | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor |
| Okean-O1-5 | 28 Feb 1990 | 1991 | 660 km | 82.5° | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor |
| Okean-O1-6 | 4 Jun 1991 | 1993 | 660 km | 82.5° | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor |
| Okean-O1-7 | 11 Oct 1994 | 1996 | 660 km | 82.5° | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor |
| SICH-1 | 31 Aug 1995 | 1996 | 660 km | 82.5° | Inactive | RLSBO, RM-08, MWR, MSU-SK, Kondor |
| Okean-O-1 | 17 Jul 1999 | 2000 | 636 km | 82.5° | Inactive | RLSBO, MSU-M, MSU-SK, MSU-V, Delta-2D, R225, R-600, Trasser-O |
| SICH-1M | 1 Jan 1995 | launch failed | - | - | Inactive | RLSBO, RM-08, MSU-EU, MTVZA-OK |

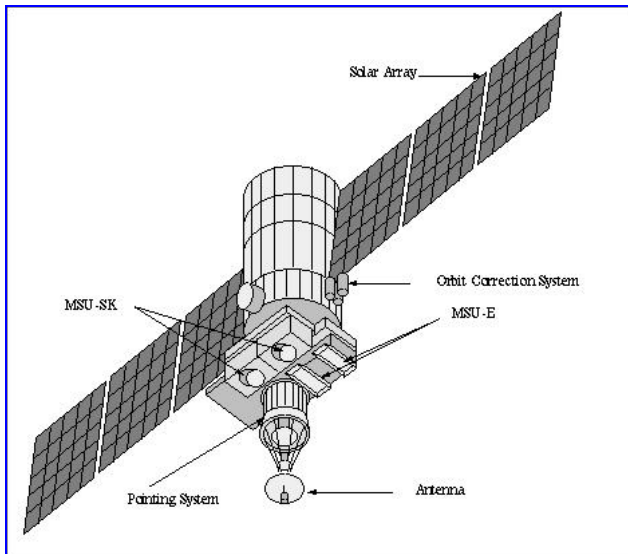


Fig. 4.7.1 - Scheme of Resurs-O1.

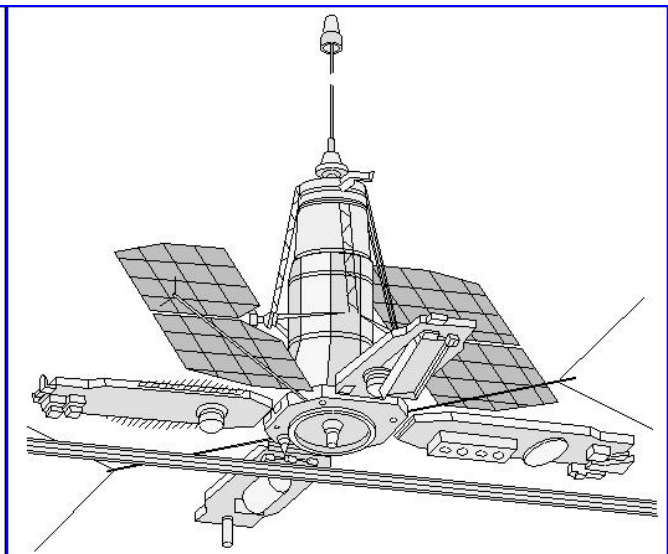


Fig. 4.7.2 - Scheme of Okean-O1.

The Resurs series

Resurs satellites are dedicated to land observation. The list of Table 4.7.1 omits the preceding series **Resurs-F1**, **Resurs-F2** and **Resurs-F1M**, about 60 satellites of the Kosmos family launched in the period 1979-1999. The instrumentation of the Resurs-O1 series and beyond is as follows:

- **Geoton** [Resurs-DK], a pushbroom radiometer with resolution 2-3 m when used in multi-spectral mode (0.5-0.6, 0.6-0.7 and 0.7-0.8 μm), 1 m when used in panchromatic mode (0.58-0.80 μm); swath 30 km possible to be addressed within an area of regard of 450 km. See instrument sheet in Annex A3.2.
- **MP-900B** [Resurs-O1-4], a TV camera with resolution 1.7 km, swath 2600 km.
- **MS (Multi-Spectral)** [Monitor-E], a 3-channel (0.54-0.59, 0.63-0.68 and 0.79-0.90 μm) pushbroom radiometer with resolution 20 m and swath 160 km possible to be addressed within an area of regard of 890 km. See instrument sheet in Annex A3.2.
- **MSU-E** [Resurs-O1 1, 2, 3], two side-to-side pushbroom radiometers with 3 channels (0.5-0.6, 0.6-0.7 and 0.8-0.9 μm), resolution 40 m and swath 45 km each, for a coupled swath of 80 km, or two 45-km side swaths possible to be addressed within an area of regard of 600 km. In **MSU-E1** [Resurs-O1-4] due to higher orbit, each radiometer had resolution 50 m and swath 60 km.
- **MSU-SK** [Resurs-O1 1, 2, 3], a conical scanning radiometer with 5 channels, four in VNIR (0.5-0.6, 0.6-0.7, 0.7-0.8, 0.8-1.1 μm), one in TIR (10.4-12.5 μm); resolution 170 m (VNIR) and 600 m (TIR); swath 600 km. In **MSU-SK1** [Resurs-O1-4] a 3.5-4.1 μm channel was added; due to higher orbit, the resolution was 210 m (VNIR) and 700 m (MWIR and TIR), the swath 700 km.
- **PAN (Panchromatic)** [Monitor-E], a single-channel (0.51-0.85 μm) pushbroom radiometer with resolution 8 m and swath 90 km possible to be addressed within an area of regard of 780 km. See instrument sheet in Annex A3.2.
- **SAR-Travers** [Resurs-O1-1], a Synthetic Aperture Radar with two frequencies, S-band (3.28 GHz) and L-band (1.28 GHz).
- **ScaRaB (Scanner for Radiation Budget)** [Resurs-O1-4], a CNES-provided radiometer with two broad-band (0.2-4.0 μm and 0.2-50 μm) and two narrow-band (0.5-0.7 μm and 10.5-12.5 μm) channels; resolution 60 km, swath 3200 km. To be re-flown on Megha-Tropiques. See instrument sheet in Annex A3.2.

The Okean series

Okean satellites are dedicated to ocean observation. The list of Table 4.7.1 omits the preceding series **Okean-E** and **Okean-OE**, 4 satellites of the Kosmos family launched in the period 1979-1984. The instrumentation of the Okean-O1 series and beyond is as follows:

- **Delta-2D** [Okean.O-1], 4-frequencies / 8-channel MW radiometer (6.9, 13.0, 22.3 and 37.5 GHz all with two polarisations); conical scanning, resolution ranging from 20 km (at 37.5 GHz) to 100 km (at 6.9 GHz), swath 1130 km.
- **Kondor** [all Okean-O1 satellites and SICH-1]: data collection system.
- **MSU-EU** [SICH-1M], a 3-channel (0.50-0.59, 0.61-0.69 and 0.79-0.92 μm) pushbroom radiometer with resolution 30 m and swath 48 km possible to be addressed within an area of regard of 750 km.
- **MSU-M** [Okean-O-1], 4-channel radiometer (0.5-0.6, 0.6-0.7, 0.7-0.8, 0.8-1.1 μm) for multi-purpose imagery; resolution 1.5 km, swath 1900 km
- **MSU-SK** [all Okean satellites and SICH-1]: a conical scanning radiometer with 5 channels, four in VNIR (0.5-0.6, 0.6-0.7, 0.7-0.8, 0.8-1.1 μm), one in TIR (10.4-12.5 μm); resolution 170 m (VNIR) and 600 m (TIR); swath 600 km. Same as for the Resurs series.
- **MSU-V** [Okean-O-1], 8-channel pushbroom radiometer for vegetation mapping; 5 in VNIR in the range 0.45-1.0 μm with resolution 50 m; 2 in SWIR with resolution 100 m (at 1.6 μm) and 300 m (at 2.2 μm), one in TIR (10.6-12.0) with resolution 250 m; swath 200 km.
- **MTVZA-OK** [SICH-1M], a complex of a MW imaging-sounding radiometer (**MTVZA**, see Section 3.6) and a 5-channel VIS/IR radiometer (0.37-0.45, 0.45-0.51, 0.58-0.68, 0.68-0.78 and 3.55-3.93 μm) (**OK**); conical scanning, resolution 1.1 km for OK, ranging from 19 km (at 183 GHz) to 260 km (at 6.9 km); swath 2000 km.
- **MWR** [Okean-O1 -1 to -7 and SICH-1], 3-channel MW radiometer, frequencies 3.53, 22.2 and 37.5 GHz, nadir-only viewing for sea-surface temperature and wind, and total-column water vapour.
- **R225** and **R-600** [Okean-O-1] were single-frequency / dual polarization MW radiometers, at 13.3 GHz and 5 GHz respectively; resolution 130 and 165 km respectively. Pointing 42° off-nadir.
- **RLSBO**, a real-aperture side-looking radar, exploiting the X-band (9.7 GHz) in all Okean and SICH satellites; Okean-O-1 had two antenna complexes, looking on each side (R = Right L = Left, see Fig. 4.7.2); resolution about 1.8 km, swath 455 km (two swaths, R and L, for Okean-O-1).
- **RM-08** [all Okean and SICH satellites except Okean-O-1], conical scanning radiometer at 36.6 GHz (0.8 cm) for sea-surface wind and sea ice, resolution 20 km, swath 550 km.
- **Trasser** [Okean-O1-3] and **Trasser-O** [Okean-O-1], a polarisation spectroradiometer for ocean colour, vegetation and aerosol; spectral range 430-800 nm, 62 channels of bandwidth 3 nm (at 430 nm) to 12 nm (at 800 nm), all with two polarisations; resolution 45 km; non-scanning instrument viewing 20° off-nadir.

Frequencies used from operational meteorological satellites for data transmission to the ground

This Annex collects the information on frequency plans of GOS satellites limited to:

- current and planned operational meteorological satellites in geostationary and sunsynchronous orbits
- frequencies used to download or relay the observed data to the central system station(s) and to local user stations.

This information is already contained in the sections dealing with the individual satellites. The purpose of this section is to provide a friendly framework for keeping the information updated. The level of detail of the information provided is totally insufficient for station design, but may allow the reader to at least capture a broad idea of the complexity of each data acquisition mode.

A1.1 Geostationary satellites

Table A.1.1 reports frequency information for geostationary satellites. It is a simplified presentation, especially as concerns the transmission of raw data to the central facility (only one stream is mentioned, whereas generally there are more). Meteorological data distribution is indicated only when it implies a dedicated user station. Data Collection Platforms are mentioned only when requiring interrogation, and the information refers to the downlink.

Table A.1.1 – Frequency plan of meteorological satellites in geostationary orbit (September 2006)

| Satellite | Utilisation | Position | Service | Frequency | Bandwidth | Polarisation | Data rate |
|------------------------|-------------|----------|---------|--------------|----------------------|--------------|-----------|
| Meteosat-5 | 1991-2007 | 63°E | to PGS | 1686.833 MHz | 1.3332 MHz | Linear | 333 kbps |
| | | | HRID | 1694.5 MHz | 0.66 MHz | Linear | 166 kbps |
| | | | WEFAX-1 | 1694.5 MHz | 20 kHz | Linear | 2.4 kbps |
| | | | WEFAX-2 | 1691.0 MHz | 20 kHz | Linear | 2.4 kbps |
| | | | MDD | 1695.74 MHz | 120 kHz (4 channels) | Linear | 2.4 kbps |
| Meteosat-6 | 1993-2007 | 10°E | to PGS | 1686.833 MHz | 1.3332 MHz | Linear | 333 kbps |
| | | | HRID | 1694.5 MHz | 0.66 MHz | Linear | 166 kbps |
| | | | WEFAX-1 | 1694.5 MHz | 20 kHz | Linear | 2.4 kbps |
| | | | WEFAX-2 | 1691.0 MHz | 20 kHz | Linear | 2.4 kbps |
| | | | MDD | 1695.74 MHz | 120 kHz (4 channels) | Linear | 2.4 kbps |
| Meteosat-7 | 1997-2008 | 57.5°E | to PGS | 1686.833 MHz | 1.3332 MHz | Linear | 333 kbps |
| | | | HRID | 1694.5 MHz | 0.66 MHz | Linear | 166 kbps |
| | | | WEFAX-1 | 1694.5 MHz | 20 kHz | Linear | 2.4 kbps |
| | | | WEFAX-2 | 1691.0 MHz | 20 kHz | Linear | 2.4 kbps |
| | | | MDD | 1695.74 MHz | 120 kHz (4 channels) | Linear | 2.4 kbps |
| Meteosat-8 (MSG-1) | 2002-2009 | 3.4°W | to PGS | 1686.833 MHz | 5.4 MHz | Linear | 3.27 Mbps |
| | | | HRIT | 1695.15 MHz | 2.0 MHz | Linear | 1.0 Mbps |
| | | | LRIT | 1691.0 MHz | 0.66 MHz | Linear | 128 kbps |
| Meteosat-9 (MSG-2) | 2005-2013 | 0° | to PGS | 1686.833 MHz | 5.4 MHz | Linear | 3.27 Mbps |
| | | | HRIT | 1695.15 MHz | 2.0 MHz | Linear | 1.0 Mbps |
| | | | LRIT | 1691.0 MHz | 0.66 MHz | Linear | 128 kbps |
| Meteosat-10 (MSG-3) | 2011-2018 | 0° | to PGS | 1686.833 MHz | 5.4 MHz | Linear | 3.27 Mbps |
| | | | HRIT | 1695.15 MHz | 2.0 MHz | Linear | 1.0 Mbps |
| | | | LRIT | 1691.0 MHz | 0.66 MHz | Linear | 128 kbps |
| Meteosat-11 (MSG-4) | 2012-2019 | 0° | to PGS | 1686.833 MHz | 5.4 MHz | Linear | 3.27 Mbps |
| | | | HRIT | 1695.15 MHz | 2.0 MHz | Linear | 1.0 Mbps |
| | | | LRIT | 1691.0 MHz | 0.66 MHz | Linear | 128 kbps |

Table A.1.1 (cont.) – Frequency plan of meteorological satellites in geostationary orbit (September 2006)

| Satellite | Utilisation | Position | Service | Frequency | Bandwidth | Polarisation | Data rate |
|---------------------|-------------|----------|---------|--------------|-----------|--------------|-----------|
| GOES-9 | 1995-2007 | 160°E | to CDA | 1676.2 MHz | 6.0 MHz | Linear | 3.0 Mbps |
| | | | GVAR | 1685.7 MHz | 5.0 MHz | Linear | 2.1 Mbps |
| | | | WEFAX | 1691.0 MHz | 1.0 MHz | Linear | 1.6 kHz |
| | | | DCIS-1 | 468.8250 MHz | 200 kHz | RHC | 100 bps |
| | | | DCIS-2 | 468.8375 MHz | 200 kHz | RHC | 100 bps |
| GOES-10 | 1997-2007 | 60°W | to CDA | 1676.2 MHz | 6.0 MHz | Linear | 3.0 Mbps |
| | | | GVAR | 1685.7 MHz | 5.0 MHz | Linear | 2.1 Mbps |
| | | | WEFAX | 1691.0 MHz | 1.0 MHz | Linear | 1.6 kHz |
| | | | DCIS-1 | 468.8250 MHz | 200 kHz | RHC | 100 bps |
| | | | DCIS-2 | 468.8375 MHz | 200 kHz | RHC | 100 bps |
| GOES-11 | 2000-2008 | 135°W | to CDA | 1676.2 MHz | 6.0 MHz | Linear | 3.0 Mbps |
| | | | GVAR | 1685.7 MHz | 5.0 MHz | Linear | 2.1 Mbps |
| | | | WEFAX | 1691.0 MHz | 1.0 MHz | Linear | 1.6 kHz |
| | | | DCIS-1 | 468.8250 MHz | 200 kHz | RHC | 100 bps |
| | | | DCIS-2 | 468.8375 MHz | 200 kHz | RHC | 100 bps |
| GOES-12 | 2001-2009 | 75°W | to CDA | 1676.2 MHz | 6.0 MHz | Linear | 3.0 Mbps |
| | | | GVAR | 1685.7 MHz | 5.0 MHz | Linear | 2.1 Mbps |
| | | | WEFAX | 1691.0 MHz | 1.0 MHz | Linear | 1.6 kHz |
| | | | DCIS-1 | 468.8250 MHz | 200 kHz | RHC | 100 bps |
| | | | DCIS-2 | 468.8375 MHz | 200 kHz | RHC | 100 bps |
| GOES-13 | 2004-2011 | 105°W | to CDA | 1676.2 MHz | 6.0 MHz | Linear | 3.0 Mbps |
| | | | GVAR | 1685.7 MHz | 5.0 MHz | Linear | 2.1 Mbps |
| | | | WEFAX | 1691.0 MHz | 1.0 MHz | Linear | 1.6 kHz |
| | | | DCIS-1 | 468.8250 MHz | 200 kHz | RHC | 100 bps |
| | | | DCIS-2 | 468.8375 MHz | 200 kHz | RHC | 100 bps |
| GOES-14 (GOES-O) | 2007-2014 | TBD | to CDA | 1676.2 MHz | 6.0 MHz | Linear | 3.0 Mbps |
| | | | GVAR | 1685.7 MHz | 5.0 MHz | Linear | 2.1 Mbps |
| | | | WEFAX | 1691.0 MHz | 1.0 MHz | Linear | 1.6 kHz |
| | | | DCIS-1 | 468.8250 MHz | 200 kHz | RHC | 100 bps |
| | | | DCIS-2 | 468.8375 MHz | 200 kHz | RHC | 100 bps |
| GOES-15 (GOES-P) | 2008-2015 | TBD | to CDA | 1676.2 MHz | 6.0 MHz | Linear | 3.0 Mbps |
| | | | GVAR | 1685.7 MHz | 5.0 MHz | Linear | 2.1 Mbps |
| | | | WEFAX | 1691.0 MHz | 1.0 MHz | Linear | 1.6 kHz |
| | | | DCIS-1 | 468.8250 MHz | 200 kHz | RHC | 100 bps |
| | | | DCIS-2 | 468.8375 MHz | 200 kHz | RHC | 100 bps |
| MTSAT-1R | 2005-2010 | 140°E | to CDAS | 1677.0 MHz | 8.2 MHz | Linear | 2.7 Mbps |
| | | | HiRID | 1687.1 MHz | 2.0 MHz | Linear | 660 kbps |
| | | | HRIT | 1687.1 MHz | 5.3 MHz | Linear | 3.5 Mbps |
| | | | WEFAX | 1691.0 MHz | 250 kHz | Linear | 1.6 kHz |
| | | | LRIT | 1691.0 MHz | 250 kHz | Linear | 75 kbps |
| | | | DCS int | 468.875 MHz | 5.0 kHz | RHC | 300 bps |
| | | | DCS reg | 468.924 MHz | 5.0 kHz | RHC | 300 bps |
| MTSAT-2 | 2010-2015 | 145°E | to CDAS | 1677.0 MHz | 8.2 MHz | Linear | 2.7 Mbps |
| | | | HRIT | 1687.1 MHz | 5.3 MHz | Linear | 3.5 Mbps |
| | | | LRIT | 1691.0 MHz | 250 kHz | Linear | 75 kbps |
| | | | DCS int | 468.875 MHz | 5.0 kHz | RHC | 300 bps |
| | | | DCS reg | 468.924 MHz | 5.0 kHz | RHC | 300 bps |

Table A.1.1 (cont.) – Frequency plan of meteorological satellites in geostationary orbit (September 2006)

| Satellite | Utilisation | Position | Service | Frequency | Bandwidth | Polarisation | Data rate |
|--------------|-------------|--------------------------|---------------|---|-----------------------------|--------------|-----------------------------------|
| Elektro-L N1 | 2007-2014 | 76°E | RDA | 7500 MHz | 60 MHz | RHC | 30.72 Mbps |
| | | | HRIT | 1691.0 MHz | 2 MHz | RHC | 0.665-1 Mbps |
| | | | LRIT | 1691.0 MHz | 200 kHz | RHC | 64-128 kbps |
| | | | DCSA | 1697.0 MHz | 2 MHz | linear | 100-1200 bps |
| Elektro-L N2 | 2010-2017 | 76°E or 14.5°E | RDA | 7500 MHz | 60 MHz | RHC | 30.72 Mbps |
| | | | HRIT | 1691.0 MHz | 2 MHz | RHC | 0.665-1 Mbps |
| | | | LRIT | 1691.0 MHz | 200 kHz | RHC | 64-128 kbps |
| | | | DCSA | 1697.0 MHz | 2 MHz | linear | 100-1200 bps |
| Elektro-L N3 | 2015-2022 | 76°E or 14.5°E | RDA | 7500 MHz | 60 MHz | RHC | 30.72 Mbps |
| | | | HRIT | 1691.0 MHz | 2 MHz | RHC | 0.665-1 Mbps |
| | | | LRIT | 1691.0 MHz | 200 kHz | RHC | 64-128 kbps |
| | | | DCSA | 1697.0 MHz | 2 MHz | linear | 100-1200 bps |
| FY-2C | 2004-2009 | 105°E | to CDAS | 1681.6 MHz | 14 MHz | Linear | 14 Mbps |
| | | | S-VISSR | 1687.5 MHz | 2.0 MHz | Linear | 660 kbps |
| | | | LRIT | 1691.0 MHz | 260 kHz | Linear | 150 kbps |
| FY-2D | 2006-2011 | 86.5°E | to CDAS | 1681.6 MHz | 14 MHz | Linear | 14 Mbps |
| | | | S-VISSR | 1687.5 MHz | 2.0 MHz | Linear | 660 kbps |
| | | | LRIT | 1691.0 MHz | 260 kHz | Linear | 150 kbps |
| FY-2E | 2009-2014 | 123°E | to CDAS | 1681.6 MHz | 14 MHz | Linear | 14 Mbps |
| | | | S-VISSR | 1687.5 MHz | 2.0 MHz | Linear | 660 kbps |
| | | | LRIT | 1691.0 MHz | 260 kHz | Linear | 150 kbps |
| FY-2F | 2011-2016 | 86.5°E | to CDAS | 1681.6 MHz | 14 MHz | Linear | 14 Mbps |
| | | | S-VISSR | 1687.5 MHz | 2.0 MHz | Linear | 660 kbps |
| | | | LRIT | 1691.0 MHz | 260 kHz | Linear | 150 kbps |
| FY-2G | 2013-2018 | 123°E | to CDAS | 1681.6 MHz | 14 MHz | Linear | 14 Mbps |
| | | | S-VISSR | 1687.5 MHz | 2.0 MHz | Linear | 660 kbps |
| | | | LRIT | 1691.0 MHz | 260 kHz | Linear | 150 kbps |
| INSAT-3A | 2003-2008 | 93.5°E | to CDAS | VHRR: 4501.5 MHz CCD: 4508.93 MHz | 500 KHz | Linear | 526.5 kbps 1.2887 Mbps |
| INSAT-3C | 2002-2010 | 74°E | Analogue MDD | 2599.225 MHz | 200 kHz | Linear | 10 kHz |
| | | | Digital MDD | 2586.000 MHz | 200 kHz | Linear | 64/128 kbps |
| | | | Analogue CWDS | 2559.225 MHz | 200 kHz | Linear | 10 kHz |
| | | | Digital CWDS | 2585 or 2615 MHz | 200 kHz | Linear | 64/128 kbps |
| INSAT-3D | 2007-2014 | 83°E | to CDAS | 4781.0 MHz 4798.0 MHz 4506.05 MHz | 6 MHz 100 kHz 500 kHz | Linear | 4.0 Mbps 40.0 kbps 4.8 kbps |
| | | | HRIT | MHz | kHz | Linear | kbps |
| | | | LRIT | MHz | kHz | Linear | kbps |
| | | | | | | | |
| Kalpana-1 | 2002-2007 | 74°E | to CDAS | 4503.5 MHz | 500 KHz | Linear | 526.5 kbps |
| COMS-1 | 2008-2015 | 128.2°E or 116.2°E | to MSC | 1687 MHz | 6.0 MHz | RHC or LHC | 6 Mbps |
| | | | HRIT | 1695.4 MHz | 5.2 MHz | RHC or LHC | 3 Mbps |
| | | | LRIT | 1692.14 MHz | 1.0 MHz | RHC or LHC | 256 kbps |
| COMS-2 | 2014-2021 | 128.2°E or 116.2°E | to MODAC | MHz | MHz | | ... Mbps |
| | | | HRIT | MHz | kHz | | ... kbps |
| | | | LRIT | MHz | kHz | | ... kbps |

A1.2 Sunsynchronous satellites

Table A1.2 reports frequency information for sunsynchronous satellites. It is a simplified presentation, especially as concerns the transmission of global data to the high-latitude Command and Data Acquisition stations (only one stream is mentioned, whereas generally there are more). Data Collection Platforms are mentioned only when requiring interrogation. DMSP satellites are not included since the ordinary way to input their data into GOS is through NOAA or by bilateral agreements.

Table A1.2 – Frequency plan of meteorological satellites in sunsynchronous orbit (September 2006)

| Satellite | Utilisation | LST | Service | Frequency | Bandwidth | Polarisation | Data rate |
|----------------------|-------------|-----------------------------|----------|-----------------------------|-----------|--------------|------------|
| NOAA-15 | 1998-2006 | 05.30 d 17.30 a | GAC/LAC | 1702.5 and 1698 or 1707 MHz | 2.66 MHz | LHC or RHC | 2.66 Mbps |
| | | | HRPT | 1698 MHz | 2.66 MHz | RHC | 665.4 kbps |
| | | | HRPT bkp | 1702.5 MHz | 2.66 MHz | LHC | 665.4 kbps |
| | | | APT | 137.5 or 137.62 MHz | 34 kHz | RHC | 2.1 kHz |
| | | | DSB | 137.35 or 137.77 MHz | kHz | RHC | 8.32 kbps |
| NOAA-16 | 2000-2006 | 03.30 d 15.30 a | GAC/LAC | 1702.5 and 1698 or 1707 MHz | 2.66 MHz | LHC or RHC | 2.66 Mbps |
| | | | HRPT | 1698 MHz | 2.66 MHz | RHC | 665.4 kbps |
| | | | HRPT bkp | 1702.5 MHz | 2.66 MHz | LHC | 665.4 kbps |
| | | | APT | 137.5 or 137.62 MHz | 34 kHz | RHC | 2.1 kHz |
| | | | DSB | 137.35 or 137.77 MHz | kHz | RHC | 8.32 kbps |
| NOAA-17 | 2002-2009 | 10.20 d 22.20 a | GAC/LAC | 1702.5 and 1698 or 1707 MHz | 2.66 MHz | LHC or RHC | 2.66 Mbps |
| | | | HRPT | 1698 MHz | 2.66 MHz | RHC | 665.4 kbps |
| | | | HRPT bkp | 1702.5 MHz | 2.66 MHz | LHC | 665.4 kbps |
| | | | APT | 137.5 or 137.62 MHz | 34 kHz | RHC | 2.1 kHz |
| | | | DSB | 137.35 or 137.77 MHz | kHz | RHC | 8.32 kbps |
| NOAA-18 | 2005-2010 | 01.40 d 13.40 a | GAC/LAC | 1702.5 and 1698 or 1707 MHz | 2.66 MHz | LHC or RHC | 2.66 Mbps |
| | | | HRPT | 1698 MHz | 2.66 MHz | RHC | 665.4 kbps |
| | | | HRPT bkp | 1702.5 MHz | 2.66 MHz | LHC | 665.4 kbps |
| | | | APT | 137.5 or 137.62 MHz | 34 kHz | RHC | 2.1 kHz |
| | | | DSB | 137.35 or 137.77 MHz | kHz | RHC | 8.32 kbps |
| NOAA-19 (NOAA-N') | 2007-2011 | 02.00 d 14.00 a (TBC) | GAC/LAC | 1702.5 and 1698 or 1707 MHz | 2.66 MHz | LHC or RHC | 2.66 Mbps |
| | | | HRPT | 1698 MHz | 2.66 MHz | RHC | 665.4 kbps |
| | | | HRPT bkp | 1702.5 MHz | 2.66 MHz | LHC | 665.4 kbps |
| | | | APT | 137.5 or 137.62 MHz | 34 kHz | RHC | 2.1 kHz |
| | | | DSB | 137.35 or 137.77 MHz | kHz | RHC | 8.32 kbps |
| NPP | 2009-2014 | 01.30 d 13.30 a | SMD | 8212.5 MHz | 375 MHz | RHC | 300 Mbps |
| | | | HRD | 7812 MHz | 30.8 MHz | RHC | 15 Mbps |
| NPOESS-1 | 2013-2018 | 01.30 d 13.30 a | SMD | 25.65 GHz | 300 MHz | RHC | 150 Mbps |
| | | | HRD | 7812 or 7830 MHz | 30.8 MHz | RHC | 20 Mbps |
| | | | LRD | 1706 | 8 MHz | RHC | 3.88 Mbps |
| NPOESS-2 | 2016-2021 | 05.30 d 17.30 a | SMD | 25.65 GHz | 300 MHz | RHC | 150 Mbps |
| | | | HRD | 7812 or 7830 MHz | 30.8 MHz | RHC | 20 Mbps |
| | | | LRD | 1706 | 8 MHz | RHC | 3.88 Mbps |
| NPOESS-3 | 2020-2025 | 01.30 d 13.30 a | SMD | 25.65 GHz | 300 MHz | RHC | 150 Mbps |
| | | | HRD | 7812 or 7830 MHz | 30.8 MHz | RHC | 20 Mbps |
| | | | LRD | 1706 | 8 MHz | RHC | 3.88 Mbps |
| NPOESS-4 | 2022-2027 | 05.30 d 17.30 a | SMD | 25.65 GHz | 300 MHz | RHC | 150 Mbps |
| | | | HRD | 7812 or 7830 MHz | 30.8 MHz | RHC | 20 Mbps |
| | | | LRD | 1706 | 8 MHz | RHC | 3.88 Mbps |

Table A1.2 (cont.) – Frequency plan of meteorological satellites in sunsynchronous orbit (September 2006)

| Satellite | Utilisation | LST | Service | Frequency | Bandwidth | Polarisation | Data rate |
|------------|-------------|--------------------|---------|---------------------------------|------------|--------------|---------------|
| MetOp-1 | 2006-2010 | 09.30 d 21.30 a | GDS | 7800 MHz | 63 MHz | RHC | 70 Mbps |
| | | | AHRPT | 1701.3 MHz (1707 MHz backup) | 4.5 MHz | RHC | 3.5 Mbps |
| | | | LRPT | 137.1 MHz (137.9125 MHz backup) | 150 kHz | RHC | 72 kbps |
| MetOp-2 | 2010-2015 | 09.30 d 21.30 a | GDS | 7800 MHz | 63 MHz | RHC | 70 Mbps |
| | | | AHRPT | 1701.3 MHz (1707 MHz backup) | 4.5 MHz | RHC | 3.5 Mbps |
| | | | LRPT | 137.1 MHz (137.9125 MHz backup) | 150 kHz | RHC | 72 kbps |
| MetOp-3 | 2015-2020 | 09.30 d 21.30 a | GDS | 7800 MHz | 63 MHz | RHC | 70 Mbps |
| | | | AHRPT | 1701.3 MHz (1707 MHz backup) | 4.5 MHz | RHC | 3.5 Mbps |
| | | | LRPT | 137.1 MHz (137.9125 MHz backup) | 150 kHz | RHC | 72 kbps |
| Meteor-M-1 | 2007-2009 | 10.20 a 22.20 d | DA | 8.128 & 8.320 GHz | 32-250 MHz | RHC | 15.4-123 Mbps |
| | | | HRPT | 1700 MHz | 2.0 MHz | RHC | 665 kbps |
| | | | LRPT | 137.9 or 137.1 MHz | 150 kHz | RHC | 72 kbps |
| | | | DA | 8.128 & 8.320 GHz | 32-250 MHz | RHC | 15.4-123 Mbps |
| Meteor-M-2 | 2008-2012 | 10.20 a 22.20 d | DA | 8.128 & 8.320 GHz | 32-250 MHz | RHC | 15.4-123 Mbps |
| | | | HRPT | 1700 MHz | 2.0 MHz | RHC | 665 kbps |
| | | | LRPT | 137.9 or 137.1 MHz | 150 kHz | RHC | 72 kbps |
| | | | DCS | 1.69 to 1.71 GHz | MHz | RHC | 1200-400 bps |
| FY-1D | 2002-2006 | 08.20 d 20.20 a | CDPT | 1708.5 MHz (1695.5 MHz bkp) | 5.6 MHz | RHC | 1.33 Mbps |
| | | | CHRPT | 1700.5 MHz (1704.5 GHz bkp) | 5.6 MHz | RHC | 1.33 Mbps |
| FY-3A | 2007-2010 | 10.00 d 22.00 a | DPT | 8146 MHz | 149 MHz | RHC | 93 Mbps |
| | | | MPT | 7775 MHz | 45 MHz | RHC | 18.7 Mbps |
| | | | AHRPT | 1704.5 MHz | 6.8 MHz | RHC | 4.2 Mbps |
| FY-3B | 2010-2013 | 02.00 d 14.00 a | DPT | 8146 MHz | 149 MHz | RHC | 93 Mbps |
| | | | MPT | 7775 MHz | 45 MHz | RHC | 18.7 Mbps |
| | | | AHRPT | 1704.5 MHz | 6.8 MHz | RHC | 4.2 Mbps |
| FY-3C | 2012-2015 | 10.00 d 22.00 a | DPT | 8146 MHz | 149 MHz | RHC | 93 Mbps |
| | | | MPT | 7775 MHz | 45 MHz | RHC | 18.7 Mbps |
| | | | AHRPT | 1704.5 MHz | 6.8 MHz | RHC | 4.2 Mbps |
| FY-3D | 2014-2017 | 02.00 d 14.00 a | DPT | 8146 MHz | 149 MHz | RHC | 93 Mbps |
| | | | MPT | 7775 MHz | 45 MHz | RHC | 18.7 Mbps |
| | | | AHRPT | 1704.5 MHz | 6.8 MHz | RHC | 4.2 Mbps |
| FY-3E | 2016-2019 | 10.00 d 22.00 a | DPT | 8146 MHz | 149 MHz | RHC | 93 Mbps |
| | | | MPT | 7775 MHz | 45 MHz | RHC | 18.7 Mbps |
| | | | AHRPT | 1704.5 MHz | 6.8 MHz | RHC | 4.2 Mbps |
| FY-3F | 2018-2021 | 02.00 d 14.00 a | DPT | 8146 MHz | 149 MHz | RHC | 93 Mbps |
| | | | MPT | 7775 MHz | 45 MHz | RHC | 18.7 Mbps |
| | | | AHRPT | 1704.5 MHz | 6.8 MHz | RHC | 4.2 Mbps |
| FY-3G | 2020-2023 | 10.00 d 22.00 a | DPT | 8146 MHz | 149 MHz | RHC | 93 Mbps |
| | | | MPT | 7775 MHz | 45 MHz | RHC | 18.7 Mbps |
| | | | AHRPT | 1704.5 MHz | 6.8 MHz | RHC | 4.2 Mbps |

Definitions and acronyms

A2.1 Definition of spectral bands

In this Report use has been made of spectral band definitions which are not fully standardised. Therefore, the following two tables list these definitions as used here. Two tables are provided, one (**Table A2.1**) for the bands used for Remote Sensing, one (**Table A2.2**) for the sub-division of the band used in radar technology.

Table A2.1 - Bands of the electromagnetic spectrum exploited for Remote Sensing

| | | |
|---------------|--|-------------------------------------|
| UV | Ultra-Violet | 0.01 - 0.38 μm |
| B | Blue | 0.436 μm |
| G | Green | 0.546 μm |
| R | Red | 0.700 μm |
| VIS | Visible | 0.38 - 0.78 μm |
| NIR | Near Infra-Red | 0.78 - 1.30 μm |
| VNIR | Visible and Near Infra-Red (VIS + NIR) | 0.38 - 1.3 μm |
| SWIR | Short-Wave Infra-Red | 1.3 - 3.0 μm |
| SW | Short Wave | 0.2 - 4.0 μm |
| LW | Long Wave | 4 - 100 μm |
| MWIR | Medium-Wave Infra-Red | 3.0 - 6.0 μm |
| TIR | Thermal Infra-Red | 6.0 - 15.0 μm |
| IR | Infra-Red (MWIR + TIR) | 3 - 15 μm |
| FIR | Far Infra-Red | 15 μm - 1 mm (= 300 GHz) |
| Sub-mm | Submillimetre wave (part of FIR) | 3000 - 300 GHz (or 0.1 - 1 mm) |
| Mm | Millimetre wave (part of MW) | 300 - 30 GHz (or 1 - 10 mm) |
| MW | Microwave | 300 - 1 GHz (or 0.1 - 30 cm) |

Table A2.2 - Bands used in radar technology (according to ASPRS, American Society for Photogrammetry and Remote Sensing)

| Band | Frequency range | Wavelength range |
|------------|-----------------|------------------|
| P | 220 - 390 MHz | 77 - 136 cm |
| UHF | 300 - 1000 MHz | 30 - 100 cm |
| L | 1 - 2 GHz | 15 - 30 cm |
| S | 2 - 4 GHz | 7.5 - 15 cm |
| C | 4 - 8 GHz | 3.75 - 7.5 cm |
| X | 8 - 12.5 GHz | 2.4 - 3.75 cm |
| Ku | 12.5 - 18 GHz | 1.67 - 2.4 cm |
| K | 18 - 26.5 GHz | 1.18 - 1.67 cm |
| Ka | 26.5 - 40 GHz | 0.75 - 1.18 cm |
| V | 40 - 75 GHz | 4.0 - 7.5 mm |
| W | 75 - 110 GHz | 2.75 - 4.0 mm |

A2.2 List of acronyms (except for instruments, that are listed in Annex 3)

| | |
|------------|--|
| ADEOS | Advanced Earth Observing Satellite |
| ADM-Aeolus | Atmospheric Dynamics Mission – Aeolus |
| AND | ALOS Data Node |
| ALOS | Advanced Land Observing Satellite |
| AMP | Applications of Meteorology Programme |
| AO | Announcement of Opportunity |
| APT | Automatic Picture Transmission |
| AREP | Atmospheric Research and Environment Programme |
| ATN | Advanced TIROS-N |
| ATOVS | Advanced TIROS Operational Vertical Sounder |
| ATS | Application Technology Satellite |
| BUFR | Binary Universal Form for data Representation |
| CALIPSO | Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observations |
| CBS | Commission for Basic Systems (of WMO) |
| CDA | Command and Data Acquisition station |
| CDAS | Command and Data Acquisition Station |
| CDPT | China Delayed Picture Transmission |
| CERES | Clouds and the Earth's Radiant Energy System |
| CGMS | Coordination Group for Meteorological Satellites |
| CHAMP | Challenging Mini-Satellite Payload |
| CHRPT | China High Resolution Picture Transmission |
| CM | Consultative Meetings on High Level Policy on Satellite Matters (of WMO) |
| CMA | China Meteorological Department |
| CNES | Centre National d'Etudes Spatiales |
| CNSA | China National Space Agency |
| COMS | Communication, Oceanography and Meteorology Satellite |
| COSMIC | Constellation Observing System for Meteorology, Ionosphere & Climate |
| CWDS | Cyclone Warning Dissemination System |
| DCP | Data Collection Platform |
| DLR | Deutsches Zentrum für Luft- und Raumfahrt (German Aerospace Centre) |
| DMSP | Defense Meteorological Satellite Program |
| DOAS | Differential Optical Absorption Spectroscopy |
| DoD | Department of Defense (of the USA) |
| DPT | Delayed Picture Transmission |
| DSB | Direct Sounder Broadcast |
| DVB | Digital Video Broadcast |
| Earth-CARE | Earth Clouds, Aerosol and Radiation Explorer |
| EDC | EROS Data Centre (of the US Geological Survey) |
| EOC | Earth Observation Center (of JAXA) |
| EOS | Earth Observing System |
| EOSDIS | Earth Observing System - Data and Information System |
| EPS | EUMETSAT Polar System |
| ERBS | Earth Radiation Budget Satellite |
| ERS | European Remote-sensing Satellite |
| ESA | European Space Agency |
| ESSA | Environmental Science and Services Administration |
| ESSP | Earth System Science Pathfinder program |
| EUMETSAT | European Organisation for the exploitation of meteorological satellites |
| FGGE | First GARP Global Experiment |
| FY | Feng-Yun (FY-1 and FY-3 sunsynchronous, FY-2 geostationary) |
| G/T | Overall merit figure of a receiving system (dB/K) |
| GAC | Global Area Coverage |
| GARP | Global Atmospheric Research Programme |
| GDS | Global Data Stream |

| | |
|---------|---|
| GEO | Geostationary Earth Orbit |
| GMES | Global Monitoring for Environment and Security |
| GMS | Geosynchronous Meteorological Satellite |
| GOCE | Gravity Field and Steady-State Ocean Circulation Explorer |
| GOES | Geostationary Operational Environmental Satellite |
| GOMS | Geostationary Operational Meteorological Satellite |
| GOS | Global Observing System |
| GOSAT | Green-house gas Observing Satellite |
| GPM | Global Precipitation Measurement mission |
| GRACE | Gravity Recovery and Climate Experiment |
| GTS | Global Telecommunication System (of the WMO WWW) |
| GVAR | GOES Variable Data Format |
| HiRID | High Resolution Imager Data |
| HRIDS | High Resolution Image Dissemination Service |
| HRIT | High Rate Information Transmission |
| HRPT | High Resolution Picture Transmission |
| HRUS | High Rate User Station |
| HWRP | Hydrology and Water Resources Programme |
| HYDROS | Hydrosphere State Mission |
| IFOV | Instantaneous Field Of View |
| IGeoLab | International Geostationary Laboratory |
| IMD | India Meteorological Department |
| INDOEX | Indian Ocean Experiment |
| INSAT | Indian National Satellite |
| IOC | Intergovernmental Oceanographic Commission (of UNESCO) |
| IRS | Indian Remote-sensing Satellite |
| ISRO | India Space Research Organisation |
| ITOS | Improved TIROS Operational System |
| JASON | Joint Altimetry Satellite Oceanography Network |
| JAXA | Japan Aerospace Exploration Agency (formerly NASDA) |
| JERS | Japanese Earth Resources Satellite |
| JMA | Japan Meteorological Agency |
| JPS | Joint Polar System |
| KARI | Korea Aerospace Research Institute |
| KMA | Korea Meteorological Administration |
| KNMI | Koninklijk Nederlands Meteorologisch Instituut |
| KOSC | Korea Ocean Satellite Center |
| LAC | Local Area Coverage |
| LBR | Low Bit Rate |
| LEO | Low Earth Orbit |
| LRIT | Low Rate Information Transmission |
| LRUS | Low Rate User Station |
| LST | Local Solar Time |
| MAP | Mesoscale Alpine Programme |
| MDD | Meteorological Data Distribution |
| MDUS | Medium-scale Data Utilisation Station |
| MetSat | Meteorological Satellite (re-named Kalpana) |
| MODAC | Meteo/Ocean Data Application Center (Korea) |
| MOP | Meteosat Operational Programme |
| MOS | Marine Observatory Satellite |
| MPT | Medium-resolution Picture Transmission |
| MSC | Meteorological Satellite Center (Korea) |
| MSG | Meteosat Second Generation |
| MTG | Meteosat Third Generation |
| MTP | Meteosat Transition Programme |
| MTSAT | Multi-functional Transport Satellite |

| | |
|-------------|---|
| NASA | National Aeronautics and Space Administration (of USA) |
| NASDA | National Space Development Agency (of Japan) |
| NOAA | National Oceanic and Atmospheric Administration |
| NPOESS | National Polar-orbiting Operational Environmental Satellite System |
| NPP | NPOESS Preparatory Program |
| NRSA | National Remote Sensing Agency (of India) |
| NRT | Near-Real-Time |
| NSIDC | National Snow and Ice Data Center |
| NWP | Numerical Weather Prediction |
| OCO | Orbiting Carbon Observatory |
| OPAG-IOS | Open Programme Area Group on the Integrated Observing Systems |
| OSTM | Ocean Surface Topography Mission |
| PAC | Processing & Archiving Centre (of ESA/Envisat) |
| PAF | Processing & Archiving Facilities (of ESA/ERS) |
| PARASOL | Polarisation et Anisotropie des Réflectances au sommet de l'Atmosphère, couplées avec un Satellite d'Observation emportant un Lidar |
| PDUS | Primary Data User Station |
| PGS | Primary Ground Station |
| POEM | Polar Orbit Earth-observation Mission |
| POES | Polar-orbiting Operational Environmental Satellite |
| R & D | Research and Development |
| RDA | Raw Data Acquisition station |
| RosHydroMet | Hydro-Meteorological Service of the Russian Federation |
| RosKosmos | Aeronautics and Space Agency of the Russian Federation |
| RTH | Regional Telecommunication Hub (of the WMO WWW) |
| SAR | Synthetic Aperture Radar |
| SDUS | Secondary Data User Station |
| SMD | Stored Mission Data |
| SMOS | Soil Moisture and Ocean Salinity |
| SMS | Synchronous Meteorological Satellite |
| SNR | Signal-to-Noise Ratio |
| SPOT | Satellite Pour l'Observation de la Terre |
| SSP | Sub Satellite Point |
| SWARM | The Earth's Magnetic Field and Environment Explorers |
| TIROS | Television and Infra-Red Observation Satellite |
| TOPEX | Topography Experiment |
| TOS | TIROS Operational System |
| TOVS | TIROS Operational Vertical Sounder |
| TRMM | Tropical Rainfall Measuring Mission |
| UARS | Upper Atmosphere Research Satellite |
| USGS | US Geological Survey |
| WCP | World Climate Programme |
| WCRP | World Climate Research Programme |
| WDPMP | Natural Disaster Prevention and Mitigation Programme |
| WEFAX | Weather Facsimile |
| WMO | World Meteorological Organization |
| WSP | WMO Space Programme |
| WWW | World Weather Watch |

Instruments of the space-based component of GOS

This Annex lists all instruments that have been mentioned in this Report, and provides somewhat detailed information on several instruments that are currently being flown, or are planned to be flown, on the satellites constituting the space-based component of the Global Observing System (GOS). Data transmission payloads (except for DCP) and orbitography/navigation systems are not included.

The information on instruments of operational meteorological satellites (those handled in Sections 2 and 3) is provided in **Annex A3.1**; that one on instruments of R&D satellites (Section 4) in **Annex A3.2**.

The information consists of two records:

- The list of instruments (**Table A3.1** and **Table A3.2** for meteorological and R&D satellites respectively), recording the corresponding satellites and the period of utilisation of the instrument through the various satellites of a series.
- Instrument sheets, only for *Earth sensors*, i.e., not for *in situ* environment monitoring at platform level, solar observation, data collection systems, data distribution and search & rescue. Only current and planned instruments are considered⁹. The instruments for which sheets are provided are highlighted in the last columns of Table A3.1 and Table A3.2. In addition, **Table A3.3** and **Table A3.4** aggregate the instruments by type of mission.

The instrument sheets collect the information as available up to end-September 2006. The basis of information consists of the reports collected at the CGMS meetings, in certain case up to shortly before CGMS-XXXIV. Wide integration has been necessary by consulting other sources of public domain (generally the web sites of CGMS members and, in cascade, the sites of individual projects). It is complained that a trend is detectable towards web sites very spectacular, clearly oriented towards the general public, but the level of technical detail is not always satisfactory. We wish to acknowledge that a wide volume of information, although missing some detail at some stage, is available on:

- http://directory.eoportal.org/res_p1_Earthobservation.html maintained by ESA.

The degree of detail of the various instrument sheets changes with the priority of the mission in respect of WMO objectives (first priority: imagery and sounding), with the development status (from operational to planned) and with the availability of information.

When, for an instrument, there are upgraded flight models co-existing with previous flight models, the instrument sheet reports the latest version, even if the satellite has not yet been launched.

The purpose of this Appendix is to constitute a framework to facilitate updating of information exchanged within CGMS. The instrument sheets can be regarded as templates providing guidance for checking the current content, updating as necessary, and filling possible gaps.

The information collected in this document has been used in the Main Text of the Report to compare the degree of service provided by the various satellites concurring to implement GOS so as to control whether the composite system is not only compliant with requirements in terms of number and distribution of satellites, ma also in terms of homogeneity of data quality from different sources supposed to be used in combination. This analysis is limited to operational meteorological satellites (Sections 2.9 and 2.10 for geostationary, 3.8 and 3.9 for sunsynchronous).

⁹ However, an exception is made for instruments on satellites working till recently. This is the case of Meteor-3M.

A3.1 Operational meteorological satellites

Table A3.1 - List of instruments, corresponding satellites and utilisation period

| Acronym | Full name | Satellites | Utilisation | Sheet |
|-----------|---|--|--|-------------|
| ABI | Advanced Baseline Imager | GOES-R and follow-on | 2014 → | X |
| AC | Radiation Budget Sensor | Meteor-1 1 to 28 | 1969-1978 | |
| AMSU-A | Advanced Microwave Sounding Unit - A | NOAA 15 to 19 Metop 1 to 3 | 1998-2014 2006-2020 | X |
| AMSU-B | Advanced Microwave Sounding Unit - B | NOAA-15/16/17 | 1998-2007 | X |
| APS | Aerosol Polarimetry Sensor | NPOESS-1/3 | 2013-2025 | X |
| APT | Automatic Picture Transmission | TIROS-8, ESSA-2/4/6/8 ITOS-1, NOAA-1 | 1967-1976 1970-1971 | |
| ARGOS-DCS | ARGOS Data Collection and localisation System | TIROS-N, NOAA 6 to 19 NPOESS 1 to 4 Metop 1 to 3 | 1978-2012 2013-2027 2006-2020 | |
| ASCAT | Advanced Scatterometer | Metop 1 to 3 | 2006-2020 | X |
| ATMS | Advanced Technology Microwave Sounder | NPP, NPOESS 1 to 4 | 2009-2027 | X |
| AVCS | Advanced Vidicon Camera System | ESSA-3/5/7/9, ITOS-1, NOAA-1 | 1966-1971 | |
| AVHRR/3 | Advanced Very High Resolution Radiometer | TIROS-N, NOAA 6 to 19 Metop 1 to 3 | 1978-2014 2006-2020 | X |
| CCD | Charge Coupled Device Camera | INSAT-2E, INSAT-3A | 1999-2012 | X |
| CMIS | Conical-scanning Microwave Imager/Sounder | NPOESS 2 to 4 | 2016-2027 | X |
| CrIS | Cross-track Infrared Sounder | NPP, NPOESS 1 to 4 | 2009-2027 | X |
| DCIS | Data Collection and Interrogation Service | SMS-1/2, GOES 1 to 15 GOMS-1 and follow-on | 1974-2015 1994 → | |
| DCS | Data Collection Service | Meteosat 1 to 11 GMS 1 to 5, MTSAT-1/2 FY-2 A to F INSAT-1A to 3D, Kalpana | 1977-2018 1977-2014 1997-2015 1982-2014 | |
| ERBE | Earth Radiation Budget Experiment | NOAA-9 and NOAA-10 | 1984-2001 | |
| ERBS | Earth Radiation Budget Sensor | NPOESS-1/3 | 2013-2025 | X |
| FCI | Flexible Combined Imager | Meteosat Third Generation | 2015 → | X |
| FPR | Flat Plate Radiometer | TIROS-2/3/4/7, ESSA-1/3/5/7/9 ITOS-1, NOAA-1 | 1960-1972 1970-1971 | |
| GEOSAR | Geostationary Search and Rescue | GOES 8 to 15 Meteosat 8 to 11 (MSG) INSAT-3 A and D Elektro-L and follow-on | 1994-2015 2002-2018 2003-2010 2007 → | |
| GERB | Geostationary Earth Radiation Budget | Meteosat 8 to 11 (MSG) | 2002-2019 | X |
| GGAK-M | Space Environment Monitor | Meteor-M 1/2 | 2007-2012 | |
| GLM | Geostationary Lightning Mapper | GOES-R and follow-on | 2014 → | X |
| GOCI | Geostationary Ocean Color Imager | COMS-1/2 | 2008-2021 | X |
| GOME-2 | Global Ozone Monitoring Experiment - 2 | Metop 1 to 3 | 2006-2020 | X |
| GRAS | GNSS Receiver for Atmospheric Sounding | Metop 1 to 3 | 2006-2020 | X |
| GVHHR | Geostationary Very High Resolution Radiometer | ATS-6 | 1974 | |
| HES | Hyperspectral Environmental Suite | GOES-R and follow-on | 2014 → | X |
| HIRS/4 | High-resolution Infra Red Sounder | TIROS-N, NOAA 6 to 19 Metop-1/2 | 1978-2014 2006-2015 | X |
| IASI | Infrared Atmospheric Sounding Interferometer | Metop 1 to 3 | 2006-2020 | X |
| IMAGER | GOES Imager INSAT Imager MTSAT Imager | GOES 8 to 15 INSAT-3D MTSAT-2 | 1994-2015 2007-2014 2010-2015 | X X X |
| IR | Infrared Instrument | Meteor-1 1 to 28, Meteor-2 1 to 22 | 1969-1994 | |
| IRAS | Infra Red Atmospheric Sounder | FY-3 1 to 7 | 2007-2023 | X |
| IRFS-2 | IR Sounding Spectrometer | Meteor-M-2 | 2008-2012 | X |
| IRS | Infra Red Sounder | Meteosat Third Generation | 2015 → | X |
| JAMI | Japanese Advanced Meteorological Imager | MTSAT-1R | 2005-2010 | X |
| KGI-4C | Space Environment Monitor (particles) | Meteor-3M | 2001-2005 | |

Table A3.1 (cont.) - List of instruments, corresponding satellites and utilisation period

| Acronym | Full name | Satellites | Utilisation | Sheet |
|-------------------|---|--|-------------------------------------|--------|
| Klimat | Infrared Imaging Radiometer | Meteor-3 1 to 7, Meteor-3M | 1985-2005 | X |
| KMSS | High-resolution VIS/NIR radiometer | Meteor-M 1/2 | 2007-2012 | X |
| LI | Lightning Imager | Meteosat Third Generation | 2015 → | X |
| MERSI | Medium Resolution Spectral Imager | FY-3 A to G | 2007-2023 | X |
| MHS | Microwave Humidity Sounding | NOAA-18/19 Metop 1 to 3 | 2005-2014 2006-2020 | X |
| MI | Meteorological Imager | COMS-1/2 | 2008-2021 | X |
| MIVZA | Imaging microwave radiometer | Meteor-3M | 2001-2005 | |
| MR-2000M1 | Television Camera | Meteor-3 1 to 7, Meteor-3M | 1985-2005 | X |
| MR-900B | Television Camera | Meteor-3 1 to 7 | 1985-1995 | |
| MRIR | Medium Resolution Infrared Radiometer | TIROS-2/3/4/7 | 1960-1967 | |
| MSGI-5EI | Space Environment Monitor (irradiances) | Meteor-3M | 2001-2005 | |
| MSSCC | Multi-color Spin Scan Cloud Camera | ATS-3 | 1967-1975 | |
| MSU | Microwave Sounding Unit | TIROS-N, NOAA 6 to 14 | 1978-2003 | |
| MSU-E | High-resolution VIS/NIR radiometer | Meteor-3M | 2001-2005 | X |
| MSU-GS | Elektro-GOMS Imager | Elektro-L and follow-on | 2007 → | X |
| MSU-MR | VIS/IR Imaging Radiometer | Meteor-M 1/2 | 2007-2012 | X |
| MTVZA | Imaging/Sounding Microwave Radiometer | Meteor-3M and Meteor-M 1/2 | 2001-2012 | X |
| MVIRI | Meteosat Visible Infra-Red Imager | Meteosat 1 to 7 | 1977-2008 | X |
| MVISR | Multichannel Visible Infrared Scanning Radiometer | FY-1 A to D | 1988-2006 | X |
| MWHS | Micro-Wave Humidity Sounder | FY-3 A to G | 2007-2023 | X |
| MWRI | Micro-Wave Radiation Imager | FY-3 A to G | 2007-2023 | X |
| MWTS | Micro-Wave Temperature Sounder | FY-3 A to G | 2007-2023 | X |
| OMPS | Ozone Mapping and Profiler Suite | NPP, NPOESS-1/3 | 2009-2025 | X |
| Radiomet | Radio-occultation sounder | Meteor-M 1/2 | 2007-2012 | X |
| RMK-2 | Space Environment Monitor | Meteor-2 1 to 22, Meteor-3 1 to 6 | 1975-1994 | |
| RMS | Radiation Measurement System | GOMS-1/2 and follow-on | 1994 → | |
| SAGE-III | Stratospheric Aerosol and Gas Experiment – III | Meteor-3M | 2001-2005 | X |
| SARSAT | Search and Rescue Satellite-Aided Tracking System | NOAA 8 to 19 except 12 NPOESS 1 to 4 Metop 1/2 | 1983-2012 2013-2027 2006-2016 | |
| SBUV/2 | Solar Backscatter Ultraviolet / 2 | NOAA 9 to 19 except 12/15 | 1984-2014 | X |
| ScaRaB | Scanner for Radiation Budget | Meteor-3 7 | 1994-1995 | |
| SEM (GEO) | Space Environment Monitor | SMS-1/2, GOES 1 to 15 GMS 1 to 5 FY-2 A to F | 1974-2015 1977-2003 1997-2015 | |
| SEM (LEO) | Space Environment Monitor | TIROS-N, NOAA 6 to 19 Metop 1/2 FY-1 A to D, FY-3 A to G | 1978-2012 2006-2015 1988-2021 | |
| SESS | Space Environment Sensor Suite | NPOESS 1 to 4 | 2013-2025 | |
| Severjanin | X-band Synthetic Aperture Radar | Meteor-M 1/2 | 2007-2012 | X |
| SEVIRI | Spinning Enhanced Visible Infra-Red Imager | Meteosat 8 to 11 (MSG) | 2002-2019 | X |
| SFM-2 | Ultraviolet spectrometer | Meteor-3M | 2001-2005 | |
| SM | Infrared Sounding Radiometer | Meteor-2 1 to 22 | 1975-1994 | |
| SOUNDER | GOES Sounder INSAT Sounder | GOES 8 to 15 INSAT-3D | 1994-2015 2007-2014 | X X |
| SPM | Solar Proton Monitor | NOAA 2 to 5 | 1972-1979 | |
| SR | Scanning Radiometer | ITOS-1, NOAA 1 to 5 | 1970-1979 | |
| SSCC | Spin Scan Cloud Camera | ATS-1 | 1966-1972 | |
| SSM/I | Special Sensor Microwave – Imager | DMSP F-8/10/11/13/14/15 | 1987-2006 | X |
| SSM/T | Special Sensor Microwave – Temperature | DMSP F 4 to 15 | 1979-2006 | X |
| SSM/T2 | Special Sensor Microwave – Humidity | DMSP F-11/12/14/15 | 1991-2006 | X |
| SSMIS | Special Sensor Microwave – Imager/Sounder | DMSP F 16 to 20 | 2003-2016 | X |

Table A3.1 (cont.) - List of instruments, corresponding satellites and utilisation period

| Acronym | Full name | Satellites | Utilisation | Sheet |
|------------|--|------------------------------------|------------------------|-------|
| SSU | Stratospheric Sounding Unit | TIROS-N, NOAA 6 to 14 | 1978-2003 | |
| STR | Scanning TV Radiometer | GOMS-1 | 1994-2000 | |
| S-VISSR | Stretched Visible-Infrared Spin Scan Radiometer | FY-2 A to F | 1997-2016 | X |
| SXI | Solar X-ray Imager | GOES 12 to 15 | 2001-2015 | |
| TOMS | Total Ozone Mapping Spectrometer | Meteor-3 6 | 1991-1993 | |
| TOU/SBUS | Total Ozone Unit & Solar Backscatter Ultraviolet Sounder | FY-3 A to G | 2007-2023 | X |
| TSIS | Total Solar Irradiance Sensor | NPOESS-2/4 | 2016-2027 | |
| TV | Television Camera | Meteor-1 1 to 28, Meteor-2 1 to 22 | 1969-1994 | |
| VAS | VISSR Atmospheric Sounder | GOES 4 to 7 | 1980-1995 | |
| VCS | Vidicon Camera System | TIROS 1 to 10, ESSA-1 | 1960-1967 | |
| VHRR (GEO) | Very High Resolution Radiometer | INSAT-1A to 3A, Kalpana | 1982-2012 | X |
| VHRR (LEO) | Very High Resolution Radiometer | NOAA 2 to 5 | 1972-1979 | |
| VIIRS | Visible/Infrared Imager Radiometer Suite | NPP, NPOESS 1 to 4 | 2009-2027 | X |
| VIRR | Visible and Infra Red Radiometer | FY-3 A to G | 2007-2023 | X |
| VISSR | Visible-Infrared Spin Scan Radiometer | SMS-1/2, GOES-1/2/3 GMS 1 to 5 | 1974-1980 1977-2003 | |
| VTPR | Vertical Temperature Profile Radiometer | NOAA 2 to 5 | 1972-1979 | |

Table A3.3 - List of the provided instrument sheets ordered by type of sensor and satellite

| GEOSTATIONARY | Meteosat | GOES | MTSAT | Elektro-L | FY-2 | INSAT-3A and 3D | Kalpana | COMS |
|------------------|---------------|---------|--------------|-----------|---------|-------------------|---------|----------|
| Imager | MVIRI, SEVIRI | IMAGER | JAMI, IMAGER | MSU-GS | S-VISSR | VHRR, CCD, IMAGER | VHRR | MI, GOCI |
| Advanced imager | FCI | ABI | | | | | | |
| Sounder | | SOUNDER | | | | SOUNDER | | |
| Advanced sounder | IRS | HES | | | | | | |
| Earth radiation | GERB | | | | | | | |
| Lightning mapper | LI | GLM | | | | | | |

| SUNSYNCHRONOUS | NOAA | DMSP | NPOESS | MetOp | Meteor-3M / Meteor-M | FY-1 / FY-3 |
|---------------------------|-------------|--------|--------|---------|---------------------------|-------------|
| VIS/IR imager | AVHRR/3 | | | AVHRR/3 | MR-2000M1, Klimat, MSU-MR | MVISR, VIRR |
| VIS/IR advanced imager | | | VIIRS | | MSU-E, KMSS | MERSI |
| IR sounder | HIRS 3/4 | | | HIRS/4 | | IRAS |
| IR advanced sounder | | | CrIS | IASI | IRFS-2 | |
| MW imager | | SSM/I | | | | MWRI |
| MW imager/sounder | | SSMIS | CMIS | | MTVZA | |
| MW sounder (temperature) | AMSU-A | SSM/T | | AMSU-A | | MWTS |
| MW sounder (humidity) | AMSU-B, MHS | SSM/T2 | | MHS | | MWHS |
| MW advanced sounder | | | ATMS | | | |
| Radio-occultation sounder | | | | GRAS | Radiomet | |
| Altimeter | | | | | | |
| Scatterometer | | | | ASCAT | | |
| SAR | | | | | Severjanin | |
| Aerosol | | | APS | | SAGE-III | |
| Earth radiation budget | | | ERBS | | | |
| Ozone | SBUS/2 | | OMPS | GOME-2 | | TOU/SBUS |

| | |
|----------------------------|--|
| ABI | Advanced Baseline Imager |
| Satellites | GOES-R (to become GOES-16) and follow-on |
| Status (Sept 2006) | Being defined – To be utilised from 2014 onward |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 16-channel VIS/IR radiometer |
| Coverage/cycle | Full disk each 15 min, 3000x5000 km ² ("CONUS", Continental U.S.) in 5 min, 1000x1000 km ² in 30 s |
| Resolution (s.s.p.) | 0.5 km at 0.64 μ m, 1.0 km at 0.47, 0.86 and 1.61 μ m, 2 km in the remaining 12 channels |

| Central wavelength | Bandwidth | Radiometric accuracy (NE Δ T or SNR) |
|--------------------|--------------|---|
| 470 nm | 40 nm | 300 @ 100 % albedo |
| 640 nm | 100 nm | 300 @ 100 % albedo |
| 860 nm | 40 nm | 300 @ 100 % albedo |
| 1380 nm | 30 nm | 300 @ 100 % albedo |
| 1610 nm | 60 nm | 300 @ 100 % albedo |
| 2260 nm | 50 nm | 300 @ 100 % albedo |
| 3.90 μ m | 0.20 μ m | 0.1 K @ 300 K |
| 6.15 μ m | 0.90 μ m | 0.1 K @ 300 K |
| 7.00 μ m | 0.40 μ m | 0.1 K @ 300 K |
| 7.40 μ m | 0.20 μ m | 0.1 K @ 300 K |
| 8.50 μ m | 0.40 μ m | 0.1 K @ 300 K |
| 9.70 μ m | 0.20 μ m | 0.1 K @ 300 K |
| 10.3 μ m | 0.50 μ m | 0.1 K @ 300 K |
| 11.2 μ m | 0.80 μ m | 0.1 K @ 300 K |
| 12.3 μ m | 1.00 μ m | 0.1 K @ 300 K |
| 13.3 μ m | 0.60 μ m | 0.3 K @ 300 K |

| | |
|----------------------------|--|
| AMSU-A | Advanced Microwave Sounder Unit - A |
| Satellites | NOAA 15 to 19 - MetOp 1 to 3 |
| Status (Sept 2006) | Operational – Utilisation period: 1998 to ~ 2014 on NOAA, 2006 to ~ 2020 on MetOp |
| Mission | Temperature sounding in nearly-all-weather conditions |
| Instrument type | 15-channel MW radiometer |
| Scanning technique | Cross-track: 30 steps of 48 km ssp, swath 2250 km - Along-track: one 48-km line each 8 s |
| Coverage/cycle | Near-global coverage twice/day |
| Resolution (s.s.p.) | 48 km IFOV |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Radiometric accuracy (NE Δ T) |
|-----------------------------|-----------------|--------------|--------------------------------------|
| 23.800 | 270 | V | 0.30 K |
| 31.400 | 180 | V | 0.30 K |
| 50.300 | 180 | V | 0.40 K |
| 52.800 | 400 | V | 0.25 K |
| 53.596 \pm 0.115 | 170 | H | 0.25 K |
| 54.400 | 400 | H | 0.25 K |
| 54.940 | 400 | V | 0.25 K |
| 55.500 | 330 | H | 0.25 K |
| $f_0 = 57.290344$ | 330 | H | 0.25 K |
| $f_0 \pm 0.217$ | 78 | H | 0.40 K |
| $f_0 \pm 0.3222 \pm 0.048$ | 36 | H | 0.40 K |
| $f_0 \pm 0.3222 \pm 0.022$ | 16 | H | 0.60 K |
| $f_0 \pm 0.3222 \pm 0.010$ | 8 | H | 0.80 K |
| $f_0 \pm 0.3222 \pm 0.0045$ | 3 | H | 1.20 K |
| 89.000 | 6000 | V | 0.50 K |

| AMSU-B | Advanced Microwave Sounder Unit - B |
|----------------------------|--|
| Satellites | NOAA 15 to 17 |
| Status (Sept 2006) | Operational – Utilisation period: 1998 to ~ 2007 |
| Mission | Humidity sounding in nearly-all-weather conditions. Also precipitation |
| Instrument type | 5-channel MW radiometer |
| Scanning technique | Cross-track: 90 steps of 16 km ssp, swath 2250 km - Along-track: one 16-km line each 8/3 s |
| Coverage/cycle | Near-global coverage twice/day |
| Resolution (s.s.p.) | 16 km IFOV |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Radiometric accuracy (NE Δ T) |
|-------------------------|-----------------|--------------|--------------------------------------|
| 89.0 | 1000 | V | 0.37 K |
| 150.0 | 1000 | V | 0.84 K |
| 183.31 \pm 7.0 | 2000 | V | 0.60 K |
| 183.31 \pm 3.0 | 1000 | V | 0.70 K |
| 183.31 \pm 1.0 | 500 | V | 1.06 K |

| APS | Aerosol Polarimetry Sensor |
|---------------------------|---|
| Satellites | NPOESS 1 and 3 |
| Status (Sept 2006) | Currently not baselined – In case, to be utilised in the period 2013 to ~ 2025 |
| Mission | Aerosol optical thickness, size distribution and shape |
| Instrument type | 9-channel VIS/NIR/SWIR polarimeter with multi-angle capability |
| Scanning technique | |
| Coverage/cycle | measurements/day at km intervals – Global coverage (25 km average spacing) in 30 days |
| Resolution | 10 km IFOV |

| Central wavelength | Bandwidth | Polarisations | Radiometric accuracy (SNR) |
|--------------------|-----------|---------------------------|----------------------------|
| 412 nm | 20 nm | 0, 45, 90 and 135 degrees | @ % albedo |
| 445 nm | 18 nm | 0, 45, 90 and 135 degrees | |
| 488 nm | 20 nm | 0, 45, 90 and 135 degrees | |
| 555 nm | 20 nm | 0, 45, 90 and 135 degrees | @ % albedo |
| 672 nm | 20 nm | 0, 45, 90 and 135 degrees | |
| 746 nm | 15 nm | 0, 45, 90 and 135 degrees | @ % albedo |
| 865 nm | 39 nm | 0, 45, 90 and 135 degrees | @ % albedo |
| 1240 nm | 20 nm | 0, 45, 90 and 135 degrees | @ % albedo |
| 1378 nm | 15 nm | 0, 45, 90 and 135 degrees | @ % albedo |
| 1610 nm | 60 nm | 0, 45, 90 and 135 degrees | @ % albedo |
| 2250 nm | 50 nm | 0, 45, 90 and 135 degrees | @ % albedo |

| ASCAT | Advanced Scatterometer |
|---------------------------|---|
| Satellites | MetOp 1 to 3 |
| Status (Sept 2006) | Being commissioned - To be utilised in the period: 2006 to ~ 2020 |
| Mission | Sea surface wind vector. Also large-scale soil moisture |
| Instrument type | C-band radar scatterometer (5.255 GHz), side looking both left and right. 3 antennas on each side |
| Scanning technique | Two 550-km swaths separated by a 700-km gap along-track. 3 looks each pixel (45, 90 and 135° azimuth) |
| Coverage/cycle | Global coverage in 1.5 days |
| Resolution | Best quality: 50 km – standard quality: 25 km – basic sampling: 12.5 km |

| ATMS | Advanced Technology Microwave Sounder |
|----------------------------|--|
| Satellites | NPP, NPOESS 1/3 and possibly 2/4 |
| Status (Sept 2006) | Being built – To be utilised in the period 2009 to ~ 2025 (2027 if also on NPOESS 2/4) |
| Mission | Temperature and humidity sounding in nearly-all-weather conditions. Also precipitation |
| Instrument type | 22-channel MW radiometer |
| Scanning technique | Cross-track: 96 steps of 16 km ssp, swath 2200 km - Along-track: one 16-km line each 8/3 s |
| Coverage/cycle | Near-global coverage twice/day |
| Resolution (s.s.p.) | 16 km for channels 165-183 GHz, 32 km for channels 50-90 GHz, 75 km for channels 23-32 GHz |

| Central frequency (GHz) | Bandwidth (MHz) | Quasi-polarisation | Radiometric accuracy (NE Δ T) |
|-----------------------------|-----------------|--------------------|--------------------------------------|
| 23.800 | 270 | QV | 0.90 K |
| 31.400 | 180 | QV | 0.90 K |
| 50.300 | 180 | QH | 1.20 K |
| 51.760 | 400 | QH | 0.75 K |
| 52.800 | 400 | QH | 0.75 K |
| 53.596 \pm 0.115 | 170 | QH | 0.75 K |
| 54.400 | 400 | QH | 0.75 K |
| 54.940 | 400 | QH | 0.75 K |
| 55.500 | 330 | QH | 0.75 K |
| $f_0 = 57.290344$ | 330 | QH | 0.75 K |
| $f_0 \pm 0.217$ | 78 | QH | 1.20 K |
| $f_0 \pm 0.3222 \pm 0.048$ | 36 | QH | 1.20 K |
| $f_0 \pm 0.3222 \pm 0.022$ | 16 | QH | 1.50 K |
| $f_0 \pm 0.3222 \pm 0.010$ | 8 | QH | 2.40 K |
| $f_0 \pm 0.3222 \pm 0.0045$ | 3 | QH | 3.60 K |
| 89.5 | 5000 | QV | 0.50 K |
| 165.5 | 3000 | QH | 0.60 K |
| 183.31 \pm 7.0 | 2000 | QH | 0.80 K |
| 183.31 \pm 4.5 | 2000 | QH | 0.80 K |
| 183.31 \pm 3.0 | 1000 | QH | 0.80 K |
| 183.31 \pm 1.8 | 1000 | QH | 0.80 K |
| 183.31 \pm 1.0 | 500 | QH | 0.90 K |

| AVHRR/3 | Advanced Very High Resolution Radiometer / 3 |
|----------------------------|---|
| Satellites | TIROS-N, NOAA 6 to 19 - MetOp 1 to 3 |
| Status (Sept 2006) | Operational – Utilisation period: 1978 to ~ 2014 on NOAA, 2006 to ~ 2020 on MetOp |
| Mission | Multi-purpose VIS/IR imagery |
| Instrument type | 6-channel VIS/IR radiometer (channel 1.6 and 3.7 alternative) |
| Scanning technique | Cross-track: 2048 pixel of 800 m ssp, swath 2900 km - Along-track: six 1.1-km lines/s |
| Coverage/cycle | Global coverage twice/day (IR) or once/day (VIS) |
| Resolution (s.s.p.) | 1.1 km IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (NE Δ T or SNR) |
|--------------------|----------------------|---|
| 0.630 μ m | 0.58 - 0.68 μ m | 9 @ 0.5 % albedo |
| 0.862 μ m | 0.725 - 1.00 μ m | 9 @ 0.5 % albedo |
| 1.61 μ m | 1.58 - 1.64 μ m | 20 @ 0.5 % albedo |
| 3.74 μ m | 3.55 - 3.93 μ m | 0.12 K @ 300 K |
| 10.80 μ m | 10.3 - 11.3 μ m | 0.12 K @ 300 K |
| 12.00 μ m | 11.5 - 12.5 μ m | 0.12 K @ 300 K |

| CCD | Charge-Coupled Device Camera |
|---------------------|--|
| Satellites | INSAT-2E and INSAT-3A |
| Status (Sept 2006) | Operational – Utilisation period: 1999 to ~ 2012 |
| Mission | Cloud imagery |
| Instrument type | 3-channel VIS camera |
| Coverage/cycle | 10° x 10° each 3 hours. More frequently on demand. Daylight operation only |
| Resolution (s.s.p.) | 1.0 km |

| Central wavelength | Spectral interval | Radiometric Accuracy (SNR) |
|--------------------|---------------------------|----------------------------|
| 0.71 μm | 0.63 - 0.79 μm | 417 @ 100 % albedo |
| 0.81 μm | 0.77 - 0.86 μm | 336 @ 100 % albedo |
| 1.62 μm | 1.55 - 1.70 μm | 342 @ 100 % albedo |

| CMIS | Conical-scanning Microwave Imager/Sounder |
|-----------------------|--|
| Satellites | NPOESS 2 to 4 |
| Status (Sept 2006) | Design being reconsidered in view of descopeing – Utilisation period: 2016 to ~ 2027 |
| Mission | Multi-purpose MW imager with temperature/humidity sounding channels for improved precipitation |
| Instrument type | 63-frequency, 77-channel MW radiometer |
| Scanning technique | Conical: 53.6- 58.1° zenith angle, swath 1700 km – Scan rate: 31.6 scan/min = 12.5 km/scan |
| Coverage/cycle | Global coverage once/day |
| Resolution (constant) | Changing with frequency, consistent with antenna diameters of 2.2 m (6-90 GHz) and 0.7 m (> 90GHz) |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations (*) | Accuracy (NE Δ T) | IFOV | Pixel |
|-------------------------|----------------------|-------------------|--------------------------|--------------|---------------|
| 6.625 | 350 | V, H | K | 34 x 56 km | 40 x 12.5 km |
| 10.65 | 100 | V, H, R, L | K | 21 x 35 km | 20 x 12.5 km |
| 18.7 | 200 | V, H, P, M, L, R | K | 12 x 20 km | 10 x 12.5 km |
| 23.8 | 400 | V, H | K | 9.5 x 17 km | 10 x 12.5 km |
| 36.5 | 1000 | V, H, P, M | K | 6.2 x 10 km | 5 x 12.5 km |
| 50.3 | 134 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 52.240 | 1280 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 53.570 | 960 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 54.380 | 440 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 54.905 | 350 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 55.490 | 340 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 56.660 | 300 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 59.380 | 280 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 59.940 | 440 | V | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 60.3712 | 57.6 | L | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 60.4080 | 16 | L | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 60.4202 | 8.4 | L | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 60.5088 | 44.8 | L | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 60.43476 (**) | 20 (40 FFT channels) | H | K | 4.5 x 7.5 km | 5 x 12.5 km |
| 89.0 | 4000 | V, H | K | 2.5 x 4.2 | 2.5 x 6.25 km |
| 166 \pm 0.7875 | 1425 | V | K | 15 x 25 | 10 x 12.5 km |
| 183.31 \pm 7.70 | 4500 | V | K | 15 x 25 | 10 x 12.5 km |
| 183.31 \pm 3.10 | 3500 | V | K | 15 x 25 | 10 x 12.5 km |
| 183.31 \pm 0.7125 | 1275 | V | K | 15 x 25 | 10 x 12.5 km |

(*) Polarisations: H = horizontal, V = vertical, P = + 45°, M = - 45°, L = left-hand circular, R = right-hand circular

(**) 20 MHz band centred on 60.43476 GHz (7+ line of O₂) split in 40 channels by Fast Fourier Transform (FFT)

| CrIS | | Cross-track Infrared Sounder | |
|----------------------------------|---|-------------------------------------|--------------------------------------|
| Satellites | NPP, NPOESS 1/3 and possibly 2/4 | | |
| Status (Sept 2006) | Being built – To be utilised in the period 2009 to ~ 2025 (2007 if also on NPOESS 2/4) | | |
| Mission | Temperature/humidity sounding, ozone profile and total-column green-house gases | | |
| Instrument type | IR spectrometer/interferometer (1300 channels) | | |
| Scanning technique | Cross-track: 32 steps of 48 km ssp, swath 2200 km - Along-track: one 48-km line each 8 s | | |
| Coverage/cycle | Near-global coverage twice/day | | |
| Resolution (s.s.p.) | 3 x 3 14 km IFOV covering a 48 x 48 km ² cell (average sampling distance: 16 km) | | |
| Spectral range (μm) | Spectral range (cm^{-1}) | Spectral resolution (unapodised) | Radiometric accuracy (NE Δ T) |
| 9.13 - 15.40 μm | 650 - 1095 cm^{-1} | 0.625 cm^{-1} | K @ K |
| 5.71 - 8.26 μm | 1210 - 1750 cm^{-1} | 1.25 cm^{-1} | K @ K |
| 3.92 - 4.64 μm | 2155 - 2550 cm^{-1} | 2.5 cm^{-1} | K @ K |

| ERBS | | Earth Radiation Budget Sensor | | |
|----------------------------|---|--------------------------------------|--------------------------------------|-------|
| Satellites | NPOESS 1 and possibly 3 | | | |
| Status (Sept 2006) | Recurring model of CERES – To be utilised in the period 2013 to ~ 2018 (possibly to ~ 2025) | | | |
| Mission | Earth radiation budget | | | |
| Instrument type | Two broad-band and one narrow-band channel radiometer | | | |
| Scanning technique | Cross-track: 80 steps of 20 km ssp, swath 3000 km - Along-track: one 20-km line each 3 s | | | |
| Coverage/cycle | Global coverage twice/day (IR and total radiance) or once/day (short-wave) | | | |
| Resolution (s.s.p.) | 20 km | | | |
| Channel | Spectral interval | Noise Equivalent Radiance | Absolute accuracy | SNR |
| Narrow-band | 8 - 12 μm | 0.3 $\text{Wm}^{-2}\text{sr}^{-1}$ | Wm | |
| Short-wave | 0.3 - 5.0 μm | 0.8 $\text{Wm}^{-2}\text{sr}^{-1}$ | $\text{Wm}^{-2}\text{sr}^{-1}$ | |
| Total radiance | 0.3 - 100 μm | 0.6 $\text{Wm}^{-2}\text{sr}^{-1}$ | $\text{Wm}^{-2}\text{sr}^{-1}$ | |

| FCI | | Flexible Combined Imager | | |
|----------------------------|---|---------------------------------|--|--|
| Satellites | Meteosat-12 and follow-on (Meteosat Third Generation) | | | |
| Status (Sept 2006) | Being defined - To be utilised from 2015 onward | | | |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features | | | |
| Instrument type | 16-channel VIS/IR radiometer | | | |
| Coverage/cycle | Full disk in 10 min and 2.5 min over Europe; or alternating modes | | | |
| Resolution (s.s.p.) | Sampling distance (pixel) of 0.5, 1.0 or 2.0 km (see table). IFOV ~ 1.2 times the sampling distance | | | |

| Channel no. | Central wavelength | Bandwidth | Radiometric accuracy (SNR or NE Δ T) | Pixel |
|-------------|---------------------|--------------------|---|--------|
| 1 | 444 nm | 60 nm | 25 @ 1 % albedo | 1.0 km |
| 2 | 510 nm | 50 nm | 25 @ 1 % albedo | 1.0 km |
| 3 | 645 nm | 80 nm | 30 @ 1 % albedo | 0.5 km |
| 4 | 860 nm | 70 nm | 30 @ 1 % albedo | 1.0 km |
| 5 | 960 nm | 60 nm | 12 @ 1 % albedo | 1.0 km |
| 6 | 1375 nm | 30 nm | 40 @ 1 % albedo | 1.0 km |
| 7 | 1610 nm | 60 nm | 30 @ 1 % albedo | 1.0 km |
| 8 | 2260 nm | 50 nm | 25 @ 1 % albedo | 0.5 km |
| 9 | 3.80 μm | 0.40 μm | 0.1 K @ 300 K | 1.0 km |
| 10 | 6.30 μm | 0.40 μm | 0.3 K @ 250 K | 2.0 km |
| 11 | 7.35 μm | 0.50 μm | 0.3 K @ 250 K | 2.0 km |
| 12 | 8.70 μm | 0.30 μm | 0.1 K @ 300 K | 2.0 km |
| 13 | 9.66 μm | 0.30 μm | 0.3 K @ 250 K | 2.0 km |
| 14 | 10.50 μm | 0.70 μm | 0.1 K @ 300 K | 1.0 km |
| 15 | 12.30 μm | 0.50 μm | 0.1 K @ 300 K | 2.0 km |
| 16 | 13.30 μm | 0.60 μm | 0.2 K @ 270 K | 2.0 km |

| GERB | | Geostationary Earth Radiation Budget | | |
|---------------------|---|---|------------------------------------|------|
| Satellites | Meteosat 8 to 11 (Meteosat Second Generation) | | | |
| Status (Sept 2006) | Operational – Utilisation period: 2002 to ~ 2019 | | | |
| Mission | Earth radiation budget | | | |
| Instrument type | Two broad-band channels radiometer | | | |
| Coverage/cycle | Full disk each 5 min. Integration over three cycles (15 min) to comply with accuracy requirements | | | |
| Resolution (s.s.p.) | 42 km | | | |
| Channel | Spectral interval | Noise Equivalent Radiance | Absolute accuracy | SNR |
| Short-wave | 0.32 - 4.0 μm | 0.8 $\text{Wm}^{-2}\text{sr}^{-1}$ | 2.4 $\text{Wm}^{-2}\text{sr}^{-1}$ | 1250 |
| Total radiance | 0.32 - 30 μm | 0.15 $\text{Wm}^{-2}\text{sr}^{-1}$ | 0.4 $\text{Wm}^{-2}\text{sr}^{-1}$ | 400 |

| GLM | | Geostationary Lightning Mapper | | |
|---------------------|---|---------------------------------------|--|--|
| Satellites | GOES-R and follow-on | | | |
| Status (Sept 2006) | Proposed – To be utilised from 2014 onward | | | |
| Mission | Proxy for convective precipitation, proxy for NO_x generation, study of Earth electric field | | | |
| Instrument type | CCD camera operating at 777.4 nm (O_2) to count flashes and measure their intensity | | | |
| Coverage/cycle | Large fraction of the disk continuously observed (time resolution 2 ms) | | | |
| Resolution (s.s.p.) | 8 km | | | |

| GOCI | | Geostationary Ocean Color Imager | | |
|---------------------|--|---|--|--|
| Satellites | COMS 1 and 2 | | | |
| Status (Sept 2006) | Being designed – To be utilised in the period 2008 to ~ 2021 | | | |
| Mission | Ocean color and aerosol | | | |
| Instrument type | 8-channel VIS/NIR radiometer | | | |
| Scanning technique | Bushbroom, 6000 pixel/line (3700 useful), swath 1420 km | | | |
| Coverage/cycle | Area of 2500 km x 2500 km, hourly in daylight | | | |
| Resolution (s.s.p.) | 500 m IFOV | | | |
| Central wavelength | Bandwidth | Radiometric accuracy (SNR @ specified $\text{NE}\Delta\text{L}$) | | |
| 412 nm | 20 nm | 1000 @ 0.100 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |
| 443 nm | 20 nm | 1090 @ 0.086 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |
| 490 nm | 20 nm | 1170 @ 0.067 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |
| 555 nm | 20 nm | 1070 @ 0.056 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |
| 660 nm | 20 nm | 1010 @ 0.032 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |
| 680nm | 10 nm | 870 @ 0.031 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |
| 745 nm | 20 nm | 860 @ 0.020 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |
| 865 nm | 40 nm | 750 @ 0.016 $\text{W m}^{-2} \text{sr}^{-1} \mu^{-1}$ | | |

| GOME-2 | | Global Ozone Monitoring Experiment - 2 | | |
|---------------------|--|---|--|--|
| Satellites | MetOp 1 to 3 | | | |
| Status (Sept 2006) | Being commissioned - To be utilised in the period 2006 to ~ 2020 | | | |
| Mission | Ozone profile and total-column or gross profile of other species. Tracked species: BrO, ClO, H_2O , HCHO, NO, NO_2 , NO_3 , O_2 , O_3 , O_4 , OClO, SO_2 and aerosol | | | |
| Instrument type | UV/VIS grating spectrometer, four bands, 4096 channels, with 200 polarisation channels | | | |
| Scanning technique | Cross-track: 24 steps of 40 km or 80 km ssp, swath 960 or 1920 km - Along-track: one 40-km line each 6 s | | | |
| Coverage/cycle | Global coverage each 3 days with high resolution or 1.5 days with low resolution. Daylight only | | | |
| Resolution (s.s.p.) | 40 x 40 km^2 associated to 960 km swath or 40 x 80 km^2 associated to 1920 km swath | | | |

| Spectral range | Number of channels | Spectral resolution | SNR at specified input radiance |
|----------------|--------------------|-------------------------------------|--|
| 240 - 315 nm | 1024 | 0.24 - 0.29 nm | 7-177 @ 50 % albedo and 60° Solar Zenith Angle |
| 311 - 403 nm | 1024 | 0.26 - 0.28 nm | 372-3000 @ 50 % albedo and 60° SZA |
| 401 - 600 nm | 1024 | 0.44 - 0.53 nm | 4000 @ 50 % albedo and 60° SZA |
| 590 - 790 nm | 1024 | 0.44 - 0.53 nm | 2000-4000 @ 50 % albedo and 60° SZA |
| 312 - 790 nm | 200 | 2.8 nm at 312 nm to 40 nm at 790 nm | 100 for $\lambda < 400$ nm, 1000 for $400 \text{ nm} < \lambda < 790$ nm |

| GRAS | GNSS Receiver for Atmospheric Sounding |
|--------------------|--|
| Satellites | MetOp 1 to 3 |
| Status (Sept 2006) | Being commissioned - To be utilised in the period 2006 to ~ 2020 |
| Mission | Temperature/humidity sounding with highest vertical resolution, space weather |
| Instrument type | GPS receiver measuring the phase delay due to refraction during occultation between GPS and LEO |
| Scanning technique | Limb scanning from 830 km to close-to-surface by time sampling – Azimuth: 90° sectors fore- and aft- |
| Coverage/cycle | About 500 soundings/day – Average spacing 1000 km – Global coverage (300 km spacing) in 10 days |
| Resolution | About 300 km horizontal, 0.5 km vertical |

| HES | Hyperspectral Environmental Suite |
|---------------------|---|
| Satellites | GOES-R (to become GOES-16) and follow-on |
| Status (Sept 2006) | Currently not baselined. Plan being revisited - In case, to be utilised from 2014 onward |
| Mission | Temperature/humidity sounding and wind profile derivation by tracking water vapour features |
| Instrument type | IR spectrometer (+ one VIS channel) for sounding, 14-19 channel radiometer for coastal waters |
| Coverage/cycle | Full disk in maximum 60 min. Limited areas in correspondingly shorter time intervals |
| Resolution (s.s.p.) | 2-10 km for sounding (0.5-1.0 km for the VIS channel), 0.15-2.0 km for coastal waters |

| Spectral range (μm) | Spectral range (cm^{-1}) | Spectral resolution (goal and threshold) | Accuracy (variation in the range) |
|----------------------------------|-------------------------------------|--|-----------------------------------|
| 15.0 - 15.4 μm | 650 - 665 cm^{-1} | 0.5 - 0.625 cm^{-1} | 0.30 - 1.00 K @ 250 K |
| 13.9 - 15.0 μm | 665 - 720 cm^{-1} | 0.5 - 0.625 cm^{-1} | 0.17 - 0.30 K @ 250 K |
| 13.0 - 13.9 μm | 720 - 770 cm^{-1} | 0.5 - 0.625 cm^{-1} | 0.15 - 0.17 K @ 250 K |
| 9.84 - 13.0 μm | 770 - 1016 cm^{-1} | 0.5 - 0.625 cm^{-1} | 0.15 - 0.20 K @ 250 K |
| 9.56 - 9.84 μm | 1016 - 1046 cm^{-1} | 0.5 - 0.625 cm^{-1} | 0.15 - 0.20 K @ 250 K |
| 8.33 - 9.56 μm | 1046 - 1200 cm^{-1} | 0.5 - 0.625 cm^{-1} | 0.20 - 0.90 K @ 250 K |
| 5.75 - 8.26 μm or | 1210 - 1740 cm^{-1} or | 0.625 - 1.25 cm^{-1} | 0.13 - 0.24 K @ 250 K |
| 4.65 - 6.06 μm | 1650 - 2150 cm^{-1} | 0.625 - 1.25 cm^{-1} | 0.60 - 1.60 K @ 250 K |
| 4.44 - 4.65 μm | 2150 - 2250 cm^{-1} | 2.5 cm^{-1} | 1.5 - 2.0 K @ 250 K |
| 3.68 - 4.44 μm (goal) | 2250 - 2720 cm^{-1} | 2.5 cm^{-1} | 0.4 - 3.0 K @ 250 K |
| 0.52 - 0.70 μm | N/A | 0.18 μm | 300 @ 100 % albedo |

| Channel designed for coastal water monitoring | Baseline channels for ocean colour Resolution 150 - 300 m | | Central wavelength | Bandwidth | SNR at specified input radiance |
|---|--|--------------------|-------------------------------|-------------------------------|---------------------------------|
| | | | 0.412 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.443 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.477 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.490 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.510 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.530 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.550 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.645 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.667 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.678 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.750 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | | | 0.763 μm | 0.02 μm | 300 (threshold) to 600 (goal) |
| | 0.865 μm | 0.04 μm | 300 (threshold) to 600 (goal) | | |
| | 0.905 μm | 0.02 μm | 300 (threshold) to 600 (goal) | | |
| Goal channels | Cloud detection Resolution 0.9 - 1.2 km | 1.38 μm | 0.03 μm | 300 (threshold) to 600 (goal) | |
| | | 1.61 μm | 0.06 μm | 300 (threshold) to 600 (goal) | |
| | | 2.26 μm | 0.05 μm | 300 (threshold) to 600 (goal) | |
| | Sea surface temperature Resolution 1.0 - 2.0 km | 11.2 μm | 0.8 μm | NE Δ T = 0.1 K @ 250 K | |
| 12.3 μm | | 1.0 μm | NE Δ T = 0.1 K @ 250 K | | |

| HIRS 3/4 | High-resolution Infra Red Sounder 3 / 4 |
|---------------------|---|
| Satellites | TIROS-N, NOAA 6 to 19 - MetOp 1 and 2 |
| Status (Sept 2006) | Operational – Utilisation period: 1978 to ~ 2014 on NOAA, 2006 to ~ 2015 on MetOp |
| Mission | Temperature/humidity sounding |
| Instrument type | 20-channel IR radiometer (including one VIS) |
| Scanning technique | Cross-track: 56 steps of 26 km ssp, swath 2200 km - Along-track: one line each 42 km each 6.4 s |
| Coverage/cycle | Near-global coverage twice/day |
| Resolution (s.s.p.) | 18 km for HIRS/3, 10 km IFOV for HIRS/4 |

| Wavelength | Wavenumber | Bandwidth | Radiometric accuracy (NE Δ N or SNR) | Radiometric accuracy (NE Δ T or SNR) |
|---------------------|-----------------------|----------------------|--|--|
| 14.95 μm | 669 cm^{-1} | 3 cm^{-1} | 3.00 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 14.71 μm | 680 cm^{-1} | 10 cm^{-1} | 0.67 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 14.49 μm | 690 cm^{-1} | 12 cm^{-1} | 0.50 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 14.22 μm | 703 cm^{-1} | 16 cm^{-1} | 0.31 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 13.97 μm | 716 cm^{-1} | 16 cm^{-1} | 0.21 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 13.64 μm | 733 cm^{-1} | 16 cm^{-1} | 0.24 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 13.35 μm | 749 cm^{-1} | 16 cm^{-1} | 0.20 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 12.47 μm | 802 cm^{-1} | 16 cm^{-1} | 0.15 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 11.11 μm | 900 cm^{-1} | 35 cm^{-1} | 0.10 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 9.71 μm | 1030 cm^{-1} | 25 cm^{-1} | 0.15 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 7.33 μm | 1364 cm^{-1} | 40 cm^{-1} | 0.20 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 6.52 μm | 1534 cm^{-1} | 55 cm^{-1} | 0.20 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 4.57 μm | 2188 cm^{-1} | 23 cm^{-1} | 0.006 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 4.52 μm | 2210 cm^{-1} | 23 cm^{-1} | 0.003 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 4.47 μm | 2237 cm^{-1} | 23 cm^{-1} | 0.004 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 4.45 μm | 2247 cm^{-1} | 23 cm^{-1} | 0.004 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 4.13 μm | 2420 cm^{-1} | 28 cm^{-1} | 0.002 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 4.00 μm | 2500 cm^{-1} | 35 cm^{-1} | 0.002 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 3.76 μm | 2660 cm^{-1} | 100 cm^{-1} | 0.001 $\text{mW}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}\cdot\text{cm}$ | K @ K |
| 0.69 μm | N/A | 0.05 μm | 0.10 % albedo | @ % albedo |

| | |
|----------------------------|---|
| IASI | Infrared Atmospheric Sounding Interferometer |
| Satellites | Metop 1 to 3 |
| Status (Sept 2006) | Being commissioned - To be utilised in the period 2006 to ~ 2020 |
| Mission | Temperature/humidity sounding, ozone profile and total-column green-house gases |
| Instrument type | IR spectrometer/interferometer (8461 channels) with one embedded IR imaging channel |
| Scanning technique | Cross-track: 30 steps of 48 km ssp, swath 2130 km - Along-track: one 48-km line each 8 s |
| Coverage/cycle | Near-global coverage twice/day |
| Resolution (s.s.p.) | 4 x 12-km IFOV close to the centre of a 48 x 48 km ² cell (average sampling distance: 24 km) |

| Spectral range (μm) | Spectral range (cm^{-1}) | Spectral resolution (unapodised) | Accuracy (for 0.25 cm^{-1} channels) (NEΔT) |
|--|---|---|--|
| 8.26 - 15.50 μm | 645 - 1210 cm^{-1} | 0.25 cm^{-1} | 0.2-0.3 K @ 280 K |
| 5.00 - 8.26 μm | 1210 - 2000 cm^{-1} | 0.25 cm^{-1} | 0.2-0.5 K @ 280 K |
| 3.62 - 5.00 μm | 2000 - 2760 cm^{-1} | 0.25 cm^{-1} | 0.5-2.0 K @ 280 K |
| 10.3-12.5 μm | N/A | N/A | 0.8 K @ 280 K |

| | |
|----------------------------|---|
| IMAGER | GOES Imager |
| Satellites | GOES 8 to 15 |
| Status (Sept 2006) | Operational – Utilisation period: 1994 to ~ 2015 |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 5-channel VIS/IR radiometer |
| Coverage/cycle | Full disk each 30 min. Limited areas in correspondingly shorter time intervals |
| Resolution (s.s.p.) | 4.0 km for IR channels; 1.0 km for the VIS channel |

| Central wavelength | Spectral interval | Radiometric accuracy (NEΔT or SNR) |
|---------------------------|---------------------------|---|
| 0.65 μm | 0.55 - 0.75 μm | @ ... % albedo |
| 3.90 μm | 3.80 - 4.00 μm | 0.11 K @ 300 K |
| 6.55 μm | 5.80 - 7.30 μm | 0.14 K @ 300 K |
| 10.70 μm | 10.2 - 11.2 μm | 0.09 K @ 300 K |
| 13.35 μm | 13.0 - 13.7 μm | K @ 300 K |

| | |
|----------------------------|---|
| IMAGER | INSAT Imager |
| Satellites | INSAT-3D |
| Status (Sept 2006) | Being built – To be utilised in the period 2007 to ~ 2014 |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 6-channel VIS/IR radiometer |
| Coverage/cycle | Full disk each 30 min. Limited areas in correspondingly shorter time intervals |
| Resolution (s.s.p.) | 4.0 km for IR window channels; 1.0 km for VIS/SWIR channels; 8.0 km for water-vapour channel |

| Central wavelength | Spectral interval | Radiometric accuracy (NEΔT or SNR) |
|---------------------------|---------------------------|---|
| 0.65 μm | 0.52 - 0.72 μm | 150 @ 1 % albedo |
| 1.625 μm | 1.55 - 1.70 μm | 150 @ 1 % albedo |
| 3.90 μm | 3.80 - 4.00 μm | 1.4 K @ 300 K |
| 6.8 μm | 6.50 - 7.10 μm | 1.0 K @ 230 K |
| 10.8 μm | 10.2 - 11.2 μm | 0.35 K @ 300 K |
| 12.0 μm | 11.5 - 12.5 μm | 0.35 K @ 300 K |

| IMAGER | MTSAT Imager |
|----------------------------|---|
| Satellites | MTSAT- 2 |
| Status (Sept 2006) | Standby (Operational utilisation period: 2010 to 2015) |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 5-channel VIS/IR radiometer |
| Coverage/cycle | Full disk each 30 min. Half disk each 15 min. |
| Resolution (s.s.p.) | 4.0 km for IR channels; 1.0 km for the VIS channel |

| Central wavelength | Spectral interval | Radiometric accuracy (NE Δ T or SNR) |
|--------------------|---------------------|---|
| 0.675 μ m | 0.55 - 0.80 μ m | 6.5 @ 2.5 % albedo |
| 3.75 μ m | 3.50 - 4.00 μ m | 0.09 K @ 300 K |
| 6.75 μ m | 6.50 - 7.00 μ m | 0.12 K @ 300 K |
| 10.8 μ m | 10.3 - 11.3 μ m | 0.11 K @ 300 K |
| 12.0 μ m | 11.5 - 12.5 μ m | 0.20 K @ 300 K |

| IRAS | Infra Red Atmospheric Sounder |
|----------------------------|---|
| Satellites | FY-3 A to G |
| Status (Sept 2006) | Close to launch – To be utilised in the period 2007 to ~ 2023 |
| Mission | Temperature/humidity sounding |
| Instrument type | 26-channel IR radiometer (including 6 in short-wave) |
| Scanning technique | Cross-track: 56 steps of 26 km ssp, swath 2250 km - Along-track: one line each 42 km each 6.4 s |
| Coverage/cycle | Near-global coverage twice/day |
| Resolution (s.s.p.) | 17 km IFOV |

| Wavelength | Wavenumber | Bandwidth | Radiometric accuracy (NE Δ T or NE Δ ρ) |
|---------------|------------------------|-----------------------|---|
| 14.95 μ m | 669 cm^{-1} | 3 cm^{-1} | 2.50 K @ 290 K |
| 14.71 μ m | 680 cm^{-1} | 10 cm^{-1} | 0.50 K @ 290 K |
| 14.49 μ m | 690 cm^{-1} | 12 cm^{-1} | 0.37 K @ 290 K |
| 14.22 μ m | 703 cm^{-1} | 16 cm^{-1} | 0.22 K @ 290 K |
| 13.97 μ m | 716 cm^{-1} | 16 cm^{-1} | 0.20 K @ 290 K |
| 13.64 μ m | 733 cm^{-1} | 16 cm^{-1} | 0.22 K @ 290 K |
| 13.35 μ m | 749 cm^{-1} | 16 cm^{-1} | 0.18 K @ 290 K |
| 12.47 μ m | 802 cm^{-1} | 30 cm^{-1} | 0.12 K @ 290 K |
| 11.11 μ m | 900 cm^{-1} | 35 cm^{-1} | 0.10 K @ 290 K |
| 9.71 μ m | 1030 cm^{-1} | 25 cm^{-1} | 0.14 K @ 290 K |
| 7.43 μ m | 1345 cm^{-1} | 50 cm^{-1} | 0.27 K @ 290 K |
| 7.33 μ m | 1365 cm^{-1} | 40 cm^{-1} | 0.37 K @ 290 K |
| 6.52 μ m | 1533 cm^{-1} | 55 cm^{-1} | 0.53 K @ 290 K |
| 4.57 μ m | 2188 cm^{-1} | 23 cm^{-1} | 0.10 K @ 290 K |
| 4.52 μ m | 2210 cm^{-1} | 23 cm^{-1} | 0.05 K @ 290 K |
| 4.47 μ m | 2235 cm^{-1} | 23 cm^{-1} | 0.08 K @ 290 K |
| 4.45 μ m | 2245 cm^{-1} | 23 cm^{-1} | 0.08 K @ 290 K |
| 4.19 μ m | 2388 cm^{-1} | 25 cm^{-1} | 0.06 K @ 290 K |
| 3.98 μ m | 2515 cm^{-1} | 35 cm^{-1} | 0.10 K @ 290 K |
| 3.76 μ m | 2660 cm^{-1} | 100 cm^{-1} | 0.11 K @ 290 K |
| 1.64 μ m | 6098 cm^{-1} | 450 cm^{-1} | 0.1 % |
| 1.24 μ m | 8065 cm^{-1} | 650 cm^{-1} | 0.1 % |
| 0.94 μ m | 10638 cm^{-1} | 200 cm^{-1} | 0.1 % |
| 0.94 μ m | 10638 cm^{-1} | 550 cm^{-1} | 0.1 % |
| 0.885 μ m | 11299 cm^{-1} | 385 cm^{-1} | 0.1 % |
| 0.69 μ m | 14500 cm^{-1} | 1000 cm^{-1} | 0.1 % |

| IRFS-2 | | Infrared Sounding Spectrometer | |
|--|--|---|--|
| Satellites | Meteor-M-2 | | |
| Status (Sept 2006) | Being built – To be utilised in the period 2008 to ~ 2012 | | |
| Mission | Temperature/humidity sounding, ozone profile and total-column green-house gases | | |
| Instrument type | IR spectrometer/interferometer, 4000 channels | | |
| Scanning technique | Cross-track: 30 steps to cover a swath of 1000 km if contiguous, up to 2500 km with gaps | | |
| Coverage/cycle | Near-global coverage twice/day (with gaps) or once/day (continuous) | | |
| Resolution (s.s.p.) | 35 km IFOV | | |
| Spectral range (μm) | Spectral range (cm^{-1}) | Spectral resolution (unapodised) | Radiometric accuracy (NEΔT) |
| 5 – 15 μm | 667 – 2000 cm^{-1} | 0.5 cm^{-1} | 0.5 K @ 300 K |

| IRS | | Infra-Red Sounder | |
|---|--|----------------------------|--|
| Satellites | Meteosat-12 and follow-on (Meteosat Third Generation) | | |
| Status (Sept 2006) | Being defined - To be utilised from 2015 onward | | |
| Mission | Temperature/humidity sounding and wind profile derivation by tracking water vapour features | | |
| Instrument type | IR spectrometer/interferometer with large detector arrays for simultaneous sounding of more pixels | | |
| Coverage/cycle | Full disk in 30 min. Limited areas in correspondingly shorter time intervals | | |
| Resolution (s.s.p.) | 4.0 km | | |
| Spectral range (cm^{-1}) | Spectral range (μm) | Spectral resolution | Radiometric accuracy (NEΔT) |
| 700 - 1210 cm^{-1} | 14.3 - 8.26 μm | 0.625 cm^{-1} | 0.2-0.5 K @ 280 K |
| 1600 - 2175 cm^{-1} | 6.25 – 4.6 μm | 0.625 cm^{-1} | 0.2-0.8 K @ 280 K |

| JAMI | | Japanese Advanced Meteorological Imager | |
|----------------------------|---|---|--|
| Satellites | MTSAT- 1R | | |
| Status (Sept 2006) | Operational (Utilisation period: 2005 to 2010) | | |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features | | |
| Instrument type | 5-channel VIS/IR radiometer | | |
| Coverage/cycle | Full disk each 30 min. Half disk each 15 min. | | |
| Resolution (s.s.p.) | 4.0 km for IR channels; 1.0 km for the VIS channel | | |
| Central wavelength | Spectral interval | Radiometric accuracy (NEΔT or SNR) | |
| 0.725 μm | 0.55 - 0.90 μm | 6.5 @ 2.5 % albedo | |
| 3.75 μm | 3.50 - 4.00 μm | 0.18 K @ 300 K | |
| 6.75 μm | 6.50 - 7.00 μm | 0.18 K @ 300 K | |
| 10.8 μm | 10.3 - 11.3 μm | 0.15 K @ 300 K | |
| 12.0 μm | 11.5 - 12.5 μm | 0.18 K @ 300 K | |

| Klimat | | Infrared Imaging Radiometer | |
|----------------------------|--|--|--|
| Satellites | Meteor-3M | | |
| Status (Sept 2006) | Inactive – Utilised in the period: 2001 to ~ 2004 | | |
| Mission | Cloud imagery | | |
| Instrument type | 1-channel IR radiometer | | |
| Scanning technique | Cross-track, swath 3100 km – Along-track: two 3-km lines/s | | |
| Coverage/cycle | Global coverage twice/day | | |
| Resolution (s.s.p.) | 3.0 km IFOV | | |
| Central wavelength | Spectral interval | Radiometric accuracy (NEΔT) | |
| 11.5 μm | 10.5 – 12.5 μm | 0.5 K @ 300 K | |

| KMSS | High-resolution VIS/IR Radiometer |
|---------------------|---|
| Satellites | Meteor-M-1/2 |
| Status (Sept 2006) | Being built – To be utilised in the period 2007 to ~ 2012 |
| Mission | High-resolution imagery |
| Instrument type | 4-channel VIS/NIR radiometer |
| Scanning technique | Cross-track: 1210 CCD/line; swath up to 1000 km |
| Coverage/cycle | Duty cycle 10 %; to be operated with strategic pointing |
| Resolution (s.s.p.) | 50 - 100 m IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---------------------|---------------------------|----------------------------|
| 0.485 μm | 0.45 - 0.52 μm | 200 @ 100 % albedo |
| 0.555 μm | 0.53 – 0.58 μm | 200 @ 100 % albedo |
| 0.655 μm | 0.63 – 0.68 μm | 200 @ 100 % albedo |
| 0.845 μm | 0.79 – 0.90 μm | 200 @ 100 % albedo |

| LI | Lightning Imager |
|---------------------|---|
| Satellites | Meteosat-12 and follow-on (Meteosat Third Generation) |
| Status (Sept 2006) | Being defined - To be utilised from 2015 onward |
| Mission | Proxy for convective precipitation, proxy for NO _x generation, study of Earth electric field |
| Instrument type | CCD camera operating at 777.4 nm (O ₂) to count flashes and measure their intensity |
| Coverage/cycle | Full disk continuously observed (time resolution ~1 ms) |
| Resolution (s.s.p.) | 10 km |

| MERSI | Medium Resolution Spectral Imager |
|---------------------|--|
| Satellites | FY-3 A to G |
| Status (Sept 2006) | Close to launch – To be utilised in the period: 2007 to ~ 2023 |
| Mission | Vegetation indexes and ocean colour |
| Instrument type | 20-channel radiometer, 19 narrow-bandwidth in VIR/NIR/SWIR and one broadband in the Thermal IR |
| Scanning technique | Cross-track: 2048 (8192) pixels of 1 km (250 m) ssp, swath 2900 km - Along-track: ten 10-km lines each 1.5 s |
| Coverage/cycle | Global coverage in 1 day (in daylight) |
| Resolution (s.s.p.) | 250 m for broad-band channels, 1.0 km for narrow-band channels |

| Channel set | Central wavelength | Spectral range or Bandwidth | Radiometric accuracy (NE Δ T or NE Δ ρ) |
|--|----------------------|-----------------------------|---|
| Broad-band channels with 250 m resolution, mostly for clouds, vegetation and surface temperature | 0.470 μm | 0.445 - 0.495 μm | 0.45 % |
| | 0.550 μm | 0.525 - 0.575 μm | 0.4 % |
| | 0.650 μm | 0.625 - 0.675 μm | 0.3 % |
| | 0.865 μm | 0.840 - 0.890 μm | 0.3 % |
| | 11.250 μm | 10.0 - 12.5 μm | 0.3 K @ 300 K |
| Narrow-band channels with 1000 m resolution, for ocean colour, vegetation, aerosol | 412 nm | 20 nm | 0.1 % |
| | 443 nm | 20 nm | 0.1 % |
| | 490 nm | 20 nm | 0.05 % |
| | 520 nm | 20 nm | 0.05 % |
| | 565 nm | 20 nm | 0.05 % |
| | 650 nm | 20 nm | 0.05 % |
| | 685 nm | 20 nm | 0.05 % |
| | 765 nm | 20 nm | 0.05 % |
| | 865 nm | 20 nm | 0.05 % |
| | 905 nm | 20 nm | 0.10 % |
| | 940 nm | 20 nm | 0.10 % |
| | 980 nm | 20 nm | 0.10 % |
| | 1030 nm | 20 nm | 0.10 % |
| | 1640 nm | 50 nm | 0.05 % |
| | 2130 nm | 50 nm | 0.05 % |

| MHS | Microwave Humidity Sounder Unit | | |
|----------------------------|--|--------------|--------------------------------------|
| Satellites | NOAA 18 to 19 - Metop 1 to 3 | | |
| Status (Sept 2006) | Operational - Utilisation period: 2005 to ~ 2014 on NOAA, 2006 to ~ 2020 on MetOp | | |
| Mission | Humidity sounding in almost all-weather conditions. Also precipitation rate | | |
| Instrument type | 5-channel MW radiometer | | |
| Scanning technique | Cross-track: 90 steps of 16 km ssp, swath 2180 km - Along-track: one 16-km line each 8/3 s | | |
| Coverage/cycle | Near-global coverage twice/day | | |
| Resolution (s.s.p.) | 16 km IFOV | | |
| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Radiometric accuracy (NE Δ T) |
| 89.0 | 2800 | V | 0.22 K |
| 157.0 | 2800 | V | 0.38 K |
| 183.31 \pm 3.0 | 2000 | H | 0.42 K |
| 183.31 \pm 1.0 | 1000 | H | 0.57 K |
| 190.311 | 2000 | V | 0.45 K |

| MI | Meteorological Imager | | |
|----------------------------|---|---|--|
| Satellites | COMS 1 and 2 | | |
| Status (Sept 2006) | Being designed – To be utilised in the period 2008 to ~ 2021 | | |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features | | |
| Instrument type | 5-channel VIS/IR radiometer | | |
| Coverage/cycle | Full disk in 27 min. Limited areas in correspondingly shorter time intervals | | |
| Resolution (s.s.p.) | 1 km IFOV in 1 VIS channel, 4 km IFOV in 4 IR channels | | |
| Central wavelength | Spectral interval | Radiometric accuracy (NE Δ T or SNR) | |
| 0.675 μ m | 0.55 - 0.8 μ m | 10 @ 5 % albedo, 170 @ 100 % albedo | |
| 3.75 μ m | 3.50 - 4.0 μ m | 0.10 K @ 300 K | |
| 6.75 μ m | 6.5 - 7.0 μ m | 0.12 K @ 300 K | |
| 10.8 μ m | 10.3 - 11.3 μ m | 0.12 K @ 300 K | |
| 12 μ m | 11.5 - 12.5 μ m | 0.20 K @ 300 K | |

| MR-2000M1 | Television Camera | | |
|----------------------------|--|----------------------------|--|
| Satellites | Meteor-3M | | |
| Status (Sept 2006) | Inactive – Utilised in the period: 2001 to ~ 2005 | | |
| Mission | Cloud imagery | | |
| Instrument type | 1-channel television camera | | |
| Scanning technique | Cross-track swath 3100 km – Along-track: 4 lines/s | | |
| Coverage/cycle | Global coverage once/day (in daylight) | | |
| Resolution (s.s.p.) | 1.5 km IFOV | | |
| Central wavelength | Spectral interval | Radiometric accuracy (SNR) | |
| 0.65 μ m | 0.50 - 0.80 μ m | 250 @ 100 % albedo | |

| MSU-E | VIS/IR Imaging Radiometer | | |
|----------------------------|--|--|--|
| Satellites | Meteor-3M | | |
| Status (Sept 2006) | Inactive – Utilisation period: 2001 to ~ 2005 | | |
| Mission | High-resolution imagery | | |
| Instrument type | 3-channel VIS/NIR radiometer | | |
| Scanning technique | Cross-track: 1210 CCD/line; swath 46 km with pointing capability within 430 km | | |
| Coverage/cycle | Duty cycle 10 %; to be operated with strategic pointing | | |
| Resolution (s.s.p.) | 38 m IFOV | | |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---------------------|-----------------------------|----------------------------|
| 0.555 μm | 0.535 - 0.575 μm | 200 @ 100 % albedo |
| 0.655 μm | 0.63 - 0.68 μm | 200 @ 100 % albedo |
| 0.845 μm | 0.79 - 0.90 μm | 200 @ 100 % albedo |

| MSU-GS | Elektro-GOMS Imager |
|---------------------|---|
| Satellites | Elektro-L and follow on |
| Status (Sept 2006) | Being built -To be utilised from 2007 onward |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 10-channel VIS/IR radiometer |
| Coverage/cycle | Full disk each 15-30 min. |
| Resolution (s.s.p.) | 4.0 km for the IR channels, 1.0 km for the VNIR channels |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR or NE Δ T) |
|--------------------|---------------------------|---|
| 0.57 μm | 0.50 - 0.65 μm | 200 @ 100 % albedo |
| 0.72 μm | 0.65 - 0.80 μm | 200 @ 100 % albedo |
| 0.86 μm | 0.80 - 0.90 μm | 200 @ 100 % albedo |
| 3.75 μm | 3.50 - 4.00 μm | 0.35 K @ 300 K |
| 6.35 μm | 5.70 - 7.00 μm | 0.4 K @ 300 K |
| 8.00 μm | 7.50 - 8.50 μm | 0.1 K @ 300 K |
| 8.70 μm | 8.20 - 9.20 μm | 0.15 K @ 300 K |
| 9.70 μm | 9.20 - 10.2 μm | 0.15 K @ 300 K |
| 10.7 μm | 10.2 - 11.2 μm | 0.15 K @ 300 K |
| 11.7 μm | 11.2 - 12.5 μm | 0.25 K @ 300 K |

| MSU-MR | VIS/IR Imaging Radiometer | |
|---------------------|---|---|
| Satellites | Meteor-M-1/2 | |
| Status (Sept 2006) | Being built – To be utilised in the period 2007 to ~ 2012 | |
| Mission | Multi-purpose VIS/IR imagery | |
| Instrument type | 6-channel VIS/IR radiometer | |
| Scanning technique | Cross-track: 1540 pixels in line, swath 2800 km - Along-track: six 1-km lines/s | |
| Coverage/cycle | Global coverage twice/day (IR) or once/day (VIS) | |
| Resolution (s.s.p.) | 1.0 km IFOV | |
| Central wavelength | Spectral interval | Radiometric accuracy (SNR or NE Δ T) |
| 0.60 μm | 0.50 - 0.70 μm | 1000 @ 80 % albedo |
| 0.95 μm | 0.80 - 1.10 μm | 1000 @ 80 % albedo |
| 1.70 μm | 1.60 - 1.80 μm | 1000 @ 80 % albedo |
| 3.80 μm | 3.50 - 4.10 μm | 0.5 K @ 300 K |
| 11.00 μm | 10.5 - 11.5 μm | 0.15 K @ 300 K |
| 12.00 μm | 11.5 - 12.5 μm | 0.15 K @ 300 K |

| MTVZA | Imaging/Sounding Microwave Radiometer |
|--------------------|--|
| Satellites | Meteor-M-1/2 |
| Status (Sept 2006) | Being built – To be utilised in the period 2007 to ~ 2012 |
| Mission | Multi-purpose MW imager with temperature/humidity sounding channels for improved precipitation |
| Instrument type | 21-frequency / 29-channel MW radiometer |
| Scanning technique | Conical: 53.3° zenith angle, swath 1500 km – Scan rate: 24.9 scan/min = 15.8 km/scan |
| Coverage/cycle | Near-global coverage twice/day |
| Resolution | From 10 km at 183 GHz to 200 km at 10.6 GHz; consistent with an antenna diameter of 65 cm |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NE Δ T) | IFOV | Pixel |
|------------------------------------|-----------------|---------------|--------------------------|-----------|----------|
| 10.6 | 100 | V, H | 0.5 K | 89x198 km | 32x32 km |
| 18.7 | 200 | V, H | 0.4 K | 52x160 km | 32x32 km |
| 23.8 | 400 | V, H | 0.3 K | 42x94 km | 32x32 km |
| 31.5 | 400 | V, H | 0.3 K | 35x76 km | 32x32 km |
| 36.7 | 400 | V, H | 0.3 K | 30x67 km | 32x32 km |
| 42.0 | 400 | V, H | 0.4 K | 26x60 km | 32x32 km |
| 48.0 | 400 | V, H | 0.4 K | 24x43 km | 32x32 km |
| 52.80 | 400 | V | 0.4 K | 21x48 km | 48x48 km |
| 53.30 | 400 | V | 0.4 K | 21x48 km | 48x48 km |
| 53.80 | 400 | V | 0.4 K | 21x48 km | 48x48 km |
| 54.64 | 400 | V | 0.4 K | 21x48 km | 48x48 km |
| 55.63 | 400 | V | 0.4 K | 21x48 km | 48x48 km |
| 57.290344 \pm 0.3222 \pm 0.1 | 50 | H | 0.4 K | 21x48 km | 48x48 km |
| 57.290344 \pm 0.3222 \pm 0.05 | 20 | H | 0.7 K | 21x48 km | 48x48 km |
| 57.290344 \pm 0.3222 \pm 0.025 | 10 | H | 0.9 K | 21x48 km | 48x48 km |
| 57.290344 \pm 0.3222 \pm 0.01 | 5 | H | 1.3 K | 21x48 km | 48x48 km |
| 57.290344 \pm 0.3222 \pm 0.005 | 3 | H | 1.7 K | 21x48 km | 48x48 km |
| 91.655 | 2500 | V, H | 0.6 K | 14x30 km | 16x16 km |
| 183.31 \pm 7.0 | 1500 | V | 0.5 K | 9x21 km | 32x32 km |
| 183.31 \pm 3.0 | 1000 | V | 0.6 K | 9x21 km | 32x32 km |
| 183.31 \pm 1.0 | 500 | V | 0.8 K | 9x21 km | 32x32 km |

| MVIRI | | Meteosat Visible Infra-Red Imager | |
|----------------------------|---|---|--|
| Satellites | Meteosat 1 to 7 | | |
| Status (Sept 2006) | Operational - Utilisation period: 1977 to ~ 2008 | | |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features | | |
| Instrument type | 3-channel VIS/IR radiometer | | |
| Coverage/cycle | Full disk each 30 min. Limited areas in correspondingly shorter time intervals | | |
| Resolution (s.s.p.) | IFOV: 5.0 km for IR channels, 2.5 km for the VIS channel | | |
| Central wavelength | Spectral interval | Radiometric accuracy (SNR or NE Δ T) | |
| 0.70 μ m | 0.50 - 0.90 μ m | 3 @ 1 % albedo | |
| 6.40 μ m | 5.70 - 7.10 μ m | 1.0 K @ 250 K | |
| 11.5 μ m | 10.5 - 12.5 μ m | 0.5 K @ 300 K | |

| MVISR | | Multichannel Visible Infrared Scanning Radiometer | |
|----------------------------|---|--|--|
| Satellites | FY-1 A to D | | |
| Status (Sept 2006) | Operational - Utilisation period: 1988 to ~ 2006 | | |
| Mission | Multi-purpose VIS/IR imagery with emphasis on vegetation and ocean colour | | |
| Instrument type | 10-channel VIS/IR radiometer | | |
| Scanning technique | Cross-track: 2048 pixel of 800 m ssp, swath 2800 km - Along-track: six 1.1-km lines/s | | |
| Coverage/cycle | Global coverage twice/day (IR) or once/day (VIS) | | |
| Resolution (s.s.p.) | 1.1 km | | |
| Central wavelength | Spectral interval | Radiometric accuracy (SNR or NE Δ T) | |
| 0.455 μ m | 0.43 - 0.48 μ m | 3.0 @ 0.5 % albedo | |
| 0.505 μ m | 0.48 - 0.53 μ m | 3.0 @ 0.5 % albedo | |
| 0.555 μ m | 0.53 - 0.58 μ m | 3.0 @ 0.5 % albedo | |
| 0.630 μ m | 0.58 - 0.68 μ m | 3.0 @ 0.5 % albedo | |
| 0.865 μ m | 0.84 - 0.89 μ m | 3.0 @ 0.5 % albedo | |
| 0.932 μ m | 0.90 - 0.965 μ m | 3.0 @ 0.5 % albedo | |
| 1.600 μ m | 1.55 - 1.64 μ m | 3.0 @ 0.5 % albedo | |
| 3.740 μ m | 3.55 - 3.93 μ m | 0.40 K @ 300 K | |
| 10.80 μ m | 10.3 - 11.3 μ m | 0.22 K @ 300 K | |
| 12.00 μ m | 11.5 - 12.5 μ m | 0.22 K @ 300 K | |

| MWHS | Micro-Wave Humidity Sounder |
|----------------------------|--|
| Satellites | FY-3 A to G |
| Status (Sept 2006) | Close to be launched – To be utilised in the period: 2007 to ~ 2023 |
| Mission | Humidity sounding in nearly-all-weather conditions |
| Instrument type | 4-frequency / 5-channel MW radiometer |
| Scanning technique | Cross-track: 98 steps of 16 km ssp, swath 2700 km - Along-track: one 15-km line each 2.667 s |
| Coverage/cycle | Global coverage twice/day |
| Resolution (s.s.p.) | 15 km IFOV |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NE Δ) |
|-------------------------|-----------------|---------------|-------------------------|
| 150 | 1000 | V, H | 0.9 K |
| 183.31 \pm 7.0 | 2000 | V | 0.9 K |
| 183.31 \pm 3.0 | 1000 | V | 0.9 K |
| 183.31 \pm 1.0 | 500 | V | 1.1 K |

| MWRI | Micro-Wave Radiation Imager |
|------------------------------|--|
| Satellites | FY-3 A to G |
| Status (Sept 2006) | Close to be launched – To be utilised in the period 2007 to ~ 2023 |
| Mission | Multi-purpose MW imager |
| Instrument type | 6-frequency, 12-channel MW radiometer |
| Scanning technique | Conical: 53.1° zenith angle, swath 1400 km – Scan rate: 35.3 scan/min = 10 km/scan |
| Coverage/cycle | Global coverage once/day |
| Resolution (constant) | Changing with frequency, consistent with an antenna diameter of 90 cm |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NE Δ) | IFOV | Pixel |
|-------------------------|-----------------|---------------|-------------------------|-------------|------------|
| 10.65 | 180 | V, H | 0.5 K | 51 x 85 km | 70 x 70 km |
| 18.7 | 200 | V, H | 0.5 K | 30 x 50 km | 40 x 40 km |
| 23.8 | 400 | V, H | 0.8 K | 27 x 45 km | 30 x 30 km |
| 36.5 | 900 | V, H | 0.5 K | 18 x 30 km | 25 x 25 km |
| 89 | 4600 | V, H | 1.0 K | 9 x 15 km | 12 x 12 km |
| 150 | 3000 | V, H | 1.3 K | 7.5 x 12 km | 10 x 10 km |

| MWTS | Micro-Wave Temperature Sounder |
|----------------------------|---|
| Satellites | FY-3 A to G |
| Status (Sept 2006) | Close to be launched – To be utilised in the period 2007 to ~ 2023 |
| Mission | Temperature sounding in nearly-all-weather conditions |
| Instrument type | 4-frequency, 4-channel MW radiometer |
| Scanning technique | Cross-track: 15 steps of 62 km ssp, swath 2250 km - Along-track: one line of 118 km each 16 s |
| Coverage/cycle | Global coverage once/day |
| Resolution (s.s.p.) | 62 km IFOV |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Accuracy |
|-------------------------|-----------------|--------------|----------|
| 50.30 | 180 | V | 0.5 K |
| 53.596 \pm 0.115 | 340 | H | 0.4 K |
| 54.94 | 400 | V | 0.4 K |
| 57.290 | 330 | H | 0.4 K |

| OMPS | Ozone Mapping and Profiler Suite |
|----------------------------|---|
| Satellites | NPP, NPOESS 1 and 3 |
| Status (Sept 2006) | Being built. Limb component currently not baselined – Utilisation period: 2009 to ~ 2025 |
| Mission | Ozone profile and total-column or gross profile of other species. Tracked species: BrO, HCHO, NO ₂ , O ₃ , OCIO, SO ₂ |
| Instrument type | Three UV/VIS/NIR grating spectrometers for mapping, nadir profiling and limb sounding respectively |
| Scanning technique | Mapper: cross-track swath 2800 km, along-track one 50-km line in 7.6 s. Nadir profiler: one along-track sounding each 38 s (250 km). Limb sounder: 1-km vertical steps between 10 and 60 km |
| Coverage/cycle | Global coverage: mapper once/day, nadir profiler in 6 days, limb sounder in 4 days. Daylight only |
| Resolution (s.s.p.) | Mapper: 50 km. Nadir profiler: 250 km. Limb sounder: about 300 km |

| Subsystem | Spectral range | Spectral resolution | SNR at specified input radiance |
|------------------------------------|-----------------------|----------------------------|--|
| Cross-track mapper for total ozone | 300 - 380 nm | 1 nm | 1000 |
| Nadir-viewing ozone profiler | 250 - 310 nm | 1 nm | 35 (at 250 nm) to 400 (at 310 nm) |
| Limb scanning | 290 - 1000 nm | 1.5 to 40 nm | 320 (at 290 nm) to 1200 (at 600 nm) |

| Radiomet | Radio-occultation sounder |
|---------------------------|---|
| Satellites | Meteor-M-2 |
| Status (Sept 2006) | Being built – Utilisation period: 2008 to ~ 2012 |
| Mission | Temperature/humidity sounding with highest vertical resolution, space weather |
| Instrument type | GPS receiver measuring the phase delay due to refraction during occultation between GPS and LEO |
| Scanning technique | Limb scanning from 830 km to close-to-surface by time sampling – Azimuth 90° fore- and aft- |
| Coverage/cycle | About 500 soundings/day – Average spacing 1000 km – Global coverage (300 km spacing) in 10 days |
| Resolution | 300 km (horizontal), 0.5-1.0 km (vertical) |

| SAGE-III | Stratospheric Aerosol and Gas Experiment – III |
|---------------------------|---|
| Satellites | Meteor-3M |
| Status (Sept 2006) | Inactive - Utilisation period: 2001 to ~ 2005 |
| Mission | Atmospheric chemistry in the stratosphere. Species: H ₂ O, NO ₂ , NO ₃ , O ₃ , OCIO and aerosol |
| Instrument type | UV/VIS/NIR/SWIR (290-1550 nm) 9-band solar and lunar occultation grating spectrometer |
| Scanning technique | Sun and moon tracking during the occultation phase, 1-km step from ~ 10 to ~ 85 km |
| Coverage/cycle | N/A (few tens of events/day limited to latitudes above ~ 60°) |
| Resolution | 300 km (horizontal), 1-2 km (vertical) |

| SBUV/2 | Solar Backscatter Ultraviolet / 2 |
|---------------------------|---|
| Satellites | NOAA 9 to 19 except 12 and 15 |
| Status (Sept 2006) | Operational – Utilisation period: 1984 to ~ 2014 |
| Mission | Vertical profile of ozone and other species. Solar irradiance |
| Instrument type | UV spectro-radiometer. Either 12 discrete 1-nm bandwidth channels selectable in the interval 252 to 340 nm, or continuous sweep from 160 to 340 nm. |
| Scanning technique | Nadir view only |
| Coverage/cycle | About 1650 measurements/day. Global coverage (170 km spacing) in 10 days, in daylight |
| Resolution | 170 km |

| | |
|---------------------------|---|
| Severjanin | Onboard Radar Complex |
| Satellites | Meteor-M 1 and 2 |
| Status (Sept 2006) | Being built – Utilisation period: 2007 to ~ 2012 |
| Mission | High-resolution all-weather land observation |
| Instrument type | X-band SAR, frequency 9.623 GHz |
| Scanning technique | Side-looking 25-48°, swath 600 km |
| Coverage/cycle | Global coverage in 1 month (duty cycle 10-20 %) |
| Resolution | Two modes: 400-500 m or 700-1000 m |

| | |
|----------------------------|--|
| SEVIRI | Spinning Enhanced Visible Infra-Red Imager |
| Satellites | Meteosat 8 to 11 (Meteosat Second Generation) |
| Status (Sept 2006) | Operational - Utilisation period: 2002 to ~ 2019 |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 12-channel VIS/IR radiometer (11 narrow-bandwidth, 1 high-resolution broad-bandwidth VIS) |
| Coverage/cycle | Full disk each 15 min. Limited areas in correspondingly shorter time intervals |
| Resolution (s.s.p.) | 4.8 km IFOV, 3 km sampling for narrow channels; 1.4 km IFOV, 1 km sampling for broad VIS channel |

| Central wavelength | Spectral interval (99 % encircled energy) | Radiometric accuracy (SNR or NEAT) |
|-------------------------------|---|------------------------------------|
| N/A (broad bandwidth channel) | 0.6 – 0.9 μm | 4.3 @ 1 % albedo |
| 0.635 μm | 0.56 – 0.71 μm | 10.1 @ 1 % albedo |
| 0.81 μm | 0.74 – 0.88 μm | 7.28 @ 1 % albedo |
| 1.64 μm | 1.50 – 1.78 μm | 3 @ 1 % albedo |
| 3.92 μm | 3.48 – 4.36 μm | 0.35 K @ 300 K |
| 6.25 μm | 5.35 – 7.15 μm | 0.75 K @ 250 K |
| 7.35 μm | 6.85 – 7.85 μm | 0.75 K @ 250 K |
| 8.70 μm | 8.30 – 9.10 μm | 0.28 K @ 300 K |
| 9.66 μm | 9.38 – 9.94 μm | 1.50 K @ 255 K |
| 10.8 μm | 9.80 – 11.8 μm | 0.25 K @ 300 K |
| 12.0 μm | 11.0 – 13.0 μm | 0.37 K @ 300 K |
| 13.4 μm | 12.4 – 14.4 μm | 1.80 K @ 270 K |

| | |
|----------------------------|---|
| SOUNDER | GOES Sounder |
| Satellites | GOES 8 to 15 |
| Status (Sept 2006) | Operational – Utilisation period: 1994 to ~ 2015 |
| Mission | Temperature/humidity sounding |
| Instrument type | 19-channel IR radiometer (including one VIS) |
| Coverage/cycle | Full disk in 8 h, 3000x3000 km ² in 42 min, 1000x1000 km ² in 5 min |
| Resolution (s.s.p.) | 8.0 km |

| Wavelength | Wavenumber | Bandwidth | Radiometric accuracy (SNR or NE Δ T) |
|---------------|-----------------------|----------------------|---|
| 14.71 μ m | 680 cm^{-1} | 13 cm^{-1} | 1.24 K @ 290 K |
| 14.37 μ m | 696 cm^{-1} | 13 cm^{-1} | 0.79 K @ 290 K |
| 14.06 μ m | 711 cm^{-1} | 13 cm^{-1} | 0.68 K @ 290 K |
| 13.64 μ m | 733 cm^{-1} | 16 cm^{-1} | 0.55 K @ 290 K |
| 13.37 μ m | 748 cm^{-1} | 16 cm^{-1} | 0.49 K @ 290 K |
| 12.66 μ m | 790 cm^{-1} | 30 cm^{-1} | 0.23 K @ 290 K |
| 12.02 μ m | 832 cm^{-1} | 50 cm^{-1} | 0.14 K @ 290 K |
| 11.03 μ m | 907 cm^{-1} | 50 cm^{-1} | 0.10 K @ 290 K |
| 9.71 μ m | 1030 cm^{-1} | 25 cm^{-1} | 0.12 K @ 290 K |
| 7.43 μ m | 1345 cm^{-1} | 55 cm^{-1} | 0.06 K @ 290 K |
| 7.02 μ m | 1425 cm^{-1} | 80 cm^{-1} | 0.06 K @ 290 K |
| 6.51 μ m | 1535 cm^{-1} | 60 cm^{-1} | 0.15 K @ 290 K |
| 4.57 μ m | 2188 cm^{-1} | 23 cm^{-1} | 0.20 K @ 290 K |
| 4.52 μ m | 2210 cm^{-1} | 23 cm^{-1} | 0.17 K @ 290 K |
| 4.45 μ m | 2248 cm^{-1} | 23 cm^{-1} | 0.20 K @ 290 K |
| 4.13 μ m | 2420 cm^{-1} | 40 cm^{-1} | 0.14 K @ 290 K |
| 3.98 μ m | 2513 cm^{-1} | 40 cm^{-1} | 0.22 K @ 290 K |
| 3.74 μ m | 2671 cm^{-1} | 100 cm^{-1} | 0.14 K @ 290 K |
| 0.70 μ m | N/A | 0.05 μ m | @ % albedo |

| SOUNDER | INSAT Sounder |
|----------------------------|---|
| Satellites | INSAT-3D |
| Status (Sept 2006) | Being built – To be utilised in the period 2007 to ~ 2014 |
| Mission | Temperature/humidity sounding |
| Instrument type | 19-channel IR radiometer (including one VIS) |
| Coverage/cycle | 6000 km x 6000 km in 3 h. Smaller areas in correspondingly shorter time intervals |
| Resolution (s.s.p.) | 10.0 km |

| Wavelength | Wavenumber | Bandwidth | Radiometric accuracy (SNR or NE Δ T) |
|---------------|-----------------------|----------------------|---|
| 14.71 μ m | 680 cm^{-1} | 13 cm^{-1} | 1.50 K @ 320 K |
| 14.37 μ m | 696 cm^{-1} | 13 cm^{-1} | 1.00 K @ 320 K |
| 14.06 μ m | 711 cm^{-1} | 13 cm^{-1} | 0.50 K @ 320 K |
| 13.96 μ m | 716 cm^{-1} | 16 cm^{-1} | 0.50 K @ 320 K |
| 13.37 μ m | 748 cm^{-1} | 16 cm^{-1} | 0.50 K @ 320 K |
| 12.66 μ m | 790 cm^{-1} | 30 cm^{-1} | 0.30 K @ 320 K |
| 12.02 μ m | 832 cm^{-1} | 50 cm^{-1} | 0.15 K @ 320 K |
| 11.03 μ m | 907 cm^{-1} | 50 cm^{-1} | 0.15 K @ 320 K |
| 9.71 μ m | 1030 cm^{-1} | 25 cm^{-1} | 0.20 K @ 320 K |
| 7.43 μ m | 1345 cm^{-1} | 55 cm^{-1} | 0.20 K @ 320 K |
| 7.02 μ m | 1425 cm^{-1} | 80 cm^{-1} | 0.20 K @ 320 K |
| 6.51 μ m | 1535 cm^{-1} | 60 cm^{-1} | 0.20 K @ 320 K |
| 4.57 μ m | 2188 cm^{-1} | 23 cm^{-1} | 0.15 K @ 320 K |
| 4.52 μ m | 2210 cm^{-1} | 23 cm^{-1} | 0.15 K @ 320 K |
| 4.45 μ m | 2248 cm^{-1} | 23 cm^{-1} | 0.15 K @ 320 K |
| 4.13 μ m | 2420 cm^{-1} | 40 cm^{-1} | 0.15 K @ 320 K |
| 3.98 μ m | 2513 cm^{-1} | 40 cm^{-1} | 0.15 K @ 320 K |
| 3.74 μ m | 2671 cm^{-1} | 100 cm^{-1} | 0.15 K @ 320 K |
| 0.695 μ m | N/A | 0.05 μ m | 1000 @ 100 % albedo |

| SSM/I | Special Sensor Microwave - IMAGER |
|------------------------------|--|
| Satellites | DMSP F 8, 10, 11, 13, 14 and 15 |
| Status (Sept 2006) | Operational – Utilisation period: 1987 to ~ 2006 |
| Mission | Multi-purpose MW imager |
| Instrument type | 4-frequency, 7-channel MW radiometer |
| Scanning technique | Conical: 53.1° zenith angle, swath 1400 km – Scan rate: 31.9 scan/min = 12.5 km/scan |
| Coverage/cycle | Global coverage once/day |
| Resolution (constant) | Changing with frequency, consistent with an antenna diameter of 61 x 66 cm |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NEΔ) | IFOV | Pixel |
|-------------------------|-----------------|---------------|----------------|------------|----------------|
| 19.35 | 400 | V, H | 0.43 K | 45 x 68 km | 25.0 x 12.5 km |
| 22.235 | 400 | V | 0.73 K | 40 x 60 km | 25.0 x 12.5 km |
| 37.0 | 1500 | V, H | 0.38 K | 24 x 36 km | 25.0 x 12.5 km |
| 85.5 | 3000 | V, H | 0.71 K | 11 x 16 km | 12.5 x 12.5 km |

| SSM/T | Special Sensor Microwave - Temperature |
|----------------------------|--|
| Satellites | DMSP F 4 to 15 |
| Status (Sept 2006) | Operational – Utilisation period: 1979 to ~ 2006 |
| Mission | Temperature sounding in nearly-all-weather conditions |
| Instrument type | 7-channel MW radiometer |
| Scanning technique | Cross-track: 7 steps of 174 km ssp, swath 1500 km - Along-track: one 48-km line each 8 s |
| Coverage/cycle | Global coverage once/day |
| Resolution (s.s.p.) | 200 km IFOV |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Accuracy (NEΔ) |
|-------------------------|-----------------|--------------|----------------|
| 50.50 | 400 | H | 0.60 K |
| 53.20 | 400 | H | 0.40 K |
| 54.35 | 400 | H | 0.40 K |
| 54.90 | 400 | H | 0.40 K |
| 58.40 | 350 | H | 0.50 K |
| 58.825 | 300 | H | 0.40 K |
| 59.40 | 250 | H | 0.40 K |

| SSM/T-2 | Special Sensor Microwave - Humidity |
|----------------------------|--|
| Satellites | DMSP F 11, 12, 14, 15 |
| Status (Sept 2006) | Operational – Utilisation period: 1991 to ~ 2006 |
| Mission | Humidity sounding in nearly-all-weather conditions |
| Instrument type | 5-channel MW radiometer |
| Scanning technique | Cross-track: 28 steps of 42 km ssp, swath 1500 km - Along-track: one 48-km line each 8 s |
| Coverage/cycle | Global coverage once/day |
| Resolution (s.s.p.) | 48 km IFOV |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Accuracy (NEΔ) |
|-------------------------|-----------------|--------------|----------------|
| 91.655 ± 1.250 | 3000 | H | 0.6 K |
| 150.0 ± 1.250 | 1500 | H | 0.6 K |
| 183.31 ± 7.0 | 500 | H | 0.6 K |
| 183.31 ± 3.0 | 1000 | H | 0.6 K |
| 183.31 ± 1.0 | 1500 | H | 0.8 K |

| | |
|------------------------------|--|
| SSMIS | Special Sensor Microwave – Imager/Sounder |
| Satellites | DMSP F 16 and DMSP S 17 to 20 |
| Status (Sept 2006) | Operational – Utilisation period: 2003 to ~ 2016 |
| Mission | Multi-purpose MW imager with temperature/humidity sounding channels for improved precipitation |
| Instrument type | 21-frequency, 24-channel MW radiometer |
| Scanning technique | Conical: 53.1° zenith angle, swath 1700 km – Scan rate: 31.9 scan/min = 12.5 km/scan |
| Coverage/cycle | Global coverage once/day |
| Resolution (constant) | Changing with frequency, consistent with an antenna diameter of 61 x 66 cm |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NEΔT) | IFOV | Pixel |
|------------------------------|-----------------|---------------|-----------------|--------------|----------------|
| 19.35 | 400 | V, H | 0.7 K | 45 x 68 km | 25.0 x 12.5 km |
| 22.235 | 400 | V | 0.7 K | 40 x 60 km | 25.0 x 12.5 km |
| 37.0 | 1500 | V, H | 0.5 K | 24 x 36 km | 25.0 x 12.5 km |
| 50.3 | 400 | H | 0.4 K | 18 x 27 km | 37.5 x 12.5 km |
| 52.8 | 400 | H | 0.4 K | 18 x 27 km | 37.5 x 12.5 km |
| 53.596 | 400 | H | 0.4 K | 18 x 27 km | 37.5 x 12.5 km |
| 54.4 | 400 | H | 0.4 K | 18 x 27 km | 37.5 x 12.5 km |
| 55.5 | 400 | H | 0.4 K | 18 x 27 km | 37.5 x 12.5 km |
| 57.29 | 350 | - | 0.5 K | 18 x 27 km | 37.5 x 12.5 km |
| 59.4 | 250 | - | 0.6 K | 18 x 27 km | 37.5 x 12.5 km |
| 60.792668 ± 0.357892 ± 0.050 | 120 | V + H | 0.7 K | 18 x 27 km | 37.5 x 12.5 km |
| 60.792668 ± 0.357892 ± 0.016 | 32 | V + H | 0.6 K | 18 x 27 km | 75.0 x 12.5 km |
| 60.792668 ± 0.357892 ± 0.006 | 12 | V + H | 1.0 K | 18 x 27 km | 75.0 x 12.5 km |
| 60.792668 ± 0.357892 ± 0.002 | 6 | V + H | 1.8 K | 18 x 27 km | 75.0 x 12.5 km |
| 60.792668 ± 0.357892 | 3 | V + H | 2.4 K | 18 x 27 km | 75.0 x 12.5 km |
| 63.283248 ± 0.285271 | 3 | V + H | 2.4 K | 18 x 27 km | 75.0 x 12.5 km |
| 91.655 | 3000 | V, H | 0.9 K | 10 x 15 km | 12.5 x 12.5 km |
| 150 | 1500 | H | 0.9 K | ... x ... km | 37.5 x 12.5 km |
| 183.31 ± 6.6 | 1500 | H | 1.2 K | ... x ... km | 37.5 x 12.5 km |
| 183.31 ± 3.0 | 1000 | H | 1.0 K | ... x ... km | 37.5 x 12.5 km |
| 183.31 ± 1.0 | 500 | H | 1.2 K | ... x ... km | 37.5 x 12.5 km |

| | |
|----------------------------|---|
| S-VISSR | Stretched Visible and Infrared Spin Scan Radiometer |
| Satellites | FY-2 A to G |
| Status (Sept 2006) | Operational – Utilisation period: 1997 to ~ 2018 |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 5-channel VIS/IR radiometer |
| Coverage/cycle | Full disk each 30 min. Limited areas in correspondingly shorter time intervals |
| Resolution (s.s.p.) | 5.0 km for IR channels; 1.25 km for the VIS channel |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR or NEΔT) |
|--------------------|-------------------|------------------------------------|
| 0.77 μm | 0.55 - 0.99 μm | 1.5 @ 0.5 % albedo |
| 3.75 μm | 3.50 - 4.00 μm | 0.4 K @ 300 K |
| 6.95 μm | 6.30 - 7.60 μm | 0.5 K @ 300 K |
| 10.8 μm | 10.3 - 11.3 μm | 0.3 K @ 300 K |
| 12.0 μm | 11.5 - 12.5 μm | 0.3 K @ 300 K |

| TOU/SBUS | Total Ozone Unit and Solar Backscatter Ultraviolet Sounder |
|---------------------------|--|
| Satellites | FY-3 A to G |
| Status (Sept 2006) | Close to launch – Utilisation period: 2007 to ~ 2023 |
| Mission | Ozone total column and vertical profile |
| Instrument type | Two UV spectro-radiometers. TOU with 6 channels of 1.2 nm bandwidth in the range 308-360 nm, SBUS with 12 discrete channels of 1.15 nm bandwidth in the range 252-340 nm |
| Scanning technique | TOU cross-track scanning, swath 3000 km, SBUS nadir view only |
| Coverage/cycle | TOU: global coverage once/day. SBUS: global coverage (200 km spacing) in 7 days. Daylight |
| Resolution | 50 km for total ozone from TOU, 200 km for ozone profile from SBUS |

| VHRR (in GEO) | Very High Resolution Radiometer |
|----------------------------|---|
| Satellites | INSAT-1 A/B/C/D, INSAT-2 A/B/D/E, INSAT-3A, Kalpana |
| Status (Sept 2006) | Operational – Utilisation period: 1982 to ~ 2012 |
| Mission | Multi-purpose VIS/IR imagery and wind derivation by tracking clouds and water vapour features |
| Instrument type | 3-channel VIS/IR radiometer |
| Coverage/cycle | Full disk each 3 hours, more frequently on demand. Half-hourly triplets around 00 and 12 UT for winds |
| Resolution (s.s.p.) | 8.0 km for IR channels; 2 km for the VIS channel |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR or NE Δ T) |
|--------------------|---------------------|---|
| 0.65 μ m | 0.55 - 0.75 μ m | > 6 @ 2.5 % albedo |
| 6.40 μ m | 5.70 - 7.10 μ m | 0.50 K @ 300 K |
| 11.5 μ m | 10.5 - 12.5 μ m | 0.25 K @ 300 K |

| VIIRS | Visible/Infrared Imager Radiometer Suite |
|----------------------------|---|
| Satellites | NPP, NPOESS 1 to 4 |
| Status (Sept 2006) | Being built – Utilisation period: 2009 to ~ 2027 |
| Mission | Multi-purpose VIS/IR imagery, including ocean colour |
| Instrument type | 22-channel VIS/IR radiometer, including a day/night 0.7 μ m channel |
| Scanning technique | Cross-track: 16 parallel lines sampled by 2048 pixel of 800 m ssp and 32 parallel lines sampled by 4096 pixel of 400 m ssp; swath 3000 km. Along-track: one 11.9-km strip of 16 or 32 lines in 1.786 s. |
| Coverage/cycle | Global coverage twice/day (IR) or once/day (VIS) |
| Resolution (s.s.p.) | 400 m for five AVHRR-like channels and the VIS day/night channel, 800 m for all other channels |

| Channel set and resolution | Central wavelength | Bandwidth or Spectral interval | Radiometric accuracy (SNR or NE Δ T) |
|--|--------------------|--------------------------------|---|
| High-quality radiometric channels, resolution 800 m | 412 nm | 20 nm | @ % albedo |
| | 445 nm | 18 nm | @ % albedo |
| | 488 nm | 20 nm | @ % albedo |
| | 555 nm | 20 nm | @ % albedo |
| | 672 nm | 20 nm | @ % albedo |
| | 746 nm | 15 nm | @ % albedo |
| | 865 nm | 39 nm | @ % albedo |
| | 1240 nm | 20 nm | @ % albedo |
| | 1378 nm | 15 nm | @ % albedo |
| | 1610 nm | 60 nm | @ % albedo |
| | 2250 nm | 50 nm | @ % albedo |
| | 3.70 μ m | 0.18 μ m | K @ 300 K |
| | 4.05 μ m | 0.155 μ m | K @ 300 K |
| | 8.55 μ m | 0.30 μ m | K @ 300 K |
| 10.763 μ m | 1.00 μ m | K @ 300 K | |
| 12.013 μ m | 0.95 μ m | K @ 300 K | |
| Day/night band, resolution 400 m | 0.7 μ m | 0.5 - 0.9 μ m | @ % albedo |
| High-resolution imaging channels, resolution 400 m | 0.64 μ m | 0.60 - 0.68 μ m | @ % albedo |
| | 0.865 μ m | 0.845 - 0.884 μ m | @ % albedo |
| | 1.61 μ m | 1.58 - 1.64 μ m | @ % albedo |
| | 3.74 μ m | 3.55 - 3.93 μ m | K @ 300 K |
| | 11.45 μ m | 10.5 - 12.4 μ m | K @ 300 K |

| VIRR | Visible and Infra Red Radiometer |
|---------------------|---|
| Satellites | FY-3 A to G |
| Status (Sept 2006) | Close to launch – Utilisation period: 2007 to ~ 2023 |
| Mission | Multi-purpose VIS/IR imagery with emphasis on vegetation and ocean colour |
| Instrument type | 10-channel VIS/IR radiometer |
| Scanning technique | Cross-track: 2048 pixel of 800 m ssp, swath 2800 km - Along-track: six 1.1-km lines/s |
| Coverage/cycle | Global coverage twice/day (IR) or once/day (VIS) |
| Resolution (s.s.p.) | 1.1 km IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (NE $\Delta\rho$ or NE Δ T) |
|--------------------|-----------------------|---|
| 0.455 μ m | 0.43 - 0.48 μ m | 0.05 % |
| 0.505 μ m | 0.48 - 0.53 μ m | 0.05 % |
| 0.555 μ m | 0.53 - 0.58 μ m | 0.05 % |
| 0.630 μ m | 0.58 - 0.68 μ m | 0.10 % |
| 0.865 μ m | 0.84 - 0.89 μ m | 0.10 % |
| 1.360 μ m | 1.325 - 1.395 μ m | 0.19 % |
| 1.600 μ m | 1.55 - 1.64 μ m | 0.15 % |
| 3.740 μ m | 3.55 - 3.93 μ m | 0.3 K @ 300 K |
| 10.80 μ m | 10.3 - 11.3 μ m | 0.2 K @ 300 K |
| 12.00 μ m | 11.5 - 12.5 μ m | 0.2 K @ 300 K |

A3.2 Research and Development satellites

Table A3.2 - List of instruments, corresponding satellites and utilisation period

| Acronym | Full name | Satellites | Utilisation | Sheet |
|-----------|--|-------------------|------------------------|-------|
| ACRIM-2 | Active Cavity Radiometer Irradiance Monitor | UARS | 1991-2005 | |
| AIRS | Atmospheric Infra-Red Sounder | Aqua | 2002-2008 | X |
| ALI | Advanced Land Imager | NMP-EO-1 | 2000-2007 | X |
| ALT | Radar Altimeter | SeaSat | 1978 | |
| AMI-SAR | Active Microwave Instrument - SAR mode | ERS-1/2 | 1991-2008 | X |
| AMI-Scat | Active Microwave Instrument - Scat mode | ERS-1/2 | 1991-2008 | X |
| AMI-Wave | Active Microwave Instrument - Wave mode | ERS-1/2 | 1991-2008 | X |
| AMR | Advanced Microwave Radiometer | OSTM | 2008-2015 | |
| AMSR-E | Advanced Microwave Scanning Radiometer for EOS (AMSR on ADEOS-2) | EOS-Aqua, ADEOS-2 | 2002-2008 2002-2003 | X |
| APT | Automatic Picture Transmission | Nimbus-1/2 | 1964-1969 | |
| ASAR | Advanced Synthetic Aperture Radar – SAR mode | Envisat | 2002-2010 | X |
| ASAR-wave | Advanced Synthetic Aperture Radar – wave mode | Envisat | 2002-2010 | X |
| ASTER | Advanced Spaceborne Thermal Emission and Reflection radiometer | Terra | 1999-2007 | X |
| ATSR | Along-Track Scanning Radiometer (including ATSR-2 and AATSR) | ERS-1/2, Envisat | 1991-2010 | X |
| AVCS | Advanced Vidicon Camera System | Nimbus-1/2 | 1964-1969 | |
| AVNIR-1/2 | Advanced Visible and Near-Infrared Radiometer | ADEOS-1 ALOS | 1996-1997 2006-2010 | X |
| AWiFS | Advanced Wide Field Sensor | ResourceSat-1/2 | 2003-2014 | X |
| BlackJack | BlackJack | CHAMP | 2000-2006 | X |
| BUV | Backscatter Ultraviolet Spectrometer | Nimbus-4 | 1970-1980 | |
| CERES | Clouds and the Earth's Radiant Energy System | TRMM, Terra, Aqua | 1997-2006 | X |
| CLAES | Cryogenic Limb Array Etalon Spectrometer | UARS | 1991-2005 | |
| CZCS | Coastal Zone Colour Scanner | Nimbus-7 | 1978-1994 | |
| DCS | Data Collection System | Landsat-1/2/3 | 1972-1983 | |
| DCS | Data Collection System | ADEOS-2 | 2002-2003 | |
| Delta-2D | MW radiometer, conical scanning | Okean-O-1 | 1999-2000 | |
| DPR | Dual-frequency Precipitation Radar | GPM-core | 2012-2017 | X |
| ERB | Earth Radiation Budget) | Nimbus-6/7 | 1975-1994 | |
| ERBE | Earth Radiation Budget Experiment | ERBS, NOAA-9/10 | 1984-2001 | |
| ESMR | Electrically Scanning Microwave Radiometer | Nimbus-5/6 | 1972-1983 | |
| ETM | Enhanced Thematic Mapper | Landsat-6 | - | |
| ETM+ | Enhanced Thematic Mapper + | Landsat-7 | 1999-2009 | X |
| FWS | Filter Wedge Spectrometer | Nimbus-4 | 1970-1980 | |
| Geoton | Panchromatic and multispectral radiometer | Resurs-DK | 2006-2009 | X |
| GLAS | Geoscience Laser Altimeter System | ICESat | 2003-2007 | X |
| GLI | Global Imager | ADEOS-2 | 2002-2003 | |
| GMI | GPM Microwave Imager | GPM-core | 2012-2017 | X |
| GOLPE | GPS Occultation and Passive reflection Experiment | SAC-C | 2000-2002 | |
| GOME | Global Ozone Monitoring Experiment | ERS-2 | 1995-2008 | X |
| GOMOS | Global Ozone Monitoring by Occultation of Stars | Envisat | 2002-2010 | X |
| GPS | Global Positioning System | Landsat-4/5 | 1982-2008 | |
| GPS/MET | Global Positioning System / Meteorology | MicroLab-1 | 1995-2001 | |
| HALOE | Halogen Occultation Experiment | UARS | 1991-2005 | |
| HIRDLS | High-Resolution Dynamics Limb Sounder | Aura | 2004-2010 | X |
| HIRS | High-resolution Infra-Red Sounder | Nimbus-6 | 1975-1983 | |
| HR | Haut Résolution | Pléiades-1/2 | 2008-2015 | X |
| HRDI | High-Resolution Doppler Imager | UARS | 1991-2005 | |
| HRG | Haut Résolution Géométrique | SPOT-5 | 2002-2008 | X |
| HRIR | High Resolution Infrared Radiometer | Nimbus-1/2/3 | 1964-1972 | |
| HRS | Haut Résolution Stéréoscopique | SPOT-5 | 2002-2008 | X |
| HRV | Haut Résolution dans le Visible | SPOT-1/2/3 | 1986-2006 | X |
| HRVIR | Haut Résolution dans le Visible et l'Infra-Rouge | SPOT-4 | 1998-2007 | X |
| HSB | Humidity Sounder for Brazil | Aqua | 2002-2008 | X |

Table A3.2 (cont.) - List of instruments, corresponding satellites and utilisation period

| | | | | |
|-------------------------|--|--|-------------------------------------|---|
| Hyperion | Hyperion | NMP-EO-1 | 2000-2007 | x |
| IDCS | Image Dissector Camera System | Nimbus-3/4 | 1969-1980 | |
| IGOS | Integrated GPS Occultation Receiver | COSMIC | 2005-2010 | |
| ILAS-I/II | Improved Limb Atmospheric Spectrometer | ADEOS-1 ADEOS-2 | 1996-1997 2002-2003 | |
| IMG | Interferometric Monitor for Greenhouse gases | ADEOS-1 | 1996-1997 | |
| IRIS | Infra-Red Interferometer Spectrometer | Nimbus-3/4 | 1969-1980 | |
| IRLS | Interrogation, Recording and Location System | Nimbus-3/4 | 1969-1980 | |
| ISAMS | Improved Stratospheric and Mesospheric Sounder | UARS | 1991-2005 | |
| ITPR | Infrared Temperature Profile Radiometer | Nimbus-5 | 1972-1983 | |
| JMR | JASON Microwave Radiometer | JASON | 2001-2008 | X |
| Kondor | Data collection system | Okean-O1, SICH-1 | 1986-1996 | |
| LAC | LEISA (Linear Etalon Imaging Spectrometer Array) Atmospheric Corrector | NMP-EO-1 | 2000-2007 | X |
| LIS | Lightning Imaging Sensor | TRMM | 1997-2008 | X |
| LISS-1 | Linear Imaging Self-Scanning Sensor - 1 | IRS-1A/1B/1E | 1988-2001 | |
| LISS-2-A/B | Linear Imaging Self-Scanning Sensor - 2-A/B | IRS-1A/1B | 1988-2001 | |
| LISS-2-M | Linear Imaging Self-Scanning Sensor - 2-M | IRS-P2 | 1994-1997 | |
| LISS-3 | Linear Imaging Self-Scanning Sensor - 3 | IRS-1C/1D, ResourcesSat-1/2 | 1995-2014 | X |
| LISS-4 | Linear Imaging Self-Scanning Sensor - 4 | ResourceSat 1/2 | 2003-2014 | X |
| LRIR | Limb Radiance Inversion Radiometer | Nimbus-6 | 1975-1983 | |
| MADRAS | Microwave Analysis & Detection of Rain & Atmospheric Structures | Megha-Tropiques | 2009-2014 | X |
| MEOSS | Monocular Electro-Optical Stereo Scanner | IRS-1E/P1 | - | |
| MERIS | Medium Resolution Imaging Spectrometer | Envisat | 2002-2010 | X |
| MESSR | Multi-spectral Electronic Self-Scanning Radiometer | MOS 1/1B | 1987-1996 | |
| MIPAS | Michelson Interferometer for Passive Atmospheric Sounding | Envisat | 2002-2010 | X |
| MISR | Multi-angle Imaging Spectro-Radiometer | Terra | 1999-2007 | X |
| MLS | Microwave Limb Sounder | UARS Aura | 1991-2005 2004-2010 | X |
| MODIS | Moderate-resolution Imaging Spectro-radiometer | Terra, Aqua | 1999-2008 | X |
| MOPITT | Measurement Of Pollution In The Troposphere | Terra | 1999-2007 | X |
| MOS | Multispectral Opto-electronic Scanner | IRS-P3 | 1996-2004 | |
| MP-900B | TV camera | Resurs-O1-4 | 1998-2002 | |
| MRIR | Medium Resolution Infrared Radiometer | Nimbus-2/3 | 1966-1972 | |
| MS | Multispectral radiometer | Monitor-E | 2005-2008 | X |
| MSMR | Multi-frequency Scanning Microwave Radiometer | OceanSat-1/2 | 1999-2013 | X |
| MSR | Microwave Scanning Radiometer | MOS 1/1B | 1987-1996 | |
| MSS | Multi-Spectral Scanner | Landsat 1 to 5 | 1972-2008 | X |
| MSU-E & E1 | Multispectral VNIR radiometer | Resurs-O1 1 to 4 | 1985-2002 | |
| MSU-EU | Multispectral VNIR radiometer | SICH-1M | - | |
| MSU-M | Multispectral VNIR radiometer | Okean-O-1 | 1999-2000 | |
| MSU-SK & SK1 | Multispectral VNIR/IR conical scanning radiometer | Resurs-O1 1 to 4 Okean-O1 1 to 7 Okean-O-1, SICH-1 | 1985-2002 1986-1996 1995-2000 | |
| MSU-V | Multispectral VIS/IR radiometer | Okean-O-1 | 1999-2000 | |
| MTVZA-OK | Multispectral VIS/IR/MW radiometer | SICH-1M | - | |
| MUSE | Monitor of Ultraviolet Solar Energy | Nimbus-3/4 | 1969-1980 | |
| MWR | Micro-Wave Radiometer | ERS-1/2, Envisat | 1991-2010 | X |
| MWR | Microwave Radiometer, no-scanning | Okean-O1, SICH-1 | 1986-1996 | |
| NEMS | Nimbus-E Microwave Sounder | Nimbus-5 | 1972-1983 | |
| NRA | NASA Radar Altimeter | Topex-Poseidon | 1992-2006 | |
| NSCAT | NASA Scatterometer | ADEOS-1 | 1996-1997 | |
| OCM | Ocean Color Monitor | OceanSat-1/2 | 1999-2013 | X |
| OCTS | Ocean Color and Temperature Scanner | ADEOS-1 | 1996-1997 | |
| OLI | Operational Land Imager | LDCM | 2010→ | X |
| OMI | Ozone Monitoring Instrument | Aura | 2004-2010 | X |
| OPS | Optical Sensor | JERS | 1992-1998 | |
| OTD | Optical Transient Detector | MicroLab-1 | 1995-2001 | |

Table A3.2 (cont.) - List of instruments, corresponding satellites and utilisation period

| | | | | |
|---------------------|---|------------------------------------|-------------------------------------|---|
| PALSAR | Phased-Array L-band Synthetic Aperture Radar | ALOS | 2006-2010 | X |
| PAN | Panchromatic Camera | IRS-1C/1D | 1995-???? | |
| PAN | Panchromatic radiometer | Monitor-E | 2005-2008 | X |
| PAN-A, PAN-F | Panchromatic Cameras | CartoSat-1/2 | 2005-2015 | X |
| PASTEC | Technology Demonstration Passenger | SPOT-4 | 1998-2007 | |
| PEM | Particle Environment Monitor | UARS | 1991-2005 | |
| PMR | Pressure Modulator Radiometer | Nimbus-6 | 1975-1983 | |
| POAM | Polar Ozone and Aerosol Measurement | SPOT-3/4 | 1993-2007 | X |
| POLDER | Polarization and Directionality of the Earth's Reflectances | ADEOS-1 ADEOS-2 PARASOL | 1996-1997 2002-2003 2004-2007 | X |
| Poseidon-2 | Poseidon-2 | JASON | 2001-2008 | X |
| Poseidon-3 | Poseidon-3 | OSTM | 2008-2015 | |
| PR | Precipitation Radar | TRMM | 1997-2008 | X |
| PRISM | Panchromatic Remote-sensing Instrument for Stereo Mapping | ALOS | 2006-2010 | X |
| R225 | Microwave Radiometer, no-scanning | Okean-O-1 | 1999-2000 | |
| R600 | Microwave Radiometer, no-scanning | Okean-O-1 | 1999-2000 | |
| RA, RA-2 | Radar Altimeter | ERS-1/2, Envisat | 1991-2010 | X |
| RBV | Return-Beam Vidicon camera | Landsat-1/2/3 | 1972-1983 | |
| RIS | Retroreflector In Space | ADEOS-1 | 1996-1997 | |
| RLSBO | Side-looking radar | Okean-O1 1 to 7 Okean-O-1, SICH | 1986-1996 1999-2000 | |
| RM-08 | MW radiometer, conical scanning | Okean-O1, SICH | 1986-1996 | |
| SAGE-II | Stratospheric Aerosol and Gas Experiment - II | ERBS | 1984-2001 | |
| SAM-II | Stratospheric Aerosol Measurement - II | Nimbus-7 | 1978-1994 | |
| SAMS | Stratospheric and Mesospheric Sounder | Nimbus-7 | 1978-1994 | |
| SAPHIR | Sondeur Atmospherique du Profil d'Humidite Intertropicale par Radiometrie | Megha-Tropiques | 2009-2014 | X |
| SAR | Synthetic Aperture Radar | SeaSat | 1978 | |
| SAR | Synthetic Aperture Radar | JERS | 1992-1998 | |
| SAR-Travers | Two-frequency SAR | Resurs-O1-1 | 1985-1986 | |
| SASS | SeaSat-A Scatterometer System | SeaSat | 1978 | |
| SBUV | Solar Backscatter Ultraviolet Spectrometer | Nimbus-7 | 1978-1994 | |
| SCAMS | Scanning Microwave Spectrometer | Nimbus-6 | 1975-1983 | |
| ScaRaB | Scanner for Radiation Budget | Megha-Tropiques, Resurs-O1-4 | 2009-2014 1998-2002 | X |
| SCIAMACHY | Scanning Imaging Absorption Spectrometer for Atmospheric Cartography | Envisat | 2002-2010 | X |
| SCR | Selective Chopper Radiometer | Nimbus-4/5 | 1970-1983 | |
| SCRM | Surface Composition Mapping Radiometer | Nimbus-5 | 1972-1983 | |
| SeaWiFS | Sea-viewing Wide Field-of-view Sensor | SeaStar | 1997-2007 | X |
| SeaWinds | SeaWinds | QuickSCAT, ADEOS-2 | 1999-2007 2002-2003 | X |
| SIRS | Satellite Infra-Red Spectrometer | Nimbus-3/4 | 1969-1980 | |
| SMMR | Scanning Multichannel Microwave Radiometer) [| Nimbus-7, SeaSat | 1978-1994 | |
| SOLSTICE | Solar/Stellar Irradiance Comparison Experiment | UARS | 1991-2005 | |
| SSALT | Single-frequency Solid-state Altimeter | Topex-Poseidon | 1992-2006 | |
| SUSIM | Solar Ultraviolet Spectral Irradiance Monitor | UARS | 1991-2005 | |
| TANSO-CAI | Thermal And Near infrared Sensor for carbon Observations - Cloud and Aerosol Imager | GOSAT | 2008-2013 | X |
| TANSO-FTS | Thermal And Near infrared Sensor for carbon Observations - Fourier Transform Spectrometer | GOSAT | 2008-2013 | X |
| TES | Tropospheric Emission Spectrometer | Aura | 2004-2010 | X |
| THIR | Temperature-Humidity Infrared Radiometer | Nimbus-4/5/6/7 | 1970-1994 | |
| TM | Thematic Mapper | Landsat-4/5 | 1982-2008 | X |
| TMI | TRMM Microwave Imager | TRMM | 1997-2008 | X |
| TMR | TOPEX Microwave Radiometer | Topex-Poseidon | 1992-2006 | |
| TOMS | Total Ozone Mapping Spectrometer | Nimbus-7, ADEOS-1 | 1978-1994 1996-1997 | |

Table A3.2 (cont.) - List of instruments, corresponding satellites and utilisation period

| | | | | |
|-------------------|--|--------------------------|------------------------|---|
| Trasser | Polarisation spectro-radiometer | Okean-O1-3, Okean-O-1 | 1988-1990 1999-2000 | |
| TWERLE | Tropical Wind Energy-conversion and Reference Level Experiment | Nimbus-6 | 1975-1983 | |
| Végétation | Végétation | SPOT-4/5 | 1998-2008 | X |
| VIRR | Visible and Infra-Red Radiometer | SeaSat | 1978 | |
| VIRS | Visible and Infra-Red Scanner | TRMM | 1997-2008 | X |
| VTIR | Visible and Thermal Infrared Radiometer | MOS 1/1B | 1987-1996 | |
| WiFS | Wide Field Sensor | IRS-1C/1D/P3 | 1995-2004 | |
| WINDII | Wind Doppler Imaging Interferometer | UARS | 1991-2005 | |
| WindSat | WindSat | Coriolis | 2003-2008 | X |
| X-AE | X-ray Astronomy Experiment | IRS-P3 | 1996-2004 | |

Table A3.4 - List of the provided instrument sheets ordered by type of sensor and R&D agency

| SUNSYNCHRONOUS | ESA | NASA | CNES | JAXA | ISRO | RosKosmos |
|---|-------------------------------|--|--------------------------|----------------|-------------------------------------|------------------|
| Medium-resolution VIS or VIS/IR imagers | ATSR-2, AATSR, MERIS | MODIS, LAC, SeaWiFS, VIRS | Vegetation | TANSO-CAI | OCM | |
| High-resolution imagers for land observation | | MSS, TM, ETM+, ASTER, ALI, OLI, Hyperion | HR, HRG, HRS, HRV, HRVIR | AVNIR-2, PRISM | AWiFS, LISS-3, LISS-4, PAN-A, PAN-F | Geoton, MS, PAN |
| IR advanced sounders | | AIRS | | | | |
| MW imagers | | AMSR-E, GMI, TMI, WindSat | MADRAS | | MSMR | |
| MW humidity sounders | | HSB | SAPHIR | | | |
| Precipitation radar | | DPR, PR | | | | |
| Lightning mapper | | LIS | | | | |
| Radio-occultation | | BlackJack | | | | |
| Radar altimeter | RA / RA-2 + MWR | | Poseidon-2 + JMR | | | |
| Lidar altimeter | | GLAS | | | | |
| Radar scatterometer | AMI-Scat | SeaWinds | | | | |
| SAR | AMI-SAR, ASAR | | | PALSAR | | |
| Waves | AMI-wave, ASAR-wave | | | | | |
| Aerosol & ERB | | CERES, MISR | POLDER, ScaRaB | | | |
| Atmospheric chemistry | GOMOS, MIPAS, GOME, SCIAMACHY | MLS, OMI, TES, HIRDLS, MOPITT, | POAM | TANSO-FTS | | |

| AIRS | Atmospheric Infra-Red Sounder |
|----------------------------|--|
| Satellite | EOS-Aqua |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2008 |
| Mission | Temperature/humidity sounding, ozone profile and total-column green-house gases |
| Instrument type | Grating spectrometer, 2378 channels, resolving power $\lambda/\Delta\lambda = 1200$, 4 supporting channels in VIS/NIR |
| Scanning technique | Cross-track: 90 samples scanned, swath 1650 km - Along-track: one 13.5-km line each 2.67 s |
| Coverage/cycle | Global coverage once/day |
| Resolution (s.s.p.) | 13.5 km IFOV for the spectrometer; 2.3 km IFOV for VIS/NIR channels |

| Spectral range (μm) | Spectral range (cm^{-1}) | Spectral resolution | Accuracy (NEΔT or SNR) |
|--|---|----------------------------|---|
| 3.74 - 4.61 μm | 2170 - 2674 cm^{-1} | ~ 2.0 cm^{-1} | 0.14 K @ 280 K |
| 6.20 - 8.22 μm | 1216 - 1613 cm^{-1} | ~ 1.0 cm^{-1} | 0.20 K @ 280 K |
| 8.80 - 15.4 μm | 650 - 1136 cm^{-1} | ~ 0.5 cm^{-1} | 0.35 K @ 280 K |
| 0.41-0.44 μm | not relevant | 30 nm | > 100 @ 40 % albedo |
| 0.58-0.68 μm | not relevant | 100 nm | > 100 @ 40 % albedo |
| 0.71-0.92 μm | not relevant | 210 nm | > 100 @ 40 % albedo |
| 0.49-0.94 μm | not relevant | N/A (broadband) | > 100 @ 40 % albedo |

| ALI | Advanced Land Imager |
|----------------------------|--|
| Satellite | NMP EO-1 |
| Status (Sept 2006) | Technological demonstration running – To be utilised in the period 2000-2007 |
| Mission | Advanced technology for land and vegetation observation |
| Instrument type | VIS/NIR radiometer, 9 VIS/NIR narrow-band channels, one panchromatic (PAN) |
| Scanning technique | Pushbroom; 1230 pixel/line (9 narrow-band channels), 3700 pixel/line (PAN); swath 37 km [reduced configuration for demonstration purpose - there should be 5 such arrays, to cover a 185 km swath] |
| Coverage/cycle | Global coverage in 80 days, in daylight [for full configuration it would be 16 days] |
| Resolution (s.s.p.) | 30 m (9 narrow-band channels), 10 m (PAN) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---------------------------|--------------------------|-----------------------------------|
| 443 nm | 433 - 453 nm | @ % albedo |
| 482 nm | 450 - 515 nm | @ % albedo |
| 565 nm | 525 - 605 nm | @ % albedo |
| 660 nm | 630 - 690 nm | @ % albedo |
| 790 nm | 775 - 805 nm | @ % albedo |
| 867 nm | 845 - 890 nm | @ % albedo |
| 1250 nm | 1200 - 1300 nm | @ % albedo |
| 1650 nm | 1550 - 1750 nm | @ % albedo |
| 2215 nm | 2080 - 2350 nm | @ % albedo |
| Panchromatic | 480 - 690 nm | @ % albedo |

| AMI-SAR | Active Microwave Instrument - SAR mode |
|---------------------------|--|
| Satellites | ERS-1 and ERS-2 |
| Status (Sept 2006) | Operational – Utilised in the period 1991 to ~ 2008 |
| Mission | High-resolution all-weather multi-purpose imager for ocean, land and ice |
| Instrument type | C-band SAR, frequency 5.3 GHz, polarisation V |
| Scanning technique | Side-looking, 23° off-nadir, swath 100 km |
| Coverage/cycle | Global coverage in 9 months average, depending on operation mode (duty cycle 12 %) |
| Resolution | 30 m |

| AMI-Scat | Active Microwave Instrument - Scat mode |
|---------------------------|---|
| Satellites | ERS-1 and ERS-2 |
| Status (Sept 2006) | Operational – Utilised in the period 1991 to ~ 2008 |
| Mission | Sea surface wind vector. Also large-scale soil moisture |
| Instrument type | C-band radar scatterometer (5.3 GHz), 3 side looking antennas |
| Scanning technique | One 500-km swaths starting from 200 km off-track. 3 looks each pixel (45, 90 and 135° azimuth) |
| Coverage/cycle | Global coverage in 3 days average, depending on operation mode (alternative to AMI-SAR, thus duty cycle about 80 %) |
| Resolution | Best quality: 50 km; sampling: 25 km |

| AMI-Wave | Active Microwave Instrument - Wave mode |
|---------------------------|--|
| Satellites | ERS-1 and ERS-2 |
| Status (Sept 2006) | Operational – Utilised in the period 1991 to ~ 2008 |
| Mission | Wave spectra (power, direction, period/length) |
| Instrument type | C-band SAR, frequency 5.3 GHz, polarisation V |
| Scanning technique | By processing 5 x 5 km ² 30-m resolution SAR imagerettes within the SAR swath, 350 km off-track, sampling at 200 or 300 km intervals. The AMI wave mode can be operated at the same time as the AMI scat mode |
| Coverage/cycle | Global coverage in 1.5 months (duty cycle 70 %) |
| Resolution | 5 x 5 km ² imagerettes sampled at 200 or 300 km intervals |

| AMSR-E | Advanced Microwave Scanning Radiometer for EOS |
|---------------------------|---|
| Satellites | EOS-Aqua (AMSR-E) and ADEOS-2 (AMSR) |
| Status (mid-2006) | Operational (on EOS-Aqua) - Utilisation period: 2002 to ~ 2008 |
| Mission | Multi-purpose MW imager |
| Instrument type | MW radiometer with 6 frequencies / 12 channels (AMSR: 8 frequencies / 14 channels) |
| Scanning technique | Conical: 55° zenith angle; swath: 1450 km (AMSR: 1600 km) - Scan rate: 40 scan/min = 10 km/scan |
| Coverage/cycle | Global coverage once/day |
| Resolution | Changing with frequency, consistent with an antenna diameter of 1.6 m (AMSR: 2.0 m) |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NEΔT) | IFOV | Pixel |
|-------------------------|-----------------|---------------|-----------------|------------|------------|
| 6.925 | 350 | V, H | 0.3 K | 43 x 75 km | 10 x 10 km |
| 10.65 | 100 | V, H | 0.6 K | 29 x 51 km | 10 x 10 km |
| 18.7 | 200 | V, H | 0.6 K | 16 x 27 km | 10 x 10 km |
| 23.8 | 400 | V, H | 0.6 K | 14 x 21 km | 10 x 10 km |
| 36.5 | 1000 | V, H | 0.6 K | 9 x 14 km | 10 x 10 km |
| 50.2 (AMSR) | 200 | H | 1.8 K | 7 x 10 km | 10 x 10 km |
| 53.8 (AMSR) | 400 | H | 1.6 K | 7 x 10 km | 10 x 10 km |
| 89.0 | 3000 | V, H | 1.1 K | 4 x 6 km | 5 x 5 km |

| ASAR | Advanced Synthetic Aperture Radar - SAR mode |
|---------------------------|--|
| Satellite | Envisat |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2010 |
| Mission | High-resolution all-weather multi-purpose imager for ocean, land and ice |
| Instrument type | C-band SAR, frequency 5.3 GHz, multi-polarisation and variable pointing/resolution |
| Scanning technique | Side-looking, 15-45° off-nadir, swath 100 to 405 km, depending on operation mode – See table |
| Coverage/cycle | Global coverage in 5 day for the 'global monitoring' mode (duty cycle 70 %); in longer periods for other operation modes (duty cycle 30 %), up to 3 months |
| Resolution | 30 m to 1 km, depending on operation mode – See table |

| Operation mode | Resolution | Swath | Polarisation | Incidence angle |
|---------------------------|------------|----------------------|---------------------|---------------------------------|
| Stripmap | 30 m | 100 km within 485 km | HH or VV | 7 possibilities from 15° to 45° |
| ScanSAR alternating pol | 30 m | 100 km within 485 km | VV/HH, HH/HV, VV/VH | 7 possibilities from 15° to 45° |
| ScanSAR wide swath | 150 m | 405 km | HH or VV | ~ 23° |
| ScanSAR wide swath | 150 m | 405 km | HH or VV | ~ 23° |
| ScanSAR global monitoring | 1 m | 405 km | HH or VV | ~ 23° |

| ASAR-Wave | Advanced Synthetic Aperture Radar - Wave mode |
|--------------------|---|
| Satellite | Envisat |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2010 |
| Mission | Wave spectra (power, direction, period/length) |
| Instrument type | C-band SAR, frequency 5.3 GHz, polarisation HH or VV |
| Scanning technique | By processing 5 x 5 km ² 30-m resolution SAR imagettes within the SAR swath of 485 km. Sampling at 100 km intervals. The ASAR wave mode can be operated at the same time as the global monitoring mode |
| Coverage/cycle | Global coverage in 1 month (duty cycle 70 %) |
| Resolution | 5 x 5 km ² imagettes sampled at 100 km intervals |

| ASTER | Advanced Spaceborne Thermal Emission and Reflection radiometer |
|---------------------|---|
| Satellite | EOS-Terra |
| Status (Sept 2006) | Operational – Utilised in the period 1999 to ~ 2007 |
| Mission | Land and vegetation observation |
| Instrument type | 14-channel radiometer in three sub-systems, VIS/NIR (3 channels), SWIR (6 channels), TIR (5 channels) |
| Scanning technique | VNIR and SWIR pushbroom; 4000 pixel/line (VNIR), 2000 pixel/line (SWIR); TIR whiskbroom (670 pixel/line; swath 60 km ssp; cross-track pointing capability within a range of ± 318 km (VNIR) or ± 116 km (SWIR and TIR); along-track stereoscopic viewing in one NIR channel (0.81 µm) |
| Coverage/cycle | By exploiting strategic pointing, any place within 16 days, or within 5 days limited to VNIR in daylight |
| Resolution (s.s.p.) | 15 m (VNIR), 30 m (SWIR), 90 m (TIR) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR or NEΔT) |
|--------------------|-------------------|------------------------------------|
| 0.56 µm | 0.52 - 0.60 µm | @ % albedo |
| 0.66 µm | 0.63 - 0.69 µm | @ % albedo |
| 0.81 µm | 0.76 - 0.86 µm | @ % albedo |
| 1.65 µm | 1.60 - 1.70 µm | @ % albedo |
| 2.165 µm | 2.145 - 2.185 µm | @ % albedo |
| 2.205 µm | 2.185 - 2.225 µm | @ % albedo |
| 2.260 µm | 2.235 - 2.285 µm | @ % albedo |
| 2.330 µm | 2.295 - 2.365 µm | @ % albedo |
| 2.395 µm | 2.360 - 2.430 µm | @ % albedo |
| 8.30 µm | 8.125 - 8.475 µm | K @ K |
| 8.65 µm | 8.475 - 8.825 µm | K @ K |
| 9.10 µm | 8.925 - 9.275 µm | K @ K |
| 10.60 µm | 10.25 - 10.95 µm | K @ K |
| 11.30 µm | 10.95 - 11.65 µm | K @ K |

| ATSR | Along-Track Scanning Radiometer |
|---------------------|---|
| Satellites | ERS-1 (ATSR), ERS-2 (ATSR-2) and Envisat (AATSR) |
| Status (Sept 2006) | Operational – Utilised in the period 1991 to ~ 2010 |
| Mission | Multi-purpose VIS/IR imagery, with emphasis on very accurate sea surface temperature for climate |
| Instrument type | 7-channel VIS/IR radiometer with dual view for accurate atmospheric corrections |
| Scanning technique | Conical oblique (cross-nadir and 47° fore); 2000 pixel of 1 km ssp; swath 500 km; scan rate 400 rpm |
| Coverage/cycle | Global coverage in 3 days (IR) or 6 days (VIS) |
| Resolution (s.s.p.) | 1 km IFOV |

| Central wavelength | Bandwidth | Radiometric accuracy (NE Δ T or SNR) |
|--------------------|---------------------|---|
| 550 nm | 20 nm | 20 @ 0.5 % albedo |
| 659 nm | 20 nm | 20 @ 0.5 % albedo |
| 865 nm | 20 nm | 20 @ 0.5 % albedo |
| 1610 nm | 300 nm | 20 @ 0.5 % albedo |
| 3.70 μ m | 3.55-3.85 μ m | 0.08 K @ 270 K |
| 10.85 μ m | 10.35-11.35 μ m | 0.05 K @ 270 K |
| 12.00 μ m | 11.50-12.50 μ m | 0.05 K @ 270 K |

| AVNIR-2 | Advanced Visible and Near-Infrared Radiometer - 2 |
|---------------------|---|
| Satellites | ALOS and ADEOS-1 (AVNIR) |
| Status (Sept 2006) | Operational on ALOS – To be utilised in the period 2006 to ~ 2010 (AVNIR: 2002-2003) |
| Mission | Vegetation observation |
| Instrument type | 4-channel VIS/NIR radiometer (AVNIR: 5 channels) |
| Scanning technique | Bushbroom, 7000 pixel/line, swath 70 km ssp, possible to be pointed cross-track within a swath of 1400 km |
| Coverage/cycle | Global coverage in 46 days, in daylight. With strategic pointing, one place can be observed each 2 days. |
| Resolution (s.s.p.) | 10 m IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|----------------------|---------------------|--|
| 0.46 μ m | 0.42 - 0.50 μ m | 200 @ 25 % albedo |
| 0.56 μ m | 0.52 - 0.60 μ m | 200 @ 29 % albedo |
| 0.65 μ m | 0.61 - 0.69 μ m | 200 @ 41 % albedo |
| 0.825 μ m | 0.76 - 0.89 μ m | 200 @ 59 % albedo |
| 0.60 μ m (AVNIR) | 0.52 - 0.69 μ m | 100 @ 100 % albedo or 5 @ 3.3 % albedo |

| AWiFS | Advanced Wide Field Sensor |
|---------------------|--|
| Satellite | IRS-P6 (ResourceSat-1) and ResourceSat-2 |
| Status (Sept 2006) | Operational - Utilisation period: 2003 to ~ 2014 |
| Mission | Land and vegetation observation |
| Instrument type | Two parallel radiometers, 4 VIS/NIR/SWIR channels |
| Scanning technique | Bushbroom, 12000 pixel/line, swath 740 km (with two instruments) |
| Coverage/cycle | Global coverage in 5 days, in daylight |
| Resolution (s.s.p.) | 56 m IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------|---------------------|----------------------------|
| 0.555 μ m | 0.52 - 0.59 μ m | @ % albedo |
| 0.650 μ m | 0.62 - 0.68 μ m | @ % albedo |
| 0.815 μ m | 0.77 - 0.86 μ m | @ % albedo |
| 1.625 μ m | 1.55 - 1.70 μ m | @ % albedo |

| BlackJack | BlackJack |
|--------------------|--|
| Satellites | CHAMP, Microlab-1 (GPS/MET), SAC-C (GOLPE), COSMIC constellation (IGOS), |
| Status (Sept 2006) | Operational – Utilised in the period 1995 to ~ 2010 |
| Mission | Temperature/humidity sounding with highest vertical resolution, space weather |
| Instrument type | GPS receiver measuring the phase delay due to refraction during occultation between GPS and LEO |
| Scanning technique | Limb scanning from 830 km to close-to-surface by time sampling – Azimuth: 90° sectors fore- and aft- |
| Coverage/cycle | About 500 soundings/day – Average spacing 1000 km – Global coverage (300 km spacing) in 10 days |
| Resolution | About 300 km horizontal, 0.5 km vertical |

| CERES | Clouds and the Earth's Radiant Energy System |
|---------------------|--|
| Satellites | TRMM, EOS-Terra and EOS-Aqua |
| Status (Sept 2006) | Operational – Utilised in the period 1997 to ~ 2008 |
| Mission | Earth radiation budget |
| Instrument type | Two broad-band and one narrow-band channel radiometer |
| Scanning technique | Cross-track: 80 steps of 20 km ssp, swath 3000 km - Along-track: one 20-km line each 3 s |
| Coverage/cycle | Global coverage twice/day (IR and total radiance) or once/day (short-wave) |
| Resolution (s.s.p.) | 20 km |

| Channel | Spectral interval | Noise Equivalent Radiance | Absolute accuracy | SNR |
|----------------|-------------------------|--------------------------------------|--------------------------------------|-------|
| Narrow-band | 8 - 12 μm | $\text{Wm}^{-2}\text{sr}^{-1}$ | $\text{Wm}^{-2}\text{sr}^{-1}$ | |
| Short-wave | 0.3 - 5.0 μm | $\text{Wm}^{-2}\text{sr}^{-1}$ | $\text{Wm}^{-2}\text{sr}^{-1}$ | |
| Total radiance | 0.3 - 100 μm | $\text{Wm}^{-2}\text{sr}^{-1}$ | $\text{Wm}^{-2}\text{sr}^{-1}$ | |

| DPR | Dual-frequency Precipitation Radar |
|---------------------|--|
| Satellite | GPM-core |
| Status (Sept 2006) | Planned – To be utilised in the period 2012 to ~ 2017 |
| Mission | Vertical profile of precipitation |
| Instrument type | Dual-frequency imaging radar, frequencies 13.6 GHz and 35.55 GHz |
| Scanning technique | Electronic scanning, planar array of 148 elements, swath 245 km at 13.6 GHz, 120 km at 35.55 GHz |
| Coverage/cycle | Nearly-global in 5 days, high-latitudes ($> 65^\circ$) not covered |
| Resolution (s.s.p.) | Horizontal 5.0 km, vertical 250 m (blind to the lowest ~ 150 m) |

| ETM+ | Enhanced Thematic Mapper + |
|---------------------|---|
| Satellite | Landsat-7 |
| Status (Sept 2005) | Operational – Utilised in the period 1999 to ~ 2006 |
| Mission | Land and vegetation observation |
| Instrument type | VIS/NIR radiometer, 6 VIS/NIR narrow-band channels, one panchromatic (PAN), one in TIR |
| Scanning technique | Wiskbroom; 6000 pixel/line (narrow-band), 12000 pixel/line (PAN), 3000 pixel/line (TIR); swath 185 km |
| Coverage/cycle | Global coverage in 16 days, in daylight. |
| Resolution (s.s.p.) | 30 m (6 narrow-band channels), 15 m (PAN), 60 m (TIR) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---------------------|---------------------------|----------------------------|
| 0.48 μm | 0.45 - 0.52 μm | 32 @ % albedo |
| 0.56 μm | 0.53 - 0.61 μm | 35 @ % albedo |
| 0.66 μm | 0.63 - 0.69 μm | 26 @ % albedo |
| 0.83 μm | 0.78 - 0.90 μm | 32 @ % albedo |
| 1.65 μm | 1.55 - 1.75 μm | 25 @ % albedo |
| 2.20 μm | 2.09 - 2.35 μm | 17 @ % albedo |
| Panchromatic | 0.50 - 0.90 μm | 15 @ % albedo |
| 11.45 μm | 10.4 - 12.5 μm | 0.5 K @ 300 K |

| Geoton | Panchromatic and multispectral radiometer |
|---------------------|--|
| Satellite | Resurs-DK |
| Status (Sept 2006) | Operational – Utilisation period: 2006 to ~ 2009 |
| Mission | Land and vegetation observation |
| Instrument type | 3-channel VIS/NIR radiometer (multispectral), 1 channel in panchromatic mode (0.58-0.8 μm) |
| Scanning technique | Bushbroom, 12000 pixel/line; swath 30 km addressable within an area of regard of 450 km |
| Coverage/cycle | Global coverage in 80 days, in daylight; locally more frequent by strategic pointing |
| Resolution (s.s.p.) | 2-3 m in multi-spectral mode, 1 m in panchromatic mode |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------|-------------------------|----------------------------|
| 0.55 μm | 0.5 – 0.6 μm | @ % albedo |
| 0.65 μm | 0.6 – 0.7 μm | @ % albedo |
| 0.75 μm | 0.7 – 0.8 μm | @ % albedo |

| GLAS | Geoscience Laser Altimeter System |
|--------------------|---|
| Satellite | ICESat |
| Status (Sept 2006) | Operational – Utilised in the period 2003 to ~ 2007 |
| Mission | Polar ice sheet thickness and topography. Also cloud top height and aerosol |
| Instrument type | Two-wavelengths (532 and 1064 nm) lidar |
| Scanning technique | Nadir-only viewing, sampling at 170 m intervals along track, near continuous profiling |
| Coverage/cycle | Global coverage in 183 d (orbit repeat cycle) leaving cross-track 2.5 km gaps at 80° latitude, 15 km at equator |
| Resolution | Horizontal: 66 m IFOV sampled at 170 m intervals along track. Vertical: 10 cm surface, 200 m cloud top |

| GMI | GPM Microwave Imager |
|--------------------|---|
| Satellite | GPM-core |
| Status (Sept 2006) | Planned – To be utilised in the period 2012 to ~ 2017 |
| Mission | Multi-purpose MW imager, with emphasis on precipitation |
| Instrument type | MW radiometer with 7 frequencies / 13 channels |
| Scanning technique | Conical: 53° zenith angle; useful swath: 850 km - Scan rate: 32 scan/min = 12.8 km/scan |
| Coverage/cycle | Global coverage in 2 days; high latitudes (> 70°) not covered |
| Resolution | Changing with frequency, consistent with an antenna diameter of 1.2 m |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NE Δ T) | IFOV | Pixel |
|-------------------------|-----------------|---------------|--------------------------|----------------|----------------|
| 10.65 | 100 | V, H | 0.6 K | 19.4 x 32.2 km | 12.8 x 25.6 km |
| 18.7 | 200 | V, H | 0.7 K | 11.2 x 18.3 km | 6.4 x 12.8 km |
| 23.8 | 200 | V | 0.9 K | 9.2 x 15.0 km | 6.4 x 12.8 km |
| 36.5 | 1000 | V, H | 0.4 K | 8.6 x 14.4 km | 6.4 x 12.8 km |
| 89.0 | 6000 | V, H | 0.7 K | 4.4 x 7.2 km | 3.2 x 6.4 km |
| 165.5 | 3000 | V, H | 1.5 K | 4.4 x 7.2 km | 3.2 x 6.4 km |
| 183.31 | 3500 | V | 1.5 K | 4.4 x 7.2 km | 3.2 x 6.4 km |
| 183.31 | 4500 | V | 1.5 K | 4.4 x 7.2 km | 3.2 x 6.4 km |

| GOME | Global Ozone Monitoring Experiment |
|---------------------|---|
| Satellite | ERS-2 |
| Status (Sept 2006) | Operational – Utilised in the period 1995 to ~ 2008 |
| Mission | Ozone profile and total-column or gross profile of other species. Tracked species: BrO, ClO, H ₂ O, HCHO, NO, NO ₂ , NO ₃ , O ₂ , O ₃ , O ₄ , OClO, SO ₂ and aerosol |
| Instrument type | UV/VIS grating spectrometer, four bands, 4096 channels, with 3 polarisation channels |
| Scanning technique | Cross-track: 3 steps of 40 km or 320 km ssp, swath 120 or 960 km - Along-track: one 40-km line each 6 s |
| Coverage/cycle | Global coverage each 24 days with high resolution or 3 days with low resolution. Daylight only |
| Resolution (s.s.p.) | 40 x 40 km ² associated to 120 km swath or 40 x 320 km ² associated to 960 km swath |

| Spectral range | Number of channels | Spectral resolution | SNR at specified input radiance |
|----------------|--------------------|------------------------------------|---|
| 240 - 295 nm | 1024 | 0.22 nm | @ W m |
| 290 - 405 nm | 1024 | 0.24 nm | @ W m ⁻² sr ⁻¹ nm ⁻¹ |
| 400 - 605 nm | 1024 | 0.40 nm | @ W m ⁻² sr ⁻¹ nm ⁻¹ |
| 590 - 790 nm | 1024 | 0.40 nm | @ W m ⁻² sr ⁻¹ nm ⁻¹ |
| 290 - 790 nm | 3 | 292-402 nm, 402-597 nm, 597-790 nm | @ W m ⁻² sr ⁻¹ nm ⁻¹ |

| GOMOS | Global Ozone Monitoring by Occultation of Stars |
|--------------------|---|
| Satellite | Envisat |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2010 |
| Mission | Profiles of ozone and other species. Tracked species: O ₃ , H ₂ O, NO ₂ , NO ₃ , OCIO, BrO, ClO and aerosol |
| Instrument type | UV/VIS/NIR grating spectrometer, three bands, ~ 1000 channels, two broadband channels for scintillations |
| Scanning technique | Limb sounding during occultation of 25-40 stars/orbit, i.e. average 500 occultations/day |
| Coverage/cycle | One global coverage/day with one measurement each 1000 x 1000 km ² cell in average |
| Resolution | Vertical: 1.7 km, in the altitude range 20-100 km. Horizontal effective resolution: ~ 300 km (limb geometry) |

| Spectral range | Number of channels | Spectral resolution | SNR at specified input radiance |
|----------------|--------------------|------------------------|---------------------------------|
| 248 - 693 nm | ~ 500 | 0.89 nm | 12 @ |
| 750 - 776 nm | ~ 200 | 0.12 nm | 6 @ |
| 915 - 956 nm | ~ 300 | 0.12 nm | 3 @ |
| 466 - 705 nm | 2 | 466-582 nm, 644-705 nm | 15 @ |

| HIRDLS | High-Resolution Dynamics Limb Sounder |
|--------------------|---|
| Satellite | EOS-Aura |
| Status (Sept 2006) | Operational – Utilised in the period 2004 to ~ 2010 |
| Mission | Chemistry of the high atmosphere. Tracked species: CFC-11, CFC-12, CH ₄ , ClONO ₂ , H ₂ O, HNO ₃ , N ₂ O, N ₂ O ₅ , NO ₂ , O ₃ , temperature and aerosol |
| Instrument type | 21-channel filter radiometer; range 6.12-17.76 μm |
| Scanning technique | Limb scanning, 6 azimuth angles, swath 2000-3000 km |
| Coverage/cycle | Global coverage each 12 hours for cells of 500 km side |
| Resolution | Vertical: 1 km, in the altitude range 10-100 km. Horizontal effective resolution: ~ 300 km (limb geometry) |

| HR | Haut Résolution |
|---------------------|---|
| Satellites | Pléiades 1 and 2 |
| Status (Sept 2006) | Under development - To be utilised in the period 2008 to ~ 2015 |
| Mission | Land and vegetation observation. Digital Elevation Model (DEM) |
| Instrument type | Two parallel radiometers, 5 VNIR channels, 4 multi-spectral (MS), one panchromatic (PAN) |
| Scanning technique | Bushbroom, 7500 pixel/line (MS), 30000 pixel/line (PAN), swath 20 km ssp; cross-track and along-track pointing capability by up to ± 30° off-nadir. By combining cross- and along- track capabilities, composite images of 120 km x 120 km may be built. Stereoscopic capability in-orbit and between successive orbits |
| Coverage/cycle | Global coverage in 26 days, in daylight. With strategic pointing, one place can be observed each 2 days. |
| Resolution (s.s.p.) | 2.8 m (MS), 0.7 m (PAN) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------|-------------------|----------------------------|
| 0.49 μm | 0.45 – 0.53 μm | @ % albedo |
| 0.55 μm | 0.52 – 0.58 μm | @ % albedo |
| 0.66 μm | 0.62 – 0.70 μm | @ % albedo |
| 0.83 μm | 0.78 – 0.89 μm | @ % albedo |
| 0.69 μm (PAN) | 0.48 – 0.90 μm | @ % albedo |

| HRG | Haut Résolution Géométrique |
|---------------------|---|
| Satellite | SPOT-5 |
| Status (Sept 2006) | Operational – Utilisation period: 2002 to ~ 2008 |
| Mission | Land and vegetation observation. Digital Elevation Model (DEM) |
| Instrument type | Two parallel radiometers, 5 VIS/NIR/SWIR channels, 4 multi-spectral (MS), one panchromatic (PAN) |
| Scanning technique | Bushbroom, 6000 pixel/line (MS), 12000 pixel/line (PAN), swath 60 km ssp (117 km with two instruments), cross-track pointing capability within a range of ± 450 km. Stereoscopic capability between successive orbits |
| Coverage/cycle | Global coverage in 26 days, in daylight. With strategic pointing, one place can be observed each 3 days. |
| Resolution (s.s.p.) | 10 m (the three VNIR channels), 20 m (the SWIR channel), 5 m (PAN) with <i>super-mode</i> at 2.5 m |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---|---------------------------|----------------------------|
| 0.545 μm | 0.49 – 0.61 μm | @ % albedo |
| 0.645 μm | 0.61 – 0.68 μm | @ % albedo |
| 0.835 μm | 0.78 – 0.89 μm | @ % albedo |
| 1.645 μm | 1.58 – 1.75 μm | @ % albedo |
| 0.59 μm (PAN) (2 shifted channels) | 0.49 – 0.69 μm | @ % albedo |

| HRS | Haut Résolution Stéréoscopique |
|---------------------|--|
| Satellite | SPOT-5 |
| Status (Sept 2006) | Operational – Utilisation period: 2002 to ~ 2008 |
| Mission | Digital Elevation Model (DEM) by in-orbit stereoscopy |
| Instrument type | Single VIS channel (0.51-0.73 μm), SNR @ % albedo |
| Scanning technique | Bushbroom, 12000 pixel/line, swath 120 km ssp, along-track fore- and aft- pointing by $\pm 20^\circ$ |
| Coverage/cycle | Global coverage in 26 days, in daylight |
| Resolution (s.s.p.) | 10 m IFOV cross-track, 5 m sampling along-track |

| HRV | Haut Résolution dans le Visible |
|---------------------|--|
| Satellites | SPOT-1, SPOT-2, SPOT-3 |
| Status (Sept 2006) | Operational (on SPOT-2) - Utilisation period: 1986 to ~ 2006 |
| Mission | Land and vegetation observation. Digital Elevation Model (DEM) |
| Instrument type | Two parallel radiometers, 4 VIS/NIR channels, three multi-spectral (MS), one panchromatic (PAN) |
| Scanning technique | Bushbroom, 3000 pixel/line (MS), 6000 pixel/line (PAN), swath 60 km ssp (117 km with two instruments), cross-track pointing capability within a range of ± 450 km. Stereoscopic capability between successive orbits |
| Coverage/cycle | Global coverage in 26 days, in daylight. With strategic pointing, one place can be observed each 3 days. |
| Resolution (s.s.p.) | 20 m (MS), 10 (PAN) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------------|---------------------------|----------------------------|
| 0.545 μm | 0.50 – 0.59 μm | @ % albedo |
| 0.645 μm | 0.61 – 0.68 μm | @ % albedo |
| 0.84 μm | 0.79 – 0.89 μm | @ % albedo |
| 0.62 μm (PAN) | 0.51 – 0.73 μm | @ % albedo |

| HRVIR | Haut Résolution dans le Visible et l'Infra-Rouge |
|---------------------|--|
| Satellite | SPOT-4 |
| Status (Sept 2006) | Operational - Utilisation period: 1998 to ~ 2007 |
| Mission | Land and vegetation observation. Digital Elevation Model (DEM) |
| Instrument type | Two parallel radiometers, 4 VIS/NIR/SWIR multi-spectral (MS) channels, one also panchromatic (PAN) |
| Scanning technique | Bushbroom, 3000 pixel/line (MS), 6000 pixel/line (PAN), swath 60 km ssp (117 km with two instruments), cross-track pointing capability within a range of ± 450 km. Stereoscopic capability between successive orbits |
| Coverage/cycle | Global coverage in 26 days, in daylight. With strategic pointing, one place can be observed each 3 days. |
| Resolution (s.s.p.) | 20 m (MS), 10 (PAN) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---------------------------|---------------------------|----------------------------|
| 0.545 μm | 0.50 – 0.59 μm | @ % albedo |
| 0.645 μm (MS) | 0.61 – 0.68 μm | @ % albedo |
| 0.645 μm (PAN) | 0.61 – 0.68 μm | @ % albedo |
| 0.84 μm | 0.79 – 0.89 μm | @ % albedo |
| 1.64 μm | 1.58 – 1.75 μm | @ % albedo |

| HSB | Humidity Sounder for Brazil |
|---------------------|--|
| Satellite | EOS-Aqua |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2008 |
| Mission | Humidity sounding in almost all-weather conditions. Also precipitation rate |
| Instrument type | 5-channel MW radiometer |
| Scanning technique | Cross-track: 90 steps of 13.5 km ssp, swath 1650 km - Along-track: one 13.5-km line each 8/3 s |
| Coverage/cycle | Near-global coverage once/day |
| Resolution (s.s.p.) | 13.5 km IFOV |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Radiometric accuracy (NE Δ T) |
|-------------------------|-----------------|--------------|--------------------------------------|
| 150.0 | 1000 | V | 1.0 K |
| 183.31 \pm 7.0 | 2000 | V | 1.0 K |
| 183.31 \pm 3.0 | 1000 | V | 1.0 K |
| 183.31 \pm 1.0 | 500 | V | 1.0 K |

| Hyperion | Hyperion |
|---------------------|--|
| Satellite | NMP EO-1 |
| Status (Sept 2006) | Technological demonstration running – To be utilised in the period 2000-2007 |
| Mission | Advanced technology for land and vegetation observation |
| Instrument type | VIS/NIR/SWIR grating spectrometer with 220 channels, in two groups covering the ranges 0.4-1.0 μ m and 0.9-2.5 μ m respectively; channels bandwidths 10 nm |
| Scanning technique | Pushbroom; 250 pixel/line; swath 7.5 km |
| Coverage/cycle | Global coverage in 1 year, in daylight. |
| Resolution (s.s.p.) | 30 m IFOV |

| JMR | JASON Microwave Radiometer |
|---------------------|--|
| Satellite | Jason (it follows TMR of TOPEX-Poseidon and will be followed by AMR on OSTM) |
| Status (Sept 2006) | Operational – Utilised in the period 2001 to ~ 2008. To continue with AMR on OSTM till ~ 2015 |
| Mission | Water vapour correction for the Poseidon-2 radar altimeter |
| Instrument type | 3-frequency MW radiometer, 18.7, 23.8 and 34 GHz |
| Scanning technique | Nadir-only viewing, associated to the Poseidon-2 radar altimeter |
| Coverage/cycle | Global coverage in 1 month for 30 km average spacing, or in 10 days for 100 km average spacing |
| Resolution (s.s.p.) | 25 km |

| LAC | LEISA (Linear Etalon Imaging Spectrometer Array) Atmospheric Corrector |
|---------------------|---|
| Satellite | NMP EO-1 |
| Status (Sept 2006) | Technological demonstration running – To be utilised in the period 2000-2007 |
| Mission | Advanced technology for land and vegetation observation – To correct ALI data for atmospheric effects |
| Instrument type | NIR filter-wedge spectrometer with 256 channels covering the ranges 0.93-1.58 μ m with spectral resolution ranging from 2 to 6 nm. In addition, a 1.38 μ m channel enables cirrus detection |
| Scanning technique | Pushbroom; 768 pixel/line; swath 185 km |
| Coverage/cycle | Global coverage in 16 days, in daylight. |
| Resolution (s.s.p.) | 250 m IFOV |

| | |
|---------------------|--|
| LIS | Lightning Imaging Sensor |
| Satellite | TRMM |
| Status (Sept 2006) | Operational – Utilised in the period 1997 to ~ 2008 |
| Mission | Proxy for convective precipitation, proxy for NO _x generation, study of Earth electric field |
| Instrument type | CCD camera operating at 777.4 nm (O ₂) to count flashes and measure their intensity |
| Scanning technique | Pushbroom, matrix array of 128 x 128 detectors, swath 600 km; each earth location observed continuously (each 2 ms) for about 90 s |
| Coverage/cycle | Intertropical coverage 1 to 2 times/day depending on latitude (best coverage at 15°N and 15°S) |
| Resolution (s.s.p.) | 4 km |

| | |
|---------------------|--|
| LISS-3 | Linear Imaging Self-Scanning Sensor - 3 |
| Satellites | IRS-1C, IRS-1D, IRS-P6 (ResourceSat-1) and ResourceSat-2 |
| Status (Sept 2006) | Operational - Utilisation period: 1995 to ~ 2014 |
| Mission | Land and vegetation observation |
| Instrument type | Two parallel radiometers, 4 VIS/NIR/SWIR channels |
| Scanning technique | Bushbroom, 6000 pixel/line (SWIR 2100 pixel/line on IRS-1C/1D), swath 140 km (with two instruments) |
| Coverage/cycle | Global coverage in 24 days, in daylight |
| Resolution (s.s.p.) | IRS-1C/1D: 23.5 m (three VNIR channels), 70 m (SWIR channel), ResourceSat-1/2: 23.5 m in all channels. |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------|-------------------|----------------------------|
| 0.555 μm | 0.52 – 0.59 μm | @ % albedo |
| 0.650 μm | 0.62 – 0.68 μm | @ % albedo |
| 0.815 μm | 0.77 – 0.86 μm | @ % albedo |
| 1.625 μm | 1.55 – 1.70 μm | @ % albedo |

| | |
|---------------------|--|
| LISS-4 | Linear Imaging Self-Scanning Sensor - 4 |
| Satellite | IRS-P6 (ResourceSat-1) and ResourceSat-2 |
| Status (Sept 2006) | Operational – Utilisation period: 2003 to ~ 2014 |
| Mission | Land and vegetation observation |
| Instrument type | 3-channel VIS/NIR radiometer, one camera each channel |
| Scanning technique | Bushbroom, 4096 pixel/line per camera; swath 23.9 km if the 3 cameras are used each for 1 different channel (thus multi-spectral), or 70 km if all cameras are used for viewing parallel strips in the same channel (thus panchromatic). Cross-track pointing capability ± 26° for stereoscopy in between orbits |
| Coverage/cycle | Global coverage in 24 days, in daylight. 5 days for a target area by using cross-track pointing |
| Resolution (s.s.p.) | 5.8 m IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------|-------------------|----------------------------|
| 0.555 μm | 0.52 – 0.59 μm | @ % albedo |
| 0.650 μm | 0.62 – 0.68 μm | @ % albedo |
| 0.815 μm | 0.77 – 0.86 μm | @ % albedo |

| | |
|--------------------|--|
| MADRAS | Microwave Analysis & Detection of Rain & Atmospheric Structures |
| Satellite | Megha-Tropiques |
| Status (Sept 2006) | Planned - To be utilised in the period 2009 to ~ 2014 |
| Mission | Contribution to the Global Precipitation Measurement mission (GPM) |
| Instrument type | MW radiometer with 5 frequencies / 9 channels |
| Scanning technique | Conical: 56° zenith angle; swath: 1740 km - Scan rate: 24.6 scan/min = 16 km/scan |
| Coverage/cycle | Intertropical coverage 2 to 5 times/day depending on latitude (best coverage at 15°N and 15°S) |
| Resolution | IFOV ranging from 7 km at 157 GHz to 50 km at 18.7 GHz |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Radiometric accuracy (NE Δ T) | IFOV | Pixel |
|-------------------------|-----------------|---------------|--------------------------------------|------------|------------|
| 18.7 | 180 | V, H | 1.0 K | 40 x 60 km | 40 x 40 km |
| 23.8 | 360 | V | 0.86 K | 40 x 60 km | 40 x 40 km |
| 36.5 | 900 | V, H | 0.72 K | 40 x 60 km | 40 x 40 km |
| 89.0 | 1100 | V, H | 1.23 K | 11 x 16 km | 10 x 10 km |
| 157.0 | 1100 | V, H | 3.3 K | 6 x 9 km | 6 x 6 km |

| MERIS | Medium Resolution Imaging Spectrometer |
|----------------------------|---|
| Satellite | Envisat |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2010 |
| Mission | Ocean colour, vegetation, aerosol, cloud properties |
| Instrument type | 15-channel VIS/NIR spectro-radiometer, channel positions and bandwidths selectable |
| Scanning technique | Bushbroom, 3700 pixel/line (split in 5 parallel optical systems), total swath 1150 km |
| Coverage/cycle | Global coverage in 3 days, in daylight |
| Resolution (s.s.p.) | Basic IFOV 300 m, reduced resolution for global data recording: 1200 km |

| Central wavelength | Bandwidth | Radiometric accuracy (SNR @ specified input radiance) |
|--------------------|-----------|---|
| 412.5 nm | 10 nm | @ |
| 442.5 nm | 10 nm | @ |
| 490 nm | 10 nm | @ |
| 510 nm | 10 nm | @ |
| 560 nm | 10 nm | @ |
| 620 nm | 10 nm | @ |
| 665 nm | 10 nm | @ |
| 681.25 nm | 7.5 nm | @ |
| 708.75 nm | 10 nm | @ |
| 753.75 nm | 7.5 nm | @ |
| 760.625 nm | 3.75 nm | @ |
| 778.75 nm | 15 nm | @ |
| 865 nm | 20 nm | @ |
| 885 nm | 10 nm | @ |
| 900 nm | 10 nm | @ |

| MIPAS | Michelson Interferometer for Passive Atmospheric Sounding |
|---------------------------|--|
| Satellite | Envisat |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2010 |
| Mission | Chemistry of the high atmosphere. Tracked species: O ₃ , NO, NO ₂ , HNO ₃ , HNO ₄ , N ₂ O ₅ , ClONO ₂ , COF ₂ , HOCl, CH ₄ , H ₂ O, N ₂ O, CFC's (F11, F12, F22, CCl ₄ , CF ₄), CO, OCS, C ₂ H ₂ , C ₂ H ₆ , SF ₆ and aerosol |
| Instrument type | Michelson interferometer; range 685-2410 cm ⁻¹ (4.15-14.6 μ m); spectral resolution 0.035 cm ⁻¹ unapodised; 60000 channels/spectrum; NESR: 50 nW·cm ⁻² ·sr ⁻¹ ·cm @ 685 cm ⁻¹ , 4.2 nW·cm ⁻² ·sr ⁻¹ ·cm @ 2410 cm ⁻¹ |
| Scanning technique | Limb scanning, fore- and side. 75 s for one vertical scan; 80 scans/orbit, 1145 profiles/day |
| Coverage/cycle | Global coverage each 3 days for one measurement in each 300 x 300 km ² cell |
| Resolution | Vertical: 3 km, in the altitude range 5-150 km. Horizontal effective resolution: ~ 300 km (limb geometry) |

| MISR | Multi-angle Imaging Spectro-Radiometer |
|----------------------------|---|
| Satellite | EOS-Terra |
| Status (Sept 2006) | Operational – Utilised in the period 1999 to ~ 2007 |
| Mission | Bidirection Reflectance Distribution Function (BRDF), vegetation, aerosol |
| Instrument type | Assembly of 9 cameras, each one with 4 spectral VIS/NIR channels, each camera with different pointing |
| Scanning technique | Pushbroom; cross-track: 1500 pixels each camera, swath 360 km; along track: nine viewing angles: nadir, $\pm 26.1^\circ$, $\pm 45.6^\circ$, $\pm 60.0^\circ$ and $\pm 70.5^\circ$ |
| Coverage/cycle | Near-global coverage in one week, in daylight. |
| Resolution (s.s.p.) | Selectable: 275 m or 550 m or 1100 m |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------|-------------------|----------------------------|
| 446 nm | - nm | @ % albedo |
| 558 nm | - nm | @ % albedo |
| 672 nm | - nm | @ % albedo |
| 866 nm | - nm | @ % albedo |

| MLS | Microwave Limb Sounder |
|---------------------------|---|
| Satellite | EOS-Aura |
| Status (Sept 2006) | Operational – Utilised in the period 2004 to ~ 2010 |
| Mission | Chemistry of the high atmosphere. Tracked species: BrO, ClO, CO, H ₂ O, HCl, HCN, HNO ₃ , HO ₂ , HOCl, N ₂ O, O ₃ , OH, SO ₂ , temperature and pressure |
| Instrument type | 5-band / 36-channels millimetre-submillimetre heterodyne radiometer at frequencies 118 GHz (9 channels), 190 GHz (6 channels), 240 GHz (7 channels), 640 GHz (9 channels) and 2500 GHz (5 channels) |
| Scanning technique | Limb scanning |
| Coverage/cycle | Global coverage each 3 d for cells of 300 km side |
| Resolution | Vertical: 1.5 km, in the altitude range 5-120 km. Horizontal effective resolution: ~ 300 km (limb geometry) |

| MODIS | Moderate-resolution Imaging Spectro-radiometer |
|----------------------------|--|
| Satellites | EOS-Terra and EOS-Aqua |
| Status (Sept 2006) | Operational – Utilised in the period 1999 to ~ 2008 |
| Mission | Multi-purpose VIS/IR imagery |
| Instrument type | 36-channel VIS/IR spectro-radiometer |
| Scanning technique | Swath 2230 km. Whiskbroom scanning: a strip of 19.7 km width along-track is cross-track scanned each 2.956 s. The strip includes 16 parallel lines sampled by 2048 pixel of 1000 m ssp, or 32 parallel lines sampled by 4096 pixel of 500 m ssp, or 64 parallel lines sampled by 8192 pixel of 250 m ssp |
| Coverage/cycle | Global coverage nearly twice/day (long-wave channels) or once/day (short-wave channels) |
| Resolution (s.s.p.) | IFOV: 0.25 km (two channels), 0.5 km (5 channels), 1.0 km (29 channels) |

| Central wavelength | Bandwidth | Radiometric accuracy (SNR or NE Δ T) at specified NESR | IFOV at ssp |
|--------------------|---------------|---|-------------|
| 645 nm | 50 nm | 128 @ 21.8 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 250 m |
| 858 nm | 35 nm | 201 @ 24.7 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 250 m |
| 469 nm | 20 nm | 243 @ 35.3 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 500 m |
| 555 nm | 20 nm | 228 @ 29.0 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 500 m |
| 1240 nm | 20 nm | 74 @ 5.4 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 500 m |
| 1640 nm | 24 nm | 275 @ 7.3 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 500 m |
| 2130 nm | 50 nm | 110 @ 1.0 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 500 m |
| 412 nm | 15 nm | 880 @ 44.9 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 443 nm | 10 nm | 838 @ 41.9 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 488 nm | 10 nm | 802 @ 32.1 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 531 nm | 10 nm | 754 @ 27.9 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 551 nm | 10 nm | 750 @ 21.0 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 667 nm | 10 nm | 910 @ 9.5 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 678 nm | 10 nm | 1087 @ 8.7 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 748 nm | 10 nm | 586 @ 10.2 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 870 nm | 15 nm | 516 @ 6.2 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 905 nm | 30 nm | 167 @ 10.0 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 936 nm | 10 nm | 57 @ 3.6 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 940 nm | 50 nm | 250 @ 15.0 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 1375 nm | 30 nm | 150 @ 6.0 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 3.750 μ m | 0.180 μ m | 0.05 K @ 0.45 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 3.959 μ m | 0.060 μ m | 2.00 K @ 2.38 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 3.959 μ m | 0.060 μ m | 0.07 K @ 0.67 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 4.050 μ m | 0.060 μ m | 0.07 K @ 0.79 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 4.515 μ m | 0.165 μ m | 0.25 K @ 0.17 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 4.515 μ m | 0.067 μ m | 0.25 K @ 0.59 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 6.715 μ m | 0.360 μ m | 0.25 K @ 1.16 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 7.325 μ m | 0.300 μ m | 0.25 K @ 2.18 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 8.550 μ m | 0.300 μ m | 0.25 K @ 9.58 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 9.730 μ m | 0.300 μ m | 0.25 K @ 3.69 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 11.030 μ m | 0.500 μ m | 0.05 K @ 9.55 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 12.020 μ m | 0.500 μ m | 0.05 K @ 8.94 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 13.335 μ m | 0.300 μ m | 0.25 K @ 4.52 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 13.635 μ m | 0.300 μ m | 0.25 K @ 3.76 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 13.935 μ m | 0.300 μ m | 0.25 K @ 3.11 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |
| 14.235 μ m | 0.300 μ m | 0.35 K @ 2.08 W·m ⁻² · μ m ⁻¹ ·sr ⁻¹ | 1000 m |

| MOPITT | Measurement Of Pollution In The Troposphere |
|---------------------|--|
| Satellites | EOS-Terra |
| Status (Sept 2006) | Operational – Utilised in the period 1999 to ~ 2007 |
| Mission | Atmospheric chemistry. Tracked species: CO (profile) and CH ₄ (total column) |
| Instrument type | Gas correlation spectrometer; 3 bands, 8 channels. For CO: 4.62 μ m (four channels) and 2.33 μ m (two channels); for CH ₄ : 2.26 μ m (two channels) |
| Scanning technique | Cross-track, 29 steps for a total swath of 640 km |
| Coverage/cycle | Global coverage in 5 days, in daylight |
| Resolution (s.s.p.) | 22 km IFOV |

| MS | Multi-Spectral radiometer | |
|----------------------------|---|----------------------------|
| Satellite | Monitor-E | |
| Status (Sept 2006) | Operational – Utilisation period: 2005 to ~ 2008 | |
| Mission | Land and vegetation observation | |
| Instrument type | 3-channel VIS/NIR radiometer | |
| Scanning technique | Bushbroom, 8000 pixel/line; swath 160 km addressable within an area of regard of 890 km | |
| Coverage/cycle | Global coverage in 14 days, in daylight; locally more frequent by strategic pointing | |
| Resolution (s.s.p.) | 20 m IFOV | |
| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
| 0.565 μm | 0.54 – 0.59 μm | @ % albedo |
| 0.660 μm | 0.63 – 0.68 μm | @ % albedo |
| 0.845 μm | 0.79 – 0.90 μm | @ % albedo |

| MSMR | Multi-frequency Scanning Microwave Radiometer | | | | |
|---------------------------|--|---------------|-------------------------------------|-------------|------------|
| Satellite | IRS-P4 (OceanSat-1) and OceanSat-2 | | | | |
| Status (Sept 2006) | Operational – Utilisation period: 1999 to ~ 2013 | | | | |
| Mission | Sea-surface temperature, wind on sea-surface, total-column water vapour over the sea | | | | |
| Instrument type | MW radiometer with 4 frequencies / 8 channels | | | | |
| Scanning technique | Conical: 55° zenith angle; swath: 1360 km - Scan rate: 11.16 scan/min = 36 km/scan | | | | |
| Coverage/cycle | Global coverage once/day | | | | |
| Resolution | Changing with frequency, consistent with an antenna diameter of 80 cm | | | | |
| Central frequency | Bandwidth | Polarisations | Radiometric accuracy (NE Δ) | IFOV | Pixel |
| 6.6 GHz | 350 MHz | V, H | < 1.0 K | 68 x 105 km | 50 x 36 km |
| 10.65 GHz | 100 MHz | V, H | < 1.0 K | 43 x 66 km | 50 x 36 km |
| 18.0 GHz | 200 MHz | V, H | < 1.0 K | 26 x 40 km | 25 x 36 km |
| 21.0 GHz | 400 MHz | V, H | < 1.0 K | 22 x 34 km | 25 x 36 km |

| MSS | Multi-Spectral Scanner | |
|----------------------------|--|----------------------------|
| Satellite | Landsat 1 to 5 | |
| Status (Sept 2006) | Operational – Utilised in the period 1972 to ~ 2008 | |
| Mission | Land and vegetation observation | |
| Instrument type | VIS/NIR radiometer, 6 short-wave channels, one in TIR | |
| Scanning technique | Wiskbroom; 2300 pixel/line; swath 185 km | |
| Coverage/cycle | Global coverage in 16 days, in daylight. | |
| Resolution (s.s.p.) | 80 m IFOV | |
| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
| 0.55 μm | 0.50 - 0.60 μm | @ % albedo |
| 0.65 μm | 0.60 - 0.70 μm | @ % albedo |
| 0.75 μm | 0.70 - 0.80 μm | @ % albedo |
| 0.95 μm | 0.80 - 1.10 μm | @ % albedo |

| MWR | Micro-Wave Radiometer |
|----------------------------|--|
| Satellites | ERS-1, ERS-2 and Envisat |
| Status (Sept 2006) | Operational – Utilised in the period 1991 to ~ 2010 |
| Mission | Water vapour correction for the radar altimeter (RA on ERS-1/2, RA-2 on Envisat) |
| Instrument type | 2-frequency MW radiometer, 23.8 and 36.5 GHz |
| Scanning technique | Nadir-only viewing, associated to the supported radar altimeter |
| Coverage/cycle | Global coverage in 1 month for 30 km average spacing, or in 10 days for 100 km average spacing |
| Resolution (s.s.p.) | 20 km |

| | |
|----------------------------|---|
| OCM | Ocean Color Monitor |
| Satellite | IRS-P4 (OceanSat-1) and OceanSat-2 |
| Status (Sept 2006) | Operational – Utilisation period: 1999 to ~ 2013 |
| Mission | Ocean colour and aerosol |
| Instrument type | 8-channel VIS/NIR radiometer |
| Scanning technique | Bushbroom, 6000 pixel/line (3700 useful), swath 1420 km |
| Coverage/cycle | Global coverage in 2 days, in daylight |
| Resolution (s.s.p.) | 360 m x 236 m IFOV |

| Central wavelength | Bandwidth | Radiometric accuracy (SNR @ specified NESR) |
|--------------------|-----------|--|
| 412 nm | 20 nm | 1300 @ 0.26 W m ⁻² sr ⁻¹ μ ⁻¹ |
| 442 nm | 20 nm | 1300 @ 0.23 W m ⁻² sr ⁻¹ μ ⁻¹ |
| 489 nm | 20 nm | 1300 @ 0.17 W m ⁻² sr ⁻¹ μ ⁻¹ |
| 512 nm | 20 nm | 1500 @ 0.17 W m ⁻² sr ⁻¹ μ ⁻¹ |
| 557 nm | 20 nm | 1500 @ 0.15 W m ⁻² sr ⁻¹ μ ⁻¹ |
| 670 nm | 20 nm | 1800 @ 0.10 W m ⁻² sr ⁻¹ μ ⁻¹ |
| 768 nm | 40 nm | 1800 @ 0.05 W m ⁻² sr ⁻¹ μ ⁻¹ |
| 867 nm | 40 nm | 2000 @ 0.08 W m ⁻² sr ⁻¹ μ ⁻¹ |

| | |
|----------------------------|---|
| OLI | Operational Land Imager (current assumption: similar to ALI) |
| Satellites | LDCM |
| Status (Sept 2006) | Planned – To be utilised in the period 2010 onwards |
| Mission | Land and vegetation observation |
| Instrument type | VIS/NIR radiometer, 9 VIS/NIR narrow-band channels, one panchromatic (PAN) |
| Scanning technique | Pushbroom; 6000 pixel/line (9 narrow-band channels), 18000 pixel/line (PAN); swath 185 km |
| Coverage/cycle | Global coverage in 16 days, in daylight. |
| Resolution (s.s.p.) | 30 m (9 narrow-band channels), 10 m (PAN) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|--------------------|-------------------|----------------------------|
| 443 nm | 433 - 453 nm | @ % albedo |
| 482 nm | 450 - 515 nm | @ % albedo |
| 565 nm | 525 - 605 nm | @ % albedo |
| 660 nm | 630 - 690 nm | @ % albedo |
| 790 nm | 775 - 805 nm | @ % albedo |
| 867 nm | 845 - 890 nm | @ % albedo |
| 1250 nm | 1200 - 1300 nm | @ % albedo |
| 1650 nm | 1550 - 1750 nm | @ % albedo |
| 2215 nm | 2080 - 2350 nm | @ % albedo |
| Panchromatic | 480 - 690 nm | @ % albedo |

| | |
|----------------------------|--|
| OMI | Ozone Monitoring Instrument |
| Satellite | EOS-Aura |
| Status (Sept 2006) | Operational – Utilised in the period 2004 to ~ 2010 |
| Mission | Ozone profile and total-column or gross profile of other species. Tracked species: BrO, NO ₂ , O ₃ , OClO, SO ₂ and aerosol |
| Instrument type | UV/VIS grating imaging spectrometer, three bands, 1560 channels total |
| Scanning technique | Pushbroom, cross-track swath 2600 km – Zoom mode available, with swath 725 km |
| Coverage/cycle | Global coverage each day, in daylight |
| Resolution (s.s.p.) | 13 x 24 km ² associated to 2600 km swath, reduced to 36 x 48 km ² for profiles. 13 x 12 km ² in zoom mode |

| Spectral range | Number of channels | Spectral resolution | SNR at specified input radiance (NESR) |
|----------------|--------------------|---------------------|--|
| 270 - 314 nm | 390 | 0.42 nm | @ mW·m ⁻² ·nm ⁻¹ ·sr ⁻¹ |
| 306 - 380 nm | 390 | 0.45 nm | @ mW·m ⁻² ·nm ⁻¹ ·sr ⁻¹ |
| 350 - 500 nm | 780 | 0.63 nm | @ mW·m ⁻² ·nm ⁻¹ ·sr ⁻¹ |

| PALSAR | Phased-Array L-band Synthetic Aperture Radar |
|--------------------|---|
| Satellite | ALOS |
| Status (Sept 2006) | Operational – To be utilised in the period 2006 to ~ 2010 |
| Mission | High-resolution all-weather soil moisture and ocean surface features observation |
| Instrument type | L-band SAR, frequency 1.27 GHz, multi-polarisation and variable pointing/resolution |
| Scanning technique | Side-looking, 10-51° off-nadir, swath 40 to 350 km, depending on operation mode – See table |
| Coverage/cycle | Global coverage in minimum 2 weeks, depending on operation mode (duty cycle 17.5 min/orbit) |
| Resolution | 7 to 100 m, depending on operation mode – See table |

| Operation mode | Resolution | Swath | Polarisation | Incidence angle |
|--------------------|------------|------------|----------------|-----------------|
| Highest resolution | 7-44 m | 40-70 km | HH or VV | 8-60° |
| High resolution | 14-89 m | 40-70 km | HH/HV or VV/VH | 8-60° |
| ScanSAR | 100 m | 250-350 km | HH or VV | 18-43° |
| Polarimetry | 24-89 m | 30 km | HH/HV + VV/VH | 8-30° |

| PAN | Panchromatic radiometer |
|---------------------|---|
| Satellite | Monitor-E |
| Status (Sept 2006) | Operational – Utilisation period: 2005 to ~ 2008 |
| Mission | Vegetation monitoring, Digital Elevation Model (DEM) by in-orbit stereoscopy |
| Instrument type | Single VNIR channel (0.51-0.85 µm), SNR @ % albedo |
| Scanning technique | Bushbroom, 12000 pixel/line, swath 90 km addressable within an area of regard of 780 km |
| Coverage/cycle | Global coverage in 26 days, in daylight; locally more frequent by strategic pointing |
| Resolution (s.s.p.) | 8 m IFOV |

| PAN-A, PAN-F | Panchromatic Cameras |
|---------------------|---|
| Satellite | IRS-P5 (CartoSat-1) and CartoSat-2 |
| Status (Sept 2006) | Operational – Utilisation period: 2005 to ~ 2015 |
| Mission | Digital Elevation Model (DEM) by in-orbit stereoscopy |
| Instrument type | Single VIS channel (0.50-0.75 µm), SNR @ % albedo |
| Scanning technique | Bushbroom, 12000 pixel/line, swath 30 km; PAN-A aft- view 10°, PAN-F fore- view 26° |
| Coverage/cycle | Global coverage in 126 days, in daylight |
| Resolution (s.s.p.) | 2.5 m IFOV |

| POAM | Polar Ozone and Aerosol Measurement |
|--------------------|--|
| Satellites | SPOT-3 (POAM-2), SPOT-4 (POAM-3) |
| Status (Sept 2006) | Operational (on SPOT-4) - Utilisation period: 1993 to ~ 2007 |
| Mission | Atmospheric chemistry in high troposphere and stratosphere. Species: H ₂ O, NO ₂ , O ₂ , O ₃ and aerosol |
| Instrument type | 9-channel photometer operating in the range 350-1024 nm (POAM-3) or 350-1064 nm (POAM-2) |
| Scanning technique | Limb scanning in solar occultation; vertical range 10-60 km |
| Coverage/cycle | N/A (few tens of events/day limited to latitudes above ~ 60°) |
| Resolution | 300 km (horizontal), 0.6 km (vertical) |

| POLDER | Polarization and Directionality of the Earth's Reflectances |
|---------------------|---|
| Satellites | PARASOL, ADEOS-1, ADEOS-2 |
| Status (Sept 2006) | Operational (on PARASOL) - Utilisation period: 2004 to ~ 2007 (ADEOS-1: 1996-97; ADEOS-2: 2002-03) |
| Mission | Aerosol, ocean colour, vegetation, Bidirection Reflectance Distribution Function (BRDF) |
| Instrument type | 9-wavelength radiometer with 3 polarisations at three wavelengths (total: 15 channels) |
| Scanning technique | 242 x 274 CCD arrays, 2200 km swath, each earth's spot viewed from more directions as satellite moves |
| Coverage/cycle | Near-global coverage each day in daylight. |
| Resolution (s.s.p.) | 6 km IFOV (PARASOL), 6.5 km IFOV (ADEOS) |

| Central wavelength | | Band width | Polarisation | | Radiometric accuracy (SNR) |
|--------------------|--------|------------|--------------|-------|----------------------------|
| PARASOL | ADEOS | | PARASOL | ADEOS | |
| - | 443 nm | 20 nm | - | three | @ % albedo |
| 443 nm | 443 nm | 20 nm | none | none | @ % albedo |
| 490 nm | 490 nm | 20 nm | three | none | @ % albedo |
| 565 nm | 565 nm | 20 nm | none | none | @ % albedo |
| 670 nm | 670 nm | 20 nm | three | three | @ % albedo |
| 763 nm | 763 nm | 10 nm | none | none | @ % albedo |
| 765 nm | 765 nm | 40 nm | none | none | @ % albedo |
| 865 nm | 865 nm | 40 nm | three | three | @ % albedo |
| 910 nm | 910 nm | 20 nm | none | none | @ % albedo |
| 1020 nm | - | 20 nm | none | | @ % albedo |

| Poseidon-2 | Poseidon-2 |
|---------------------------|--|
| Satellite | Jason (it follows NRA + SSALT of TOPEX-Poseidon and will be followed by Poseidon-3 on OSTM) |
| Status (Sept 2006) | Operational – Utilised in the period 2001 to ~ 2008. To continue with Poseidon-3 on OSTM till ~ 2015 |
| Mission | Ocean topography, significant wave height, wind speed |
| Instrument type | Two-frequency (5.3 and 13.58 GHz) radar altimeter |
| Scanning technique | Nadir-only viewing, sampling at 30 km intervals along track |
| Coverage/cycle | Global coverage in 1 month for 30 km average spacing, or in 10 days for 100 km average spacing |
| Resolution | 30 km IFOV |

| PR | Precipitation Radar |
|----------------------------|--|
| Satellite | TRMM |
| Status (Sept 2006) | Operational – Utilised in the period 1997 to ~ 2008 |
| Mission | Vertical profile of precipitation |
| Instrument type | Imaging radar, frequency 13.8 GHz, |
| Scanning technique | Electronic scanning, planar array of 128 elements, swath 215 km |
| Coverage/cycle | Intertropical coverage 1 to 2 times/day depending on latitude (best coverage at 15°N and 15°S) |
| Resolution (s.s.p.) | Horizontal 4.3 km, vertical 250 m (blind to the lowest ~ 150 m) |

| PRISM | Panchromatic Remote-sensing Instrument for Stereo Mapping |
|----------------------------|---|
| Satellite | ALOS |
| Status (Sept 2006) | Operational – To be utilised in the period 2006 to ~ 2010 |
| Mission | Digital Elevation Model (DEM) by stereoscopy |
| Instrument type | Single-channel (0.52-0.77 μ m) radiometer with three views, fore-, nadir and aft- ($\pm 24^\circ$ and nadir) |
| Scanning technique | Push-broom, nadir image 28000 pixel/line / 70 km swath, fore- and aft- 14000 pixel/line / 35 km swath |
| Coverage/cycle | Global coverage in 46 days for nadir imagery, 96 days for stereoscopy |
| Resolution (s.s.p.) | 2.5 m IFOV for the nadir image |

| RA, RA-2 | Radar Altimeter |
|---------------------------|--|
| Satellites | ERS-1, ERS-2 and Envisat |
| Status (Sept 2006) | Operational – Utilised in the period 1991 to ~ 2010 |
| Mission | Ocean topography, significant wave height, wind speed |
| Instrument type | Radar altimeter: RA-2 two-frequencies (3.2 and 13.6 GHz), ERS-1/2 RA single frequency (13.8 GHz) |
| Scanning technique | Nadir-only viewing, continuous sampling along track |
| Coverage/cycle | Global coverage in 1 month for 30 km average spacing, or in 10 days for 100 km average spacing |
| Resolution | 20 km IFOV |

| SAPHIR | Sondeur Atmospherique du Profil d'Humidite Intertropicale par Radiometrie | | |
|----------------------------|--|--------------|-----------------------------|
| Satellite | Megha-Tropiques | | |
| Status (Sept 2006) | Planned - To be utilised in the period 2009 to ~ 2014 | | |
| Mission | Humidity sounding in nearly-all-weather conditions. Also precipitation | | |
| Instrument type | 6-channel MW radiometer | | |
| Scanning technique | Cross-track: 127 steps of 10 km ssp, swath 1700 km - Along-track: one 10-km lines each 1.6 s | | |
| Coverage/cycle | Intertropical coverage 2 to 5 times/day depending on latitude (best coverage at 15°N and 15°S) | | |
| Resolution (s.s.p.) | 10 km IFOV | | |
| Central frequency (GHz) | Bandwidth (MHz) | Polarisation | Radiometric accuracy (NEΔT) |
| 183.31 ± 0.2 | 200 | V | 2.35 K |
| 183.31 ± 1.1 | 350 | V | 1.45 K |
| 183.31 ± 2.8 | 500 | V | 1.36 K |
| 183.31 ± 4.2 | 700 | V | 1.38 K |
| 183.31 ± 6.8 | 1200 | V | 1.03 K |
| 183.31 ± 11 | 2000 | V | 1.10 K |

| ScaRaB | Scanner for Radiation Budget | | | |
|----------------------------|--|--|-------------------|------|
| Satellites | Megha-Tropiques (also Meteor-3-7 and Resurs-O1-4) | | | |
| Status (Sept 2006) | Planned - To be utilised in the period 2009 to ~ 2014 (1994-95 on Meteor-3-7, in 1998-99 on Resurs-O1-4) | | | |
| Mission | Earth radiation budget at Top Of Atmosphere (TOA) | | | |
| Instrument type | 4-channel radiometer, two broad-band, two narrow-band | | | |
| Scanning technique | Cross-track: 51 pixel/scan, swath 3200 km - Along-track: 1 scan / 6 s | | | |
| Coverage/cycle | Intertropical coverage 2 to 6 times/day depending on latitude (best coverage at 15°N and 15°S) | | | |
| Resolution (s.s.p.) | 40 km IFOV | | | |
| Channel | Spectral interval | Noise Equivalent Radiance | Absolute accuracy | SNR |
| Short-wave | 0.2 - 4.0 μm | < 0.5 W m ⁻² sr ⁻¹ | 1 to 2 % | 850 |
| Total radiance | 0.2 - 50 μm | < 0.5 W m ⁻² sr ⁻¹ | 1 to 2 % | 1000 |
| VIS | 0.55 - 0.65 μm | < 1.0 W m ⁻² sr ⁻¹ | 1 to 2 % | 120 |
| TIR | 10.5-12.5 μm | <0.5 W m ⁻² sr ⁻¹ | 1 to 2 % | 60 |

| SCIAMACHY | Scanning Imaging Absorption Spectrometer for Atmospheric Cartography | | | |
|---------------------------|---|--|--|--|
| Satellite | Envisat | | | |
| Status (Sept 2006) | Operational – Utilised in the period 2002 to ~ 2010 | | | |
| Mission | Atmospheric chemistry. Tracked species: O ₃ , O ₂ , O ₄ , NO, NO ₂ , NO ₃ , N ₂ O, CO, CO ₂ , CH ₄ , H ₂ O, BrO, ClO, OCIO, HCHO, SO ₂ and aerosol | | | |
| Instrument type | UV/VIS/NIR/SWIR grating spectrometer, eight bands, 8192 channels, with 7 polarisation channels | | | |
| Scanning technique | Cross-track: 16-km cross-track x 32-km along-track, for a swath of 1000 km - One scan line in 4.5 s Limb mode: in addition to vertical scanning, ± 500 km horizontal scanning across track is provided Solar and lunar occultation: in this mode the instrument is self-calibrating (DOAS principle) The three modes are alternative to each other | | | |
| Coverage/cycle | Cross-track mode: if used full time, it would provide global coverage each 3 days (in daylight) Limb mode: if used full time, it would provide global coverage each 3 days (in daylight) Solar and lunar occultation: N/A | | | |
| Resolution | Cross-track mode: 16 x 32 km ² s.s.p. Limb mode: 3 km, in the altitude range 10-100 km, horizontal effective resolution: ~ 300 km (limb geometry) Solar and lunar occultation: 1 km, in the altitude range 10-100 km, horizontal effective resolution: ~ 300 km | | | |

| Spectral range | Number of channels | Spectral resolution | SNR at specified input radiance |
|----------------|--------------------|------------------------------------|---------------------------------|
| 240-314 nm | 1024 | 0.24 nm | @ |
| 309-405 nm | 1024 | 0.26 nm | @ |
| 394-620 nm | 1024 | 0.44 nm | @ |
| 604-805 nm | 1024 | 0.48 nm | @ |
| 785-1050 nm | 1024 | 0.54 nm | @ |
| 1000-1750 nm | 1024 | 1.48 nm | @ |
| 1940-2040 nm | 1024 | 0.22 nm | @ |
| 2265-2380 nm | 1024 | 0.26 nm | @ |
| 310-2380 nm | 7 | 67 to 137 nm, depending on channel | @ |

| SeaWiFS | Sea-viewing Wide Field-of-view Sensor |
|---------------------|---|
| Satellite | SeaStar (now called OrbView-2) |
| Status (Sept 2006) | Operational – Utilised in the period 1997 to ~ 2007 |
| Mission | Ocean colour (chlorophyll, suspended sediments, yellow matter, ...) and aerosol |
| Instrument type | 8-channel VIS/NIR radiometer |
| Scanning technique | Cross-track: 2048 pixel of 800 m ssp, swath 2800 km - Along-track: six 1.1-km lines/s - Possibility to tilt the instrument to see aft- or fore- along track by 20 degrees to avoid sunglint |
| Coverage/cycle | Global coverage each day, in daylight |
| Resolution (s.s.p.) | 1.1 IFOV |

| Central wavelength | Bandwidth | Radiometric accuracy (SNR at specified input radiance) |
|--------------------|-----------|--|
| 412 nm | 20 nm | 499 @ 9.10 mW/cm ² |
| 443 nm | 20 nm | 674 @ 8.41 mW/cm ² |
| 490 nm | 20 nm | 667 @ 6.56 mW/cm ² |
| 510 nm | 20 nm | 640 @ 5.64 mW/cm ² |
| 555 nm | 20 nm | 596 @ 4.57 mW/cm ² |
| 670 nm | 20 nm | 442 @ 2.46 mW/cm ² |
| 765 nm | 40 nm | 455 @ 1.61 mW/cm ² |
| 865 nm | 40 nm | 467 @ 1.09 mW/cm ² |

| SeaWinds | SeaWinds |
|--------------------|--|
| Satellites | QuikSCAT and ADEOS-2 |
| Status (mid-2006) | Operational (on QuikSCAT) - Utilisation period: 1999 to ~ 2007 |
| Mission | Sea surface wind vector |
| Instrument type | Ku-band radar scatterometer (13.4 GHz) |
| Scanning technique | Conical scanning, two beams, to provide four views of each spot from different angles; swath 1800 km |
| Coverage/cycle | Global coverage each day |
| Resolution | 50 km |

| TANSO-CAI | Thermal And Near infrared Sensor for carbon Observations - Cloud and Aerosol Imager |
|---------------------|--|
| Satellite | GOSAT |
| Status (Sept 2006) | Under development – To be utilised in the period 2008 to ~ 2013 |
| Mission | Cloud and aerosol observation |
| Instrument type | 4-channel UV/ VIS/NIR/SWIR radiometer |
| Scanning technique | Push-broom, 2000 pixel/line (three VNIR channels), 500 pixels/line (SWIR channel); 1000 km swath |
| Coverage/cycle | Global coverage in 3 days |
| Resolution (s.s.p.) | 0.5 km IFOV in VNIR, 1.5 km in SWIR |

| Central wavelength | Bandwidth | Radiometric accuracy (SNR) |
|--------------------|-----------|----------------------------|
| 380 nm | 20 nm | 200 @ 15 % albedo |
| 674 nm | 20 nm | 200 @ 11 % albedo |
| 870 nm | 20 nm | 200 @ 11 % albedo |
| 1600 nm | 90 nm | 200 @ 10 % albedo |

| TANSO-FTS | Thermal And Near infrared Sensor for carbon Observations - Fourier Transform Spectrometer |
|---------------------|---|
| Satellite | GOSAT |
| Status (Sept 2006) | Under development – To be utilised in the period 2008 to ~ 2013 |
| Mission | Measurements of CO ₂ , CH ₄ and other species |
| Instrument type | 4-band SWIR/TIR interferometer |
| Scanning technique | Cross-track mechanical pointing, swath 790 km |
| Coverage/cycle | Global coverage in 3 days |
| Resolution (s.s.p.) | 10.5 km IFOV |

| Spectral range (µm) | Spectral range (cm ⁻¹) | Spectral resolution (unapodised) | Radiometric accuracy (NEΔT or SNR) |
|---------------------|------------------------------------|----------------------------------|------------------------------------|
| 14.28 - 5.55 µm | 700 - 1800 cm ⁻¹ | 0.2 cm ⁻¹ | K @ 280 K |
| 1.92 - 2.08 µm | 4800 - 5200 cm ⁻¹ | 0.2 cm ⁻¹ | 300 @ 30 % albedo |
| 1.56 - 1.72 µm | 5800 - 6400 cm ⁻¹ | 0.2 cm ⁻¹ | 300 @ 30 % albedo |
| 0.757 - 0.775 µm | 12900 - 13200 cm ⁻¹ | 0.5 cm ⁻¹ | 300 @ 30 % albedo |

| TES | Tropospheric Emission Spectrometer |
|--------------------|--|
| Satellite | EOS-Aura |
| Status (Sept 2006) | Operational – Utilised in the period 2004 to ~ 2010 |
| Mission | Atmospheric chemistry. Tracked species: CFC-11, CFC-12, CH ₄ , CO, CO ₂ , H ₂ O, HCl, HDO, HNO ₃ , N ₂ , N ₂ O, NH ₃ , NO, NO ₂ , O ₃ , OCS, SO ₂ and aerosol |
| Instrument type | IR imaging interferometer, four bands, 40540 channels (cross-track mode) or 162162 channels (limb mode) |
| Scanning technique | Cross-track mode: array of 16 detectors of 0.53 x 0.53 km ² IFOV s.s.p. moving in 10 steps to cover a FOV of 5.3 x 8.5 km ² that can be pointed everywhere within a cone of 45° aperture or a swath of 885 km. Limb mode: each detector subtends a 2.3 km IFOV at the lowest altitude (surface); the 16 detectors simultaneously observe a range of altitudes of 37 km; the 10 transverse steps cover 23 km (horizontal). The two modes are alternative to each other. |
| Coverage/cycle | Cross-track mode: if used full time and exploiting strategic pointing, in 16 days (the orbital repeat cycle) a global coverage could be obtained for cells of ~ 80-km side. Limb mode: if used full time, it would provide global coverage each 3 days (for cells of 300-km side). |
| Resolution | Cross-track mode: 0.53 x 0.53 km ² s.s.p. Limb mode: 2.3 km in the altitude range 0-37 km; horizontal effective resolution: ~ 300 km (limb geometry) |

| Spectral range (µm) | Spectral range (cm ⁻¹) | Spectral resolution (unapodised) | Accuracy (NEΔT) |
|---------------------|------------------------------------|---|-----------------|
| 11.11 - 15.38 µm | 650 - 900 cm ⁻¹ | 0.059 cm ⁻¹ (nadir view), 0.015 cm ⁻¹ (limb mode) | K @ 280 K |
| 8.70 - 12.20 µm | 820 - 1150 cm ⁻¹ | 0.059 cm ⁻¹ (nadir view), 0.015 cm ⁻¹ (limb mode) | K @ 280 K |
| 5.13 - 9.09 µm | 1100 - 1950 cm ⁻¹ | 0.059 cm ⁻¹ (nadir view), 0.015 cm ⁻¹ (limb mode) | K @ 280 K |
| 3.28 - 5.26 µm | 1900 - 3050 cm ⁻¹ | 0.059 cm ⁻¹ (nadir view), 0.015 cm ⁻¹ (limb mode) | K @ 280 K |

| TM | Thematic Mapper |
|---------------------|---|
| Satellites | Landsat 4 and 5 |
| Status (Sept 2006) | Operational – Utilised in the period 1982 to ~ 2008 |
| Mission | Land and vegetation observation |
| Instrument type | VIS/NIR radiometer, 6 short-wave channels, one in TIR |
| Scanning technique | Wiskbroom; 6000 pixel/line (6 short-wave channels), 1500 pixel/line (TIR); swath 185 km |
| Coverage/cycle | Global coverage in 16 days, in daylight. |
| Resolution (s.s.p.) | 30 m (6 short-wave channels), 120 m (TIR) |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---------------------|---------------------------|----------------------------|
| 0.48 μm | 0.45 - 0.52 μm | 60 @ % albedo |
| 0.56 μm | 0.52 - 0.60 μm | 60 @ % albedo |
| 0.66 μm | 0.63 - 0.69 μm | 46 @ % albedo |
| 0.83 μm | 0.76 - 0.90 μm | 46 @ % albedo |
| 1.65 μm | 1.55 - 1.75 μm | 36 @ % albedo |
| 2.20 μm | 2.08 - 2.35 μm | 28 @ % albedo |
| 11.45 μm | 10.4 - 12.5 μm | 0.5 K @ 300 K |

| TMI | TRMM Microwave Imager |
|--------------------|--|
| Satellite | TRMM |
| Status (Sept 2006) | Operational – To be utilised in the period 1997 to ~ 2008 |
| Mission | Multi-purpose MW imager, with emphasis on precipitation |
| Instrument type | MW radiometer with 5 frequencies / 9 channels |
| Scanning technique | Conical: 53° zenith angle; useful swath: 760 km - Scan rate: 32 scan/min = 12.8 km/scan |
| Coverage/cycle | Intertropical coverage 1 to 2 times/day depending on latitude (best coverage at 15°N and 15°S) |
| Resolution | Changing with frequency, consistent with an antenna diameter of 61 x 66 cm |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NE Δ T) | IFOV | Pixel |
|-------------------------|-----------------|---------------|--------------------------|------------|--------------|
| 10.65 | 100 | V, H | 0.6 K | 37 x 63 km | 24 x 25.6 km |
| 19.35 | 500 | V, H | 0.7 K | 18 x 30 km | 12 x 12.8 km |
| 21.3 | 200 | V | 0.9 K | 18 x 23 km | 12 x 12.8 km |
| 37.0 | 2000 | V, H | 0.4 K | 9 x 16 km | 6 x 12.8 km |
| 85.5 | 3000 | V, H | 0.7 K | 5 x 7 km | 3 x 6.4 km |

| Végétation | Végétation |
|---------------------|--|
| Satellites | SPOT-4, SPOT-5 |
| Status (Sept 2006) | Operational - Utilisation period: 1998 to ~ 2008 |
| Mission | Vegetation observation |
| Instrument type | 4-channel VIS/NIR/SWIR radiometer |
| Scanning technique | Bushbroom, 1728 pixel/line, swath 2200 km |
| Coverage/cycle | Near-global coverage in one day |
| Resolution (s.s.p.) | 1.15 km IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (SNR) |
|---------------------|---------------------------|----------------------------|
| 0.450 μm | 0.43 – 0.47 μm | @ % albedo |
| 0.645 μm | 0.61 – 0.68 μm | @ % albedo |
| 0.835 μm | 0.78 – 0.89 μm | @ % albedo |
| 1.645 μm | 1.58 – 1.75 μm | @ % albedo |

| VIRS | Visible and Infra-Red Scanner |
|---------------------|---|
| Satellites | TRMM |
| Status (Sept 2006) | Operational – To be utilised in the period 1997 to ~ 2008 |
| Mission | Multi-purpose VIS/IR imagery |
| Instrument type | 5-channel VIS/IR radiometer |
| Scanning technique | Cross-track: 256 pixel of 1.6 km s.s.p., swath 720 km - Along-track: 240 lines/min, 1.7 km/scan |
| Coverage/cycle | Intertropical coverage 1 to 2 times/day depending on latitude (best coverage at 15°N and 15°S) |
| Resolution (s.s.p.) | 2.0 km IFOV |

| Central wavelength | Spectral interval | Radiometric accuracy (NE Δ T or SNR) |
|---------------------|---------------------------|---|
| 0.630 μm | 0.58 - 0.68 μm | 9 @ 0.5 % albedo |
| 1.61 μm | 1.58 - 1.64 μm | 20 @ 0.5 % albedo |
| 3.74 μm | 3.55 - 3.93 μm | 0.12 K @ 300 K |
| 10.80 μm | 10.3 - 11.3 μm | 0.12 K @ 300 K |
| 12.00 μm | 11.5 - 12.5 μm | 0.12 K @ 300 K |

| WindSat | WindSat |
|-----------------------|---|
| Satellite | Coriolis |
| Status (Sept 2006) | Operational – Utilised in the period 2003 to ~ 2008 |
| Mission | Demonstration of sea surface wind vector observation by polarimetric passive radiometry. Also sea-surface temperature, precipitation, ice, snow and soil moisture index |
| Instrument type | 5-frequency, 22-channel MW radiometer; three channels with full polarimetric capability |
| Scanning technique | Conical: 50-55° zenith angle, swath 1000 km – Scan rate: 31.6 scan/min = 12.5 km/scan |
| Coverage/cycle | Global in 1.5 days |
| Resolution (constant) | Changing with frequency, consistent with antenna diameters of 1.83 m |

| Central frequency (GHz) | Bandwidth (MHz) | Polarisations | Accuracy (NE Δ T) | IFOV | Pixel |
|-------------------------|-----------------|------------------|--------------------------|------------|--------------|
| 6.8 | 125 | V, H | K | 40 x 60 km | 40 x 50 km |
| 10.7 | 300 | V, H, P, M, L, R | K | 25 x 38 km | 20 x 25 km |
| 18.7 | 750 | V, H, P, M, L, R | K | 16 x 27 km | 10 x 25 km |
| 23.8 | 500 | V, H | K | 12 x 20 km | 10 x 12.5 km |
| 37.0 | 2000 | V, H, P, M, L, R | K | 8 x 13 km | 5 x 12.5 km |

(*) Polarisations: H = horizontal, V = vertical, P = + 45°, M = - 45°, L = left-hand circular, R = right-hand circular