

Determining optimal conditions for meso-scale AMV

10th Int'l Winds Workshop
24 Feb. 2010, Tokyo

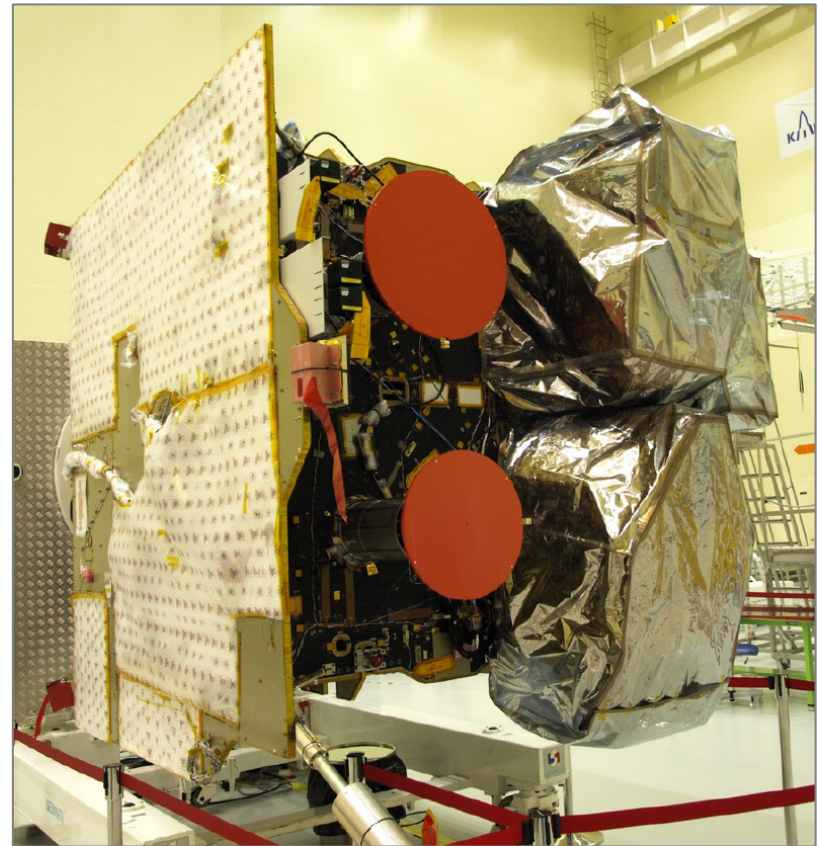
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NIMR / KMA
Régis Borde
EUMETSAT

Current status of KMA AMV

Korea plans to launch our first meteorological imager
at April THIS YEAR (Wish us luck!!)

It has four IR and one VIS channel
: central wavelengths are almost
same with MTSAT

We've developed AMV algorithm with MTSAT data
: results are comparable to GTS AMVs
(in accuracy and impact to forecast)



Attempts to observe smaller scale winds

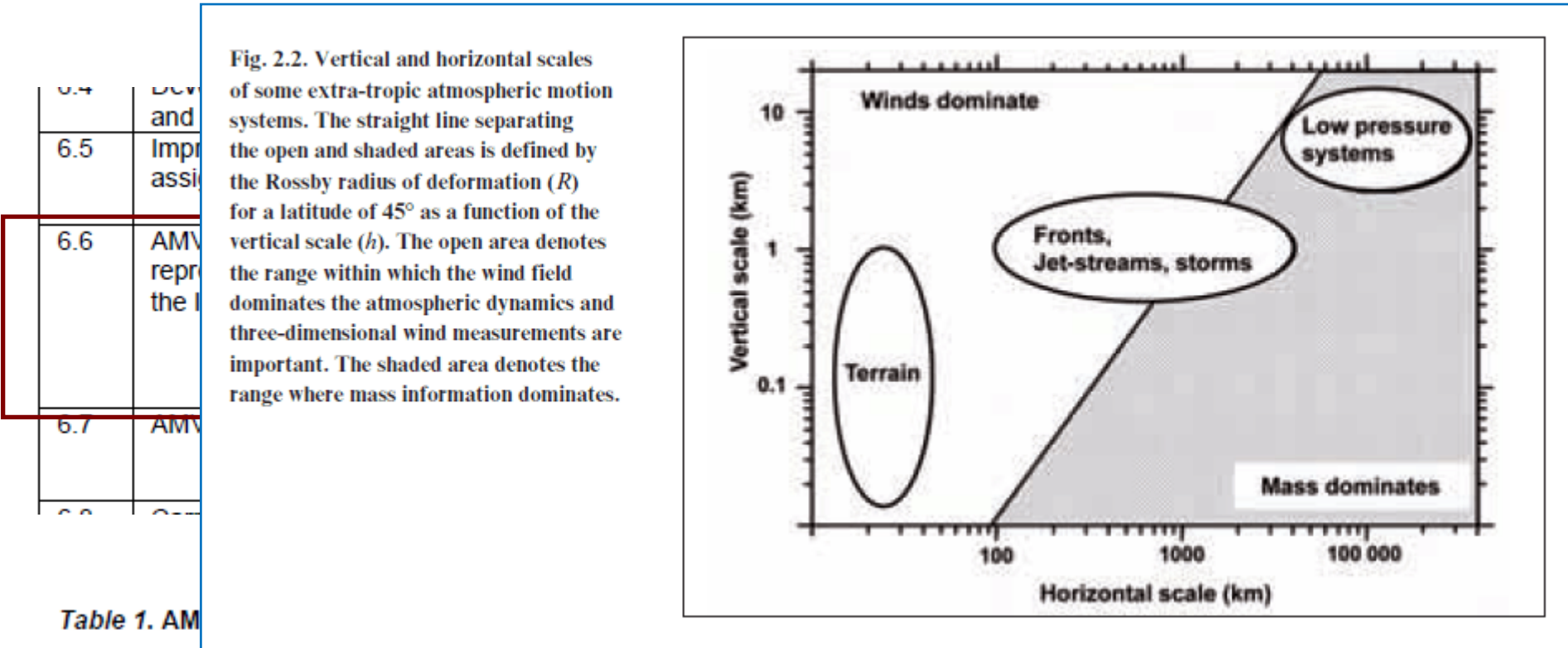


Table 1. AMV

Genkova, proceedings of 9th IVW workshop

AMV Producer	EUMESAT	CIMSS/NESDIS	Brazil	JMA	KMA
Steps subsequence	target, track, height assign.	target, height assign., track	target, track, height assign.	target, track, height assign.	target, track, height assign.
Target box	24x24 pix	15x15 pix	32x32 pix	32x32 pix	32x32 pix
Search box	80x80 pix	21x37 pix	50x50 pix	64x64 pix	64x64 pix
Target	no threshold	7 bright units	no threshold	no threshold	5 Kelvin

~72 km

~60 km

~128 km

What controls SCALE of AMV ?

1. time interval of images

- 15 minutes
- 30 minutes

2. horizontal resolution of image

- 4 km (IR channels)
- 1 km (HR-Visible channel)

3. target size

- 128 to 16 km

4. scale of NWP

- larger than 35 km (UM/KMA)

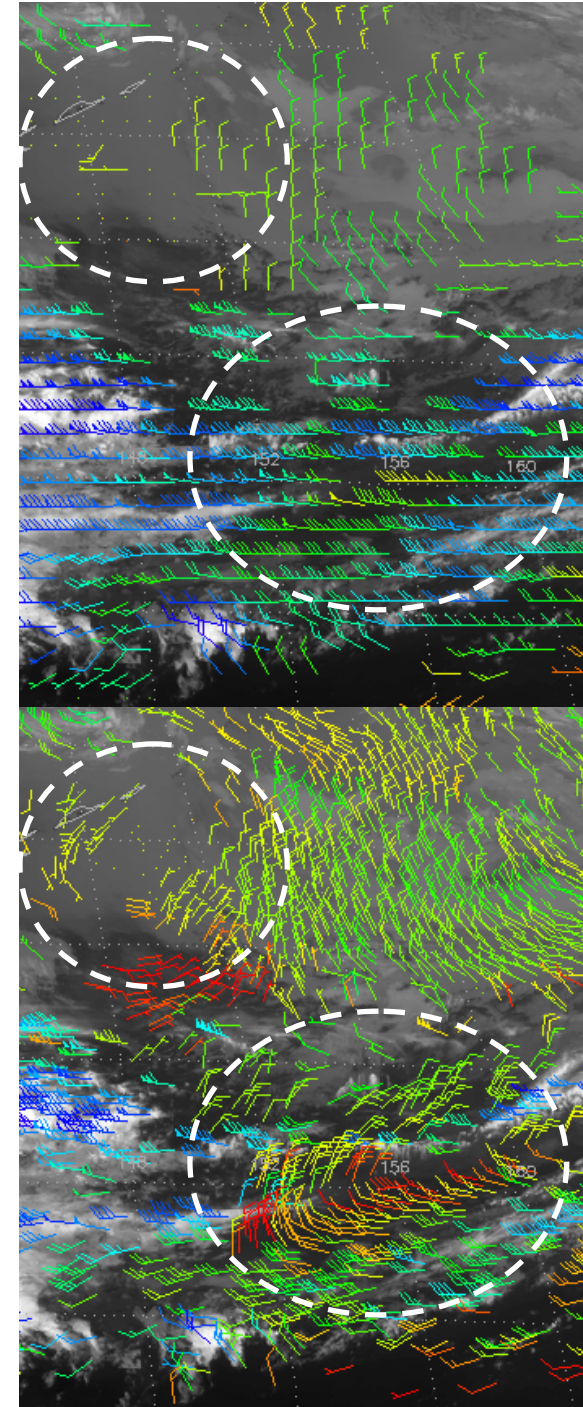


Table 1. AMV retrieval schemes specifics

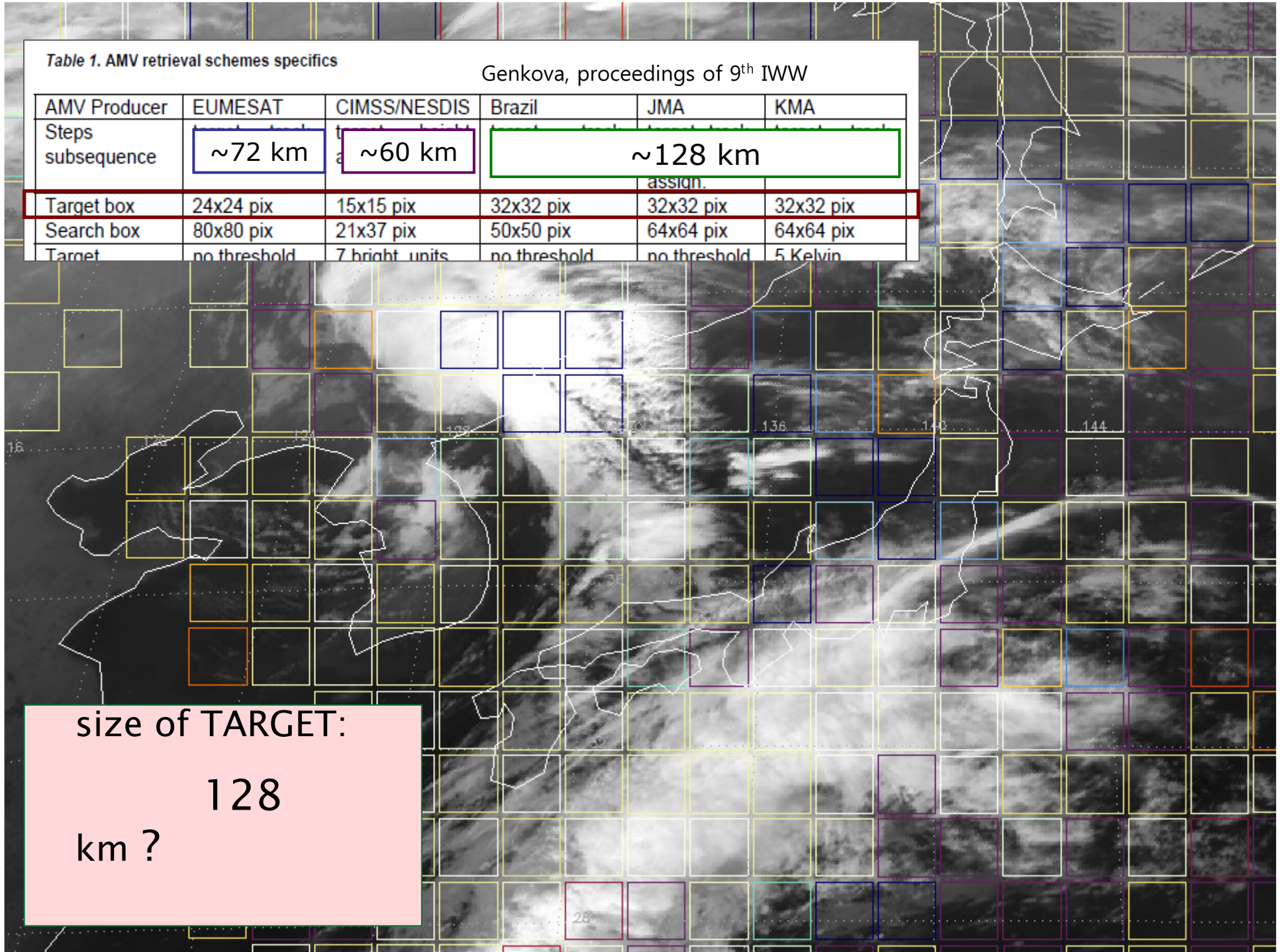
Genkova, proceedings of 9th IWW

AMV Producer	EUMESAT	CIMSS/NESDIS	Brazil	JMA	KMA
Steps subsequence	~72 km	~60 km	~128 km		
Target box	24x24 pix	15x15 pix	32x32 pix	32x32 pix	32x32 pix
Search box	80x80 pix	21x37 pix	50x50 pix	64x64 pix	64x64 pix
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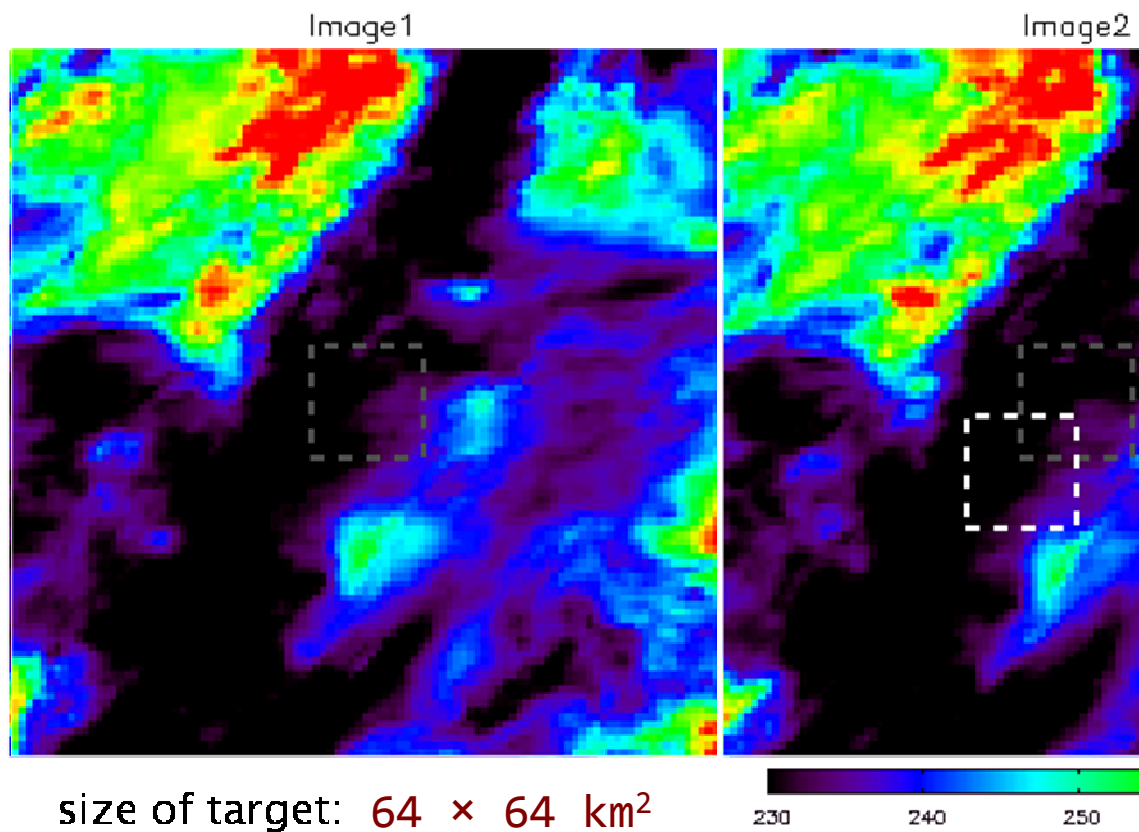
size of TARGET:

128

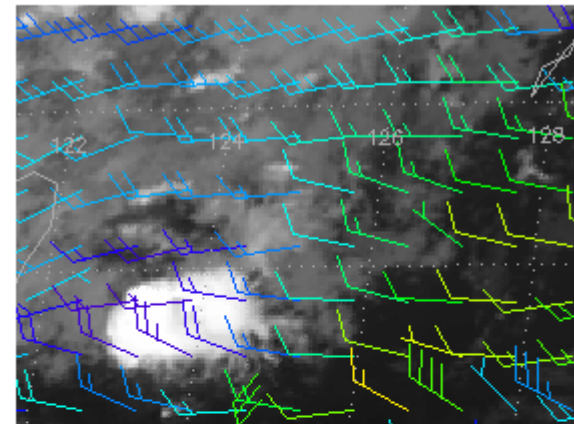
km ?



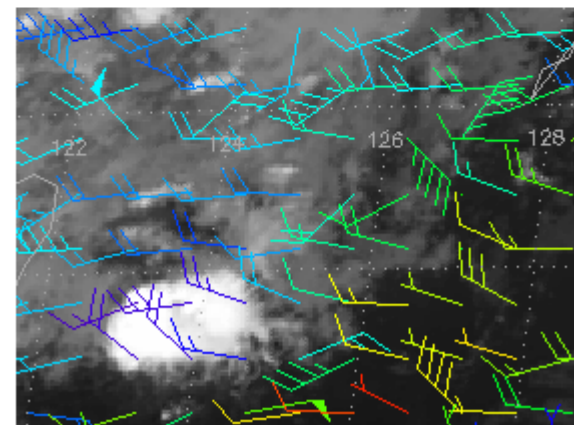
reducing Target Size



$128 \times 128 \text{ km}^2$

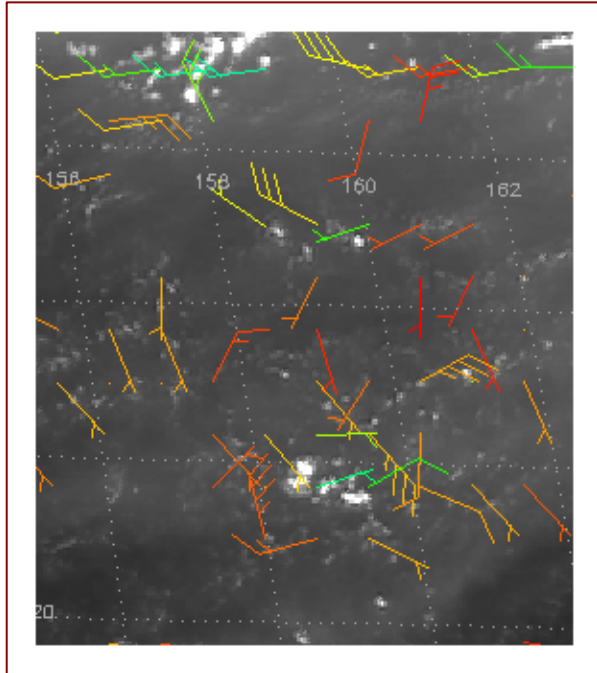


$64 \times 64 \text{ km}^2$

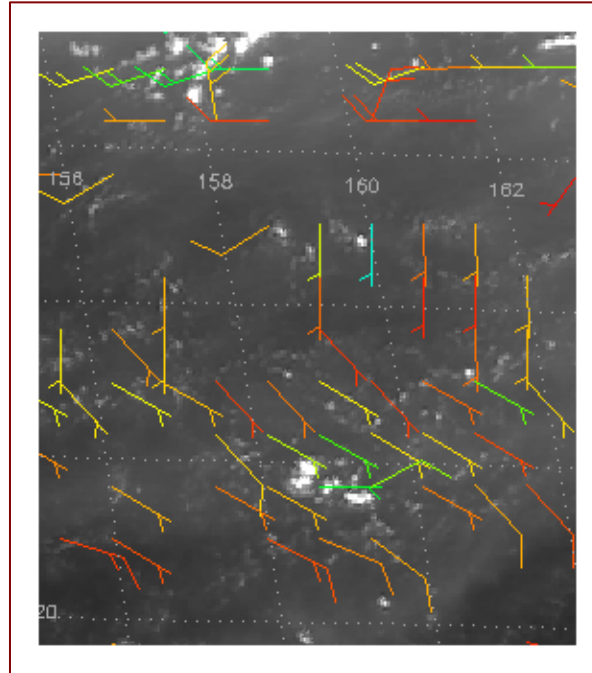


solution : Time Interval between images ?

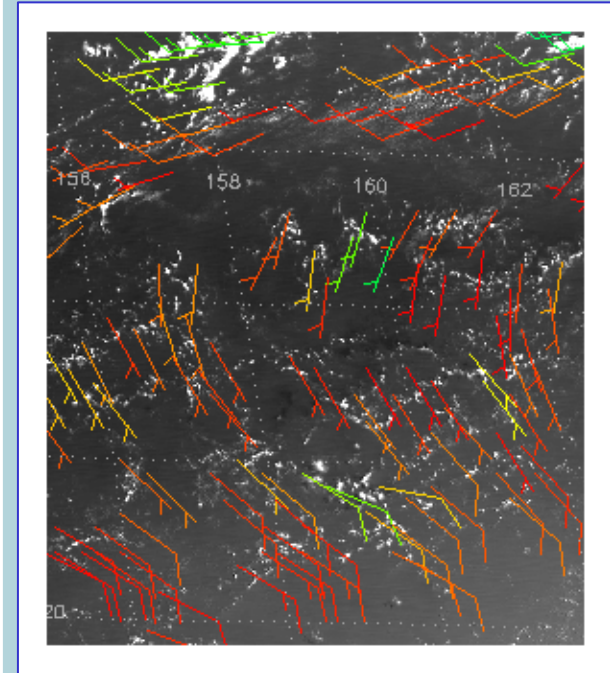
30 minutes



15 minutes



15 minutes



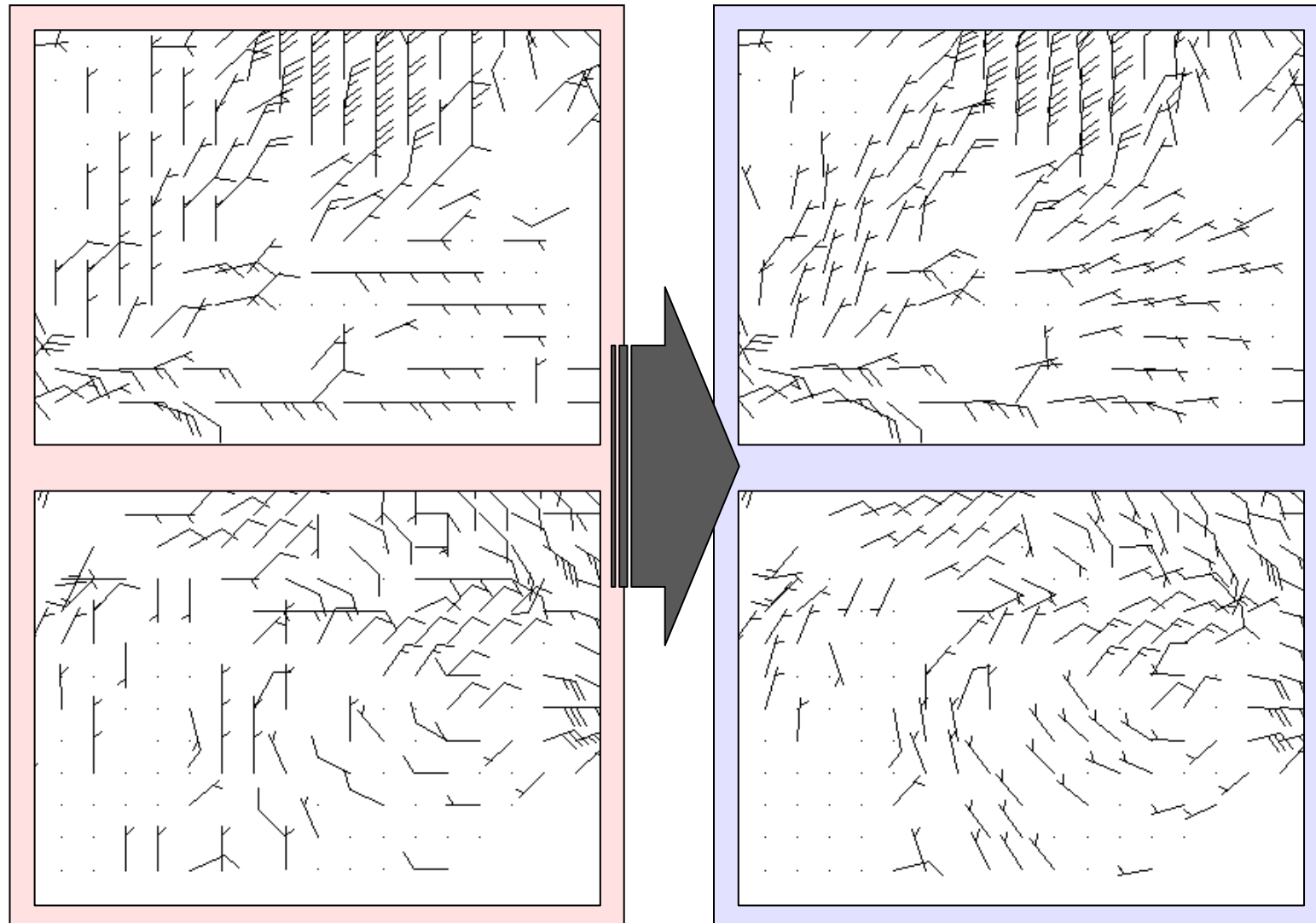
IRW-channel : res.=4 km

HRV-channel : res.=1 km

time interval	Wind speed <i>corresponding</i> one pixel displacement
30 min.	2.2 ms ⁻¹
15 min.	4.4 ms ⁻¹

time interval	Wind speed <i>corresponding</i> one pixel displacement
30 min.	0.6 ms ⁻¹
15 min.	1.1 ms ⁻¹

solution : Sub-pixel determination of target displacement ?



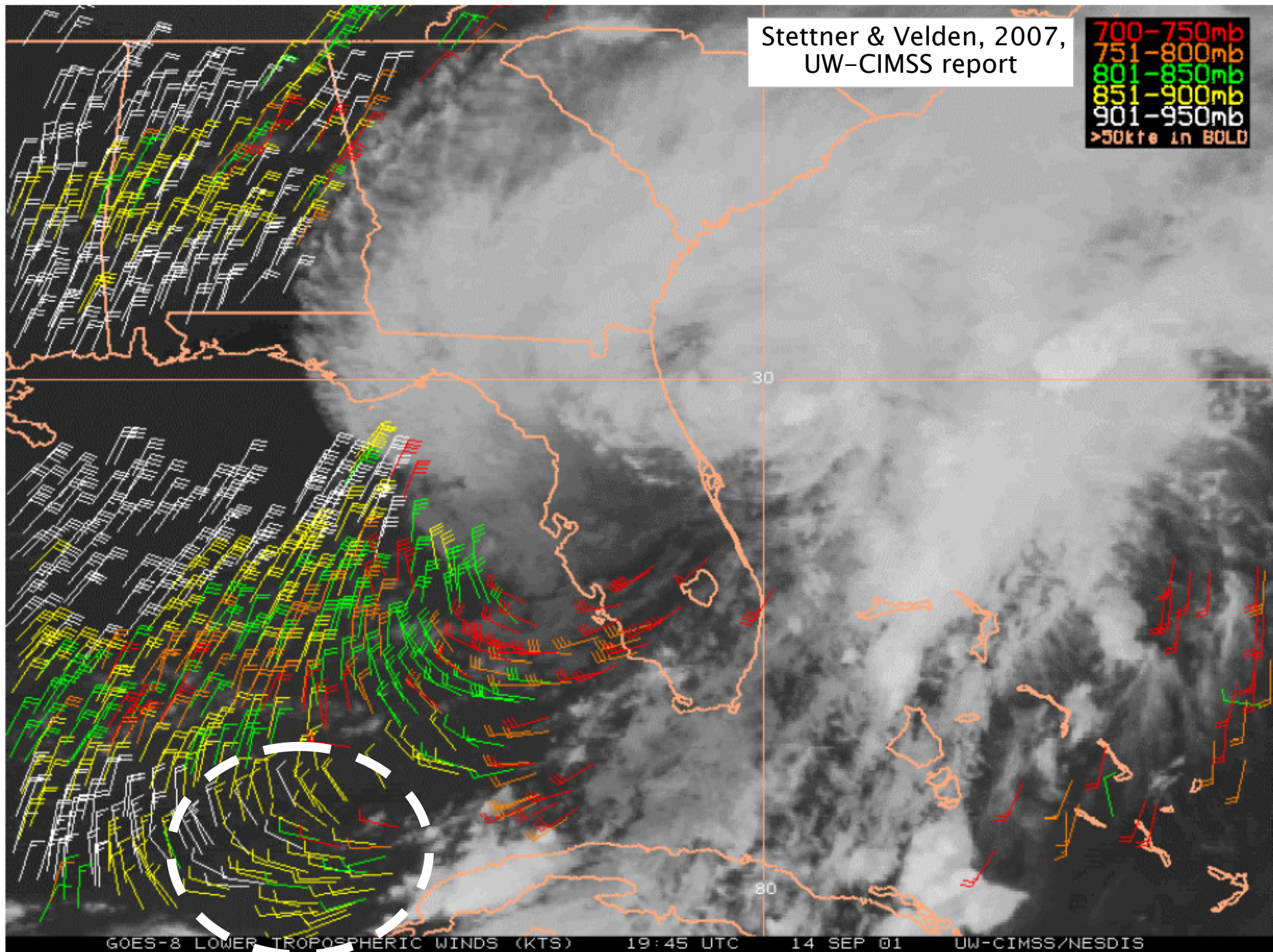


Figure 3: Lower troposphere rapid scan AMVs around Tropical Storm Gabrielle, 14 September, 2001.

What controls SCALE of AMV ?

assuming we can ignore the effects of

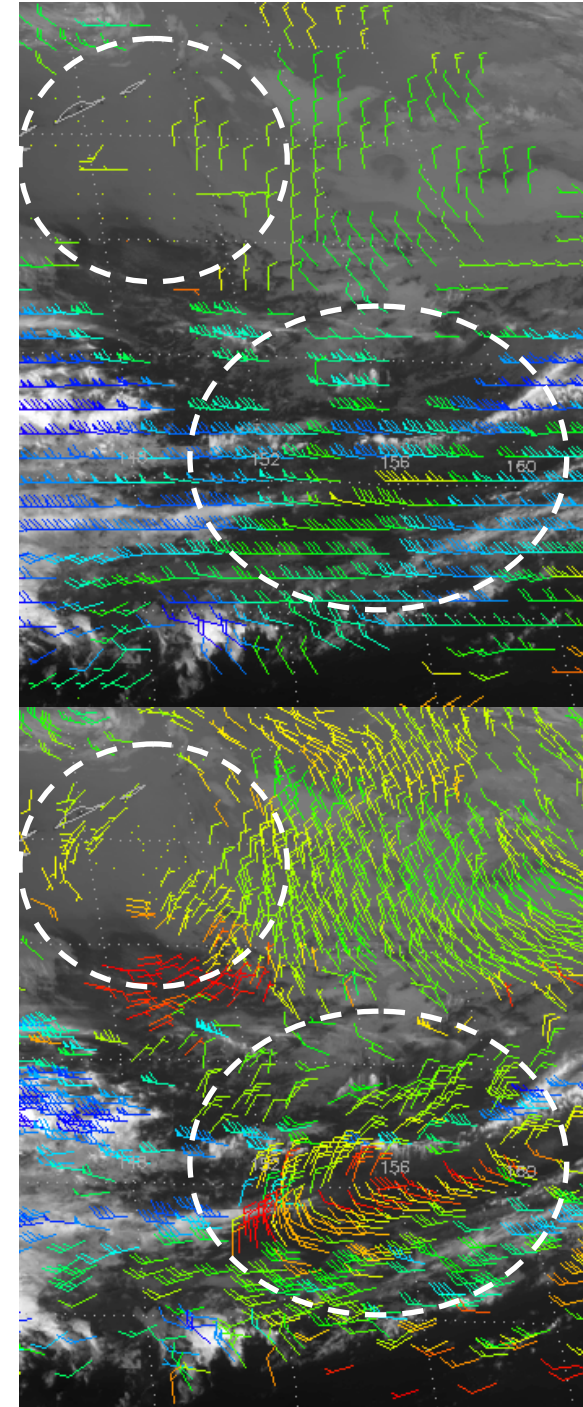
2. horizontal resolution of image
4. scale of NWP

can we determine the OPTIMAL

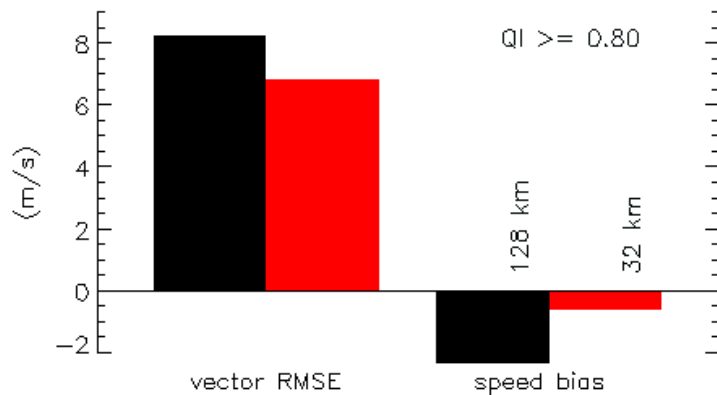
3. target size
 - 128 to 16 km

for GIVEN

1. time interval of images
 - 15 minutes
 - 30 minutes

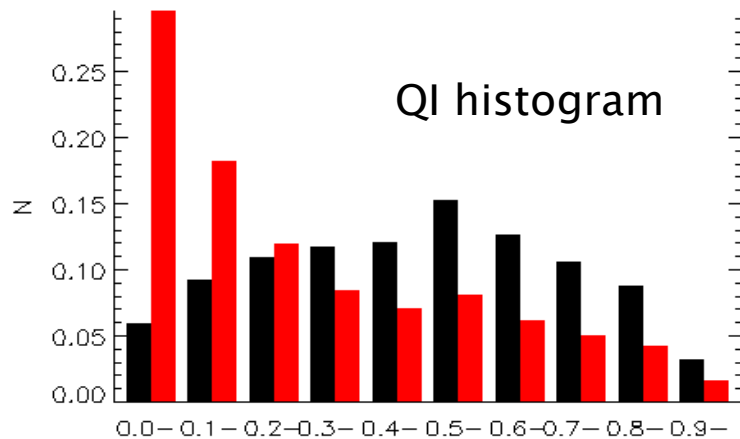


determining OPTIMAL target size
for given time interval of images



ACCURACY (to Rawinsonde)

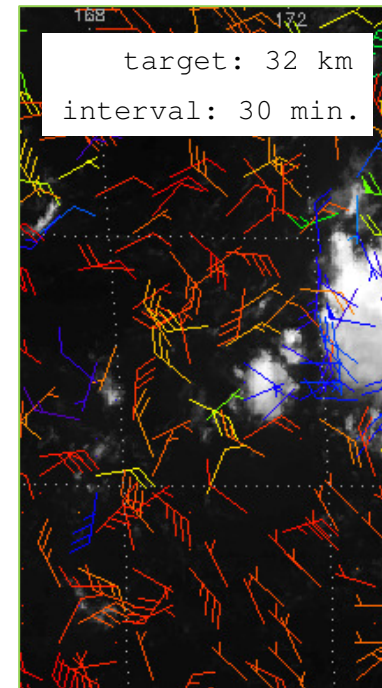
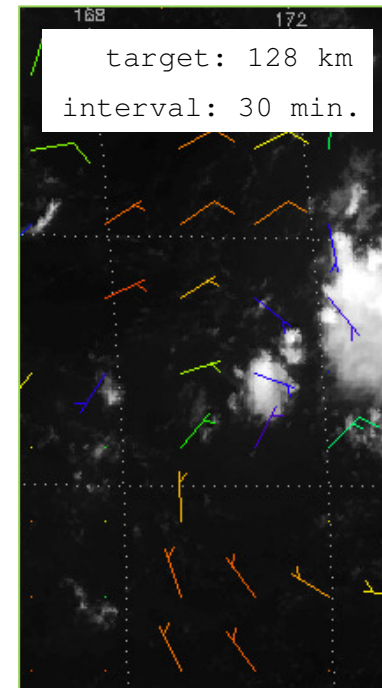
data : IRW (10.8 μ m) AMV
 period : 17 Oct – 10 Nov 2009
 filters :
 horizontal dist < 150 km
 vertical dist < 25 hPa
 quality \geq 0.8
 speed diff. < 30 m/s
 dir. diff. < 90 degree



QI (Quality Indicator) Histogram

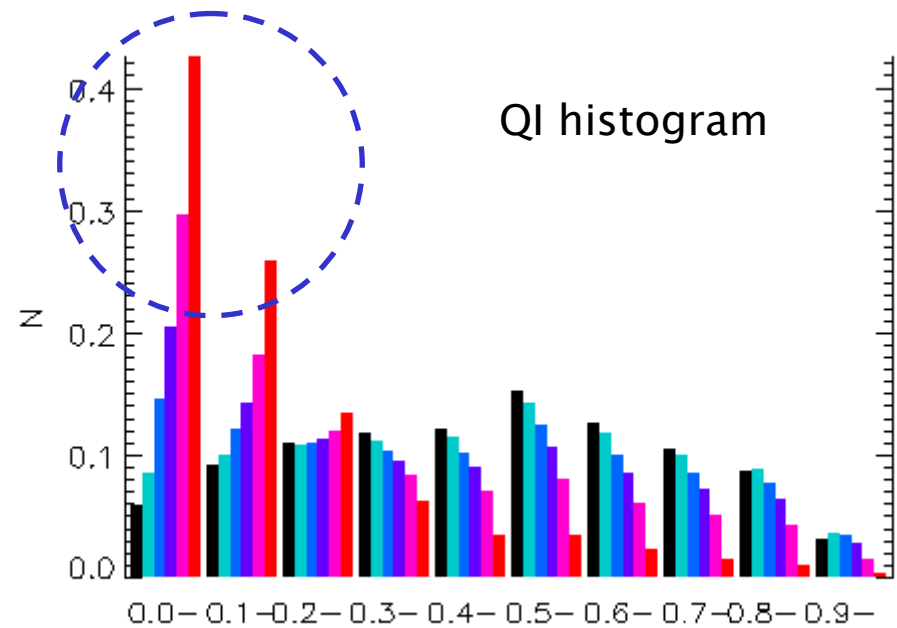
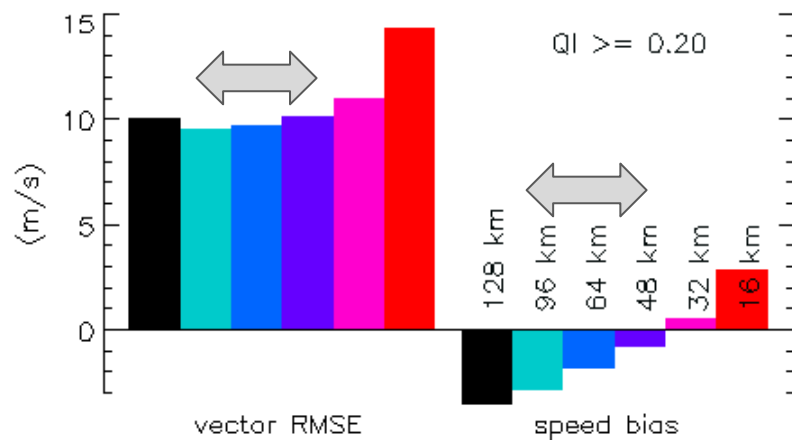
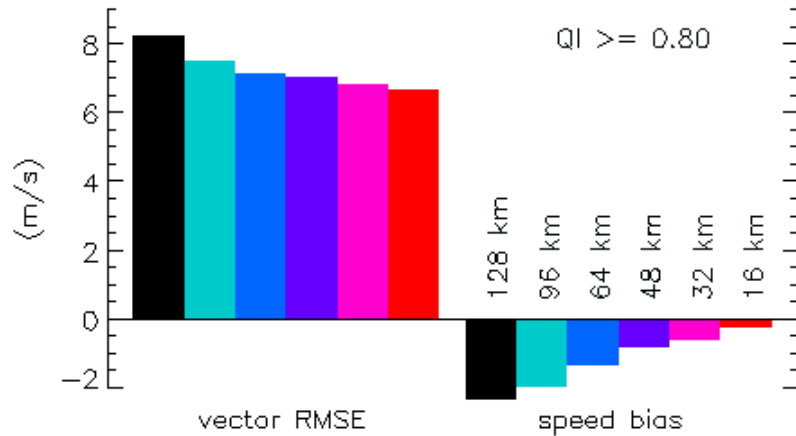
period : (same)
 filter : (none)
 x-axis : QI
 y-axis : number density

must consider
not only ACCURACY
also QUALITY



time interval of images: 30 minutes

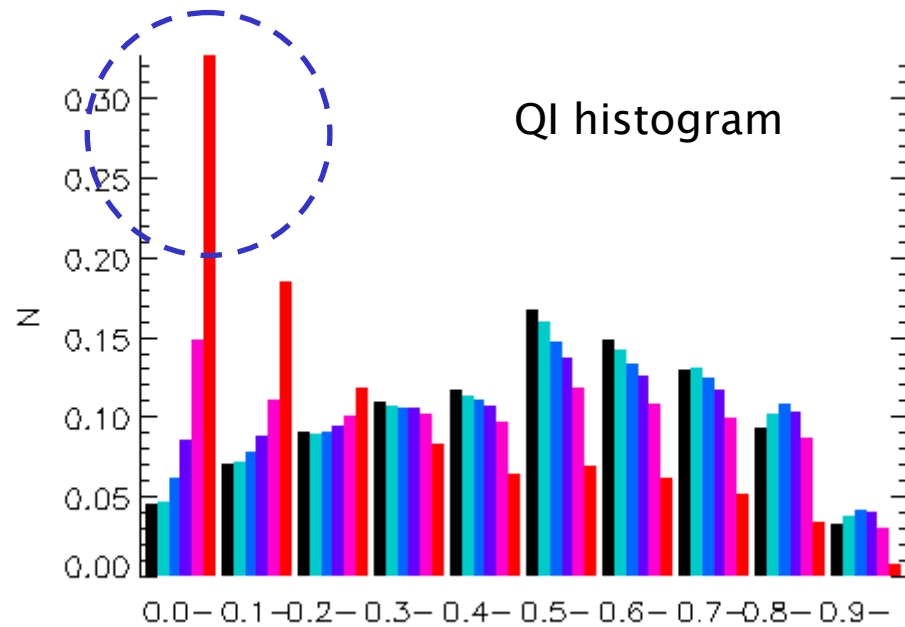
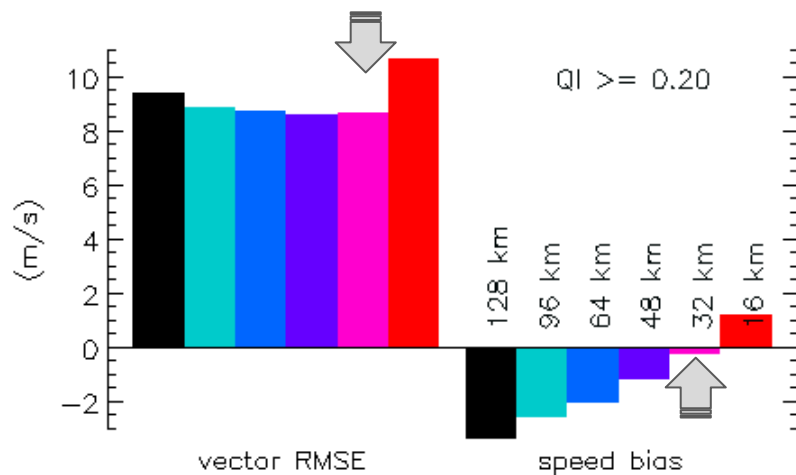
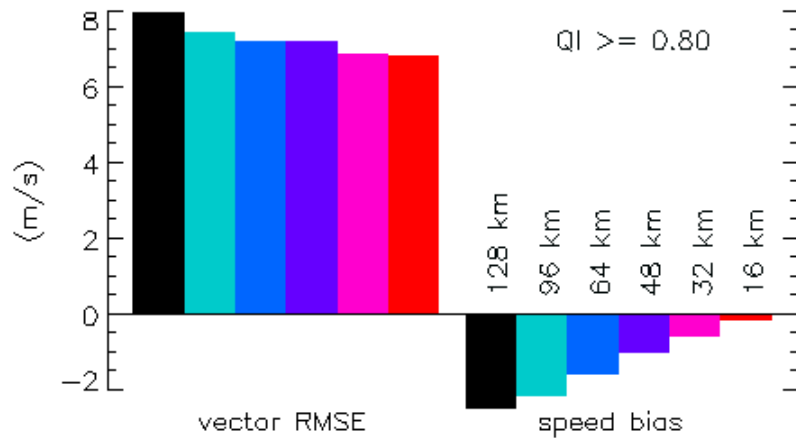
17oct-10nov 2009
IRW (10.8 μ m) AMV



time interval of images: 15 minutes

17oct-10nov 2009
IRW (10.8 μ m) AMV

	30 min.	15 min.
IRW (4 km)	96~48 km	32 km
HRV (1 km)	64 km	64~32 km



CONCLUSION

- ◆ reducing Target Size
⇒ more tracking errors
- ◆ shorter time interval between images
⇒ precision problem
- ◆ sub-pixel determination
of target displacement

	30 min.	15 min.
IRW (4 km)	96~48 km	32 km
HRV (1 km)	64 km	64~32 km

- Optimal target size varies with time interval of images
- It is determined mainly by time interval, not image resolution
- For AMV whose time scale is more than 15 minutes
target size is a matter of PHYSICAL scale of cloud deformation
NOT the number of pixels within target

DISCUSSION

- ◆ Rapid scan AMV
 - optimal target must be smaller than 30 km
 - for that scale, 4km resolution image might be a problem
 - (1) precision can be poorer than tens of m/s
 - (2) number of pixels is too few (in sense of corr. calculation)
 - optimum can be determined also by dynamic range of cloud

- ◆ After the MTSAT-1R will be changed to rapid scan mode ...